

# Software Interface

## CCURDPRC (WC-DPRC)

# PCIe Digital Programmable Resistance Card (DPRC)

<i>Driver</i>	ccurdprc (WC-DPRC)	
<i>Platform</i>	RedHawk Linux® ( <i>CentOS/Rocky/RHEL &amp; Ubuntu</i> ), Native Ubuntu® and Native Red Hat Enterprise Linux® <sup>1</sup>	
<i>Vendor</i>	Concurrent Real-Time	
<i>Hardware</i>	PCIe Digital Programable Resister Card (DPRC)	
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# 1. Introduction

This document provides the software interface to the *ccurdprc* driver which communicates with the Concurrent Real-Time PCI Express Digital Programmable Resistance Card (DPRC).

The software package that accompanies this board provides the ability for advanced users to communicate directly with the board via the driver *ioctl(2)* and *mmap(2)* system calls. When programming in this mode, the user needs to be intimately familiar with both the hardware and the register programming interface to the board. Failure to adhere to correct programming will result in unpredictable behavior.

Additionally, the software package is accompanied with an extensive set of application programming interface (API) calls that allow the user to access all capabilities of the board. The API library also allows the user the ability to communicate directly with the board through the *ioctl(2)* and *mmap(2)* system calls. In this case, there is a risk of this direct access conflicting with API calls and therefore should only be used by advanced users who are intimately familiar with the hardware, board registers and the driver code.

Various example tests have been provided in the *test* and *test/lib* directories to assist the user in developing their applications.

## 1.1 Related Documents

- PCIe Digital Programmable Resistance Card Driver Installation on RedHawk Release Notes by Concurrent Real-Time.

# 2. Software Support

Software support is provided for users to communicate directly with the board using the kernel system calls (*Direct Driver Access*) or the supplied *API*. Both approaches are identified below to assist the user in software development.

## 2.1 Direct Driver Access

### 2.1.1 open(2) system call

In order to access the board, the user first needs to open the device using the standard system call *open(2)*.

```
int    fp;
fp =   open("/dev/ccurdprc0", O_RDWR);
```

The file pointer '*fp*' is then used as an argument to other system calls. The user can also supply the *O\_NONBLOCK* flag if the user does not wish to block waiting for reads to complete. In that case, if the read is not satisfied, the call will fail. The device name specified is of the format "/dev/ccurdprc<num>" where *num* is a digit 0..9 which represents the board number that is to be accessed. Basically, the driver only allows one application to open a board at a time. The reason for this is that the application can have full access to the card, even at the board and API level. If another application were to communicate with the same card concurrently, the results would be unpredictable unless proper synchronization between applications is performed external to the driver.

This driver allows multiple applications to open the same board by specifying an additional *oflag* *O\_APPEND*. It is then the responsibility of the user to ensure that the various applications communicating with the same cards are properly synchronized. Various tests supplied in this package has the *O\_APPEND* flags enabled, however, it is strongly recommended that only one application be run with a single card at a time, unless the user is well aware of how the applications are going to interact with each other and accept any unpredictable results.

## 2.1.2 ioctl(2) system call

This system call provides the ability to control and get responses from the board. The nature of the control/response will depend on the specific *ioctl* command.

```
int    status;
int    arg;
status = ioctl(fp, <IOCTL_COMMAND>, &arg);
```

where, '*fp*' is the file pointer that is returned from the *open(2)* system call. *<IOCTL\_COMMAND>* is one of the *ioctl* commands below and *arg* is a pointer to an argument that could be anything and is dependent on the command being invoked. If no argument is required for a specific command, then set to *NULL*.

Driver IOCTL command:

```
IOCTL_CCURDPRC_ABORT_DMA
IOCTL_CCURDPRC_ADD_IRQ
IOCTL_CCURDPRC_DISABLE_PCI_INTERRUPTS
IOCTL_CCURDPRC_ENABLE_PCI_INTERRUPTS
IOCTL_CCURDPRC_GET_DRIVER_ERROR
IOCTL_CCURDPRC_GET_DRIVER_INFO
IOCTL_CCURDPRC_GET_PHYSICAL_MEMORY
IOCTL_CCURDPRC_GET_READ_MODE
IOCTL_CCURDPRC_GET_WRITE_MODE
IOCTL_CCURDPRC_INIT_BOARD
IOCTL_CCURDPRC_INTERRUPT_TIMEOUT_SECONDS
IOCTL_CCURDPRC_MAIN_CONTROL_REGISTERS
IOCTL_CCURDPRC_MMAP_SELECT
IOCTL_CCURDPRC_NO_COMMAND
IOCTL_CCURDPRC_PCI_BRIDGE_REGISTERS
IOCTL_CCURDPRC_PCI_CONFIG_REGISTERS
IOCTL_CCURDPRC_READ_EEPROM
IOCTL_CCURDPRC_REMOVE_IRQ
IOCTL_CCURDPRC_RESET_BOARD
IOCTL_CCURDPRC_SELECT_READ_MODE
IOCTL_CCURDPRC_SELECT_WRITE_MODE
IOCTL_CCURDPRC_WAIT_FOR_INTERRUPT
IOCTL_CCURDPRC_WRITE_EEPROM
```

**IOCTL\_CCURDPRC\_ABORT\_DMA:** This *ioctl* does not have any arguments. Its purpose is to abort any DMA already in progress.

**IOCTL\_CCURDPRC\_ADD\_IRQ:** This *ioctl* does not have any arguments. Its purpose is to setup the driver *interrupt handler* to handle interrupts. If support for MSI interrupts are configured, they will be enabled. Normally, there is no need to call this *ioctl* as the interrupt handler is already added when the driver is loaded. This *ioctl* should only be invoked if the user has issued the *IOCTL\_CCURDPRC\_REMOVE\_IRQ* call earlier to remove the interrupt handler.

**IOCTL\_CCURDPRC\_DISABLE\_PCI\_INTERRUPTS:** This *ioctl* does not have any arguments. Its purpose is to disable PCI interrupts. This call shouldn't be used during normal reads or writes, as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

**IOCTL\_CCURDPRC\_ENABLE\_PCI\_INTERRUPTS:** This *ioctl* does not have any arguments. Its purpose is to enable PCI interrupts. This call shouldn't be used during normal reads or writes as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

*IOCTL\_CCURDPRC\_GET\_DRIVER\_ERROR:* The argument supplied to this *ioctl* is a pointer to the *ccurdprc\_user\_error\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. The error returned is the last reported error by the driver. If the argument pointer is *NULL*, the current error is reset to *CCURDPRC\_SUCCESS*.

*IOCTL\_CCURDPRC\_GET\_DRIVER\_INFO:* The argument supplied to this *ioctl* is a pointer to the *ccurdprc\_driver\_info\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. This *ioctl* provides useful driver information.

*IOCTL\_CCURDPRC\_GET\_PHYSICAL\_MEMORY:* The argument supplied to this *ioctl* is a pointer to the *ccurdprc\_user\_phys\_mem\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. If physical memory is not allocated, the call will fail; otherwise the call will return the physical memory address and size in bytes. The only reason to request and get physical memory from the driver is to allow the user to perform DMA operations and bypass the driver and library. Care must be taken when performing user level DMA, as incorrect programming could lead to unpredictable results, including but not limited to corrupting the kernel and any device connected to the system.

*IOCTL\_CCURDPRC\_GET\_READ\_MODE:* The argument supplied to this *ioctl* is a pointer an *unsigned long int*. The value returned will be one of the read modes as defined by the *enum \_ccurdprc\_driver\_rw\_mode\_t* located in the *ccurdprc\_user.h* include file. Currently, only the *CCURDPRC\_PIO\_CHANNEL* mode is supported for driver reads.

*IOCTL\_CCURDPRC\_GET\_WRITE\_MODE:* (*CURRENTLY NOT IMPLEMENTED*) The argument supplied to this *ioctl* is a pointer an *unsigned long int*. The value returned will be one of the write modes as defined by the *enum \_ccurdprc\_driver\_rw\_mode\_t* located in the *ccurdprc\_user.h* include file. This call is not supported for driver writes.

*IOCTL\_CCURDPRC\_INIT\_BOARD:* This *ioctl* does not have any arguments. This call resets the board to a known initial default state. This call is currently identical to the *IOCTL\_CCURDPRC\_RESET\_BOARD* call.

*IOCTL\_CCURDPRC\_INTERRUPT\_TIMEOUT\_SECONDS:* The argument supplied to this *ioctl* is a pointer to an *int*. It allows the user to change the default time out from 30 seconds to user supplied time out. This is the time that the read call will wait before it times out. The call could time out if a DMA fails to complete. The device should have been opened in the block mode (*O\_NONBLOCK* not set) for reads to wait for an operation to complete.

*IOCTL\_CCURDPRC\_MAIN\_CONTROL\_REGISTERS:* This *ioctl* dumps all the PCI Main Control registers and is mainly used for debug purpose. The argument to this *ioctl* is a pointer to the *ccurdprc\_main\_control\_register\_t* structure. Raw 32-bit data values are read from the board and loaded into this structure.

*IOCTL\_CCURDPRC\_MMAP\_SELECT:* The argument to this *ioctl* is a pointer to the *ccurdprc\_mmap\_select\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. This call needs to be made prior to the *mmap(2)* system call so as to direct the *mmap(2)* call to perform the requested mapping specified by this *ioctl*. The four possible mappings that are performed by the driver are to *mmap* the local register space (*CCURDPRC\_SELECT\_LOCAL\_MMAP*), the configuration register space (*CCURDPRC\_SELECT\_CONFIG\_MMAP*) the physical memory (*CCURDPRC\_SELECT\_PHYS\_MEM\_MMAP*) that is created by the *mmap(2)* system call and the driver/library mapping (*CCURDPRC\_SELECT\_DRIVER\_LIBRARY\_MMAP*).

*IOCTL\_CCURDPRC\_NO\_COMMAND:* This *ioctl* does not have any arguments. It is only provided for debugging purpose and should not be used as it serves no purpose for the application.

*IOCTL\_CCURDPRC\_PCI\_BRIDGE\_REGISTERS:* This *ioctl* dumps all the PCI bridge registers and is mainly used for debug purpose. The argument to this *ioctl* is a pointer to the *ccurdprc\_pci\_bridge\_register\_t* structure. Raw 32-bit data values are read from the board and loaded into this structure.



**IOCTL\_CCURDPRC\_PCI\_CONFIG\_REGISTERS:** The argument supplied to this *ioctl* is a pointer to the *ccurdprc\_pci\_config\_reg\_addr\_mapping\_t* structure whose definition is located in the *ccurdprc\_user.h* include file.

**IOCTL\_CCURDPRC\_READ\_EEPROM:** The argument to this *ioctl* is a pointer to the *ccurdprc\_eeprom\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. This call is specifically used by the supplied *eeprom* application and should not be used by the user.

**IOCTL\_CCURDPRC\_REMOVE\_IRQ:** This *ioctl* does not have any arguments. Its purpose is to remove the interrupt handler that was previously setup. The interrupt handler is managed internally by the driver and the library. The user should not issue this call, otherwise reads will time out.

**IOCTL\_CCURDPRC\_RESET\_BOARD:** This *ioctl* does not have any arguments. This call resets the board to a known initial default state. This call is currently identical to the *IOCTL\_CCURDPRC\_INIT\_BOARD* call.

**IOCTL\_CCURDPRC\_SELECT\_READ\_MODE:** The argument supplied to this *ioctl* is a pointer an *unsigned long int*. The value set will be one of the read modes as defined by the *enum \_ccurdprc\_driver\_rw\_mode\_t* located in the *ccurdprc\_user.h* include file. Currently, only the *CCURDPRC\_PIO\_CHANNEL* mode is supported for driver reads.

**IOCTL\_CCURDPRC\_SELECT\_WRITE\_MODE:** (*CURRENTLY NOT IMPLEMENTED*) The argument supplied to this *ioctl* is a pointer an *unsigned long int*. The value set will be one of the write modes as defined by the *enum \_ccurdprc\_driver\_rw\_mode\_t* located in the *ccurdprc\_user.h* include file. This call is not supported for driver writes.

**IOCTL\_CCURDPRC\_WAIT\_FOR\_INTERRUPT:** The argument to this *ioctl* is a pointer to the *ccurdprc\_driver\_int\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. The user can wait for a DMA or Analog signal complete interrupt. If a time out value greater than zero is specified, the call will time out after the specified seconds, otherwise it will not time out.

**IOCTL\_CCURDPRC\_WRITE\_EEPROM:** The argument to this *ioctl* is a pointer to the *ccurdprc\_eeprom\_t* structure. Information on the structure is located in the *ccurdprc\_user.h* include file. This call is specifically used by the supplied *eeprom* application and should not be used by the user.

### 2.1.3 mmap(2) system call

This system call provides the ability to map either the local board registers, the configuration board registers, create and map a physical memory that can be used for user DMA or driver/library structure mapping. Prior to making this system call, the user needs to issue the *ioctl(2)* system call with the *IOCTL\_CCURDPRC\_MMAP\_SELECT* command. When mapping either the local board registers or the configuration board registers, the *ioctl* call returns the size of the register mapping which needs to be specified in the *mmap(2)* call. In the case of mapping a physical memory, the size of physical memory to be created is supplied to the *mmap(2)* call.

```
int *munmap_local_ptr;
ccurdprc_local_ctrl_data_t *local_ptr;
ccurdprc_mmap_select_t mmap_select;
unsigned long mmap_local_size;

mmap_select.select = CCURDPRC_SELECT_LOCAL_MMAP;
mmap_select.offset=0;
mmap_select.size=0;
ioctl(fp, IOCTL_CCURDPRC_MMAP_SELECT, (void *)&mmap_select);
mmap_local_size = mmap_select.size;
munmap_local_ptr = (int *) mmap((caddr_t)0, mmap_local_size,
                               (PROT_READ|PROT_WRITE), MAP_SHARED, fp, 0);
```

```
local_ptr = (ccurdprc_local_ctrl_data_t *)munmap_local_ptr;
local_ptr = (ccurdprc_local_ctrl_data_t *)((char *)local_ptr +
                                           mmap_select.offset);
.
.
.

if(munmap_local_ptr != NULL)
    munmap((void *)munmap_local_ptr, mmap_local_size);
```

#### **2.1.4 read(2) system call**

This system call currently supports ADC programmed I/O reads of channel registers. The option selected is determined by the *ccurDPRC\_Select\_Driver\_Read\_Mode()* call.

#### **2.1.5 write(2) system call**

Currently this option is not implemented. The option selected is determined by the *ccurDPRC\_Select\_Driver\_Write\_Mode()* call.

.

## 2.2 Application Program Interface (API) Access

The API is the recommended method of communicating with the board for most users.

There are a lot of APIs that have multiple arguments to set various parameters. If the user only wishes to change certain parameters for the call, they need to get the current settings via a query API, change only those parameters that need to be modified and then invoke a setting API to update these parameters (*i.e. read/modify/write*). This is a two API call operation.

A nice feature has been implemented in these APIs to simplify the user programming by having a common parameter `CCURDPRC_DO_NOT_CHANGE` which is a `#define`, that can be used for a lot of these calls. Arguments with this parameter will therefore cause the API to perform the read/modify/write operation instead of the user performing the same function with two API calls. The drawback to this approach is that some compilers will complain about the use of this parameter and therefore the user will require appropriate casting to get rid of warnings/errors.

The following are a list of calls that are available.

```
ccurDPRC_Abort_DMA()
ccurDPRC_Activate_Board()
ccurDPRC_ADC_Activate()
ccurDPRC_ADC_Get_Negative_Cal()
ccurDPRC_ADC_Get_Offset_Cal()
ccurDPRC_ADC_Get_Positive_Cal()
ccurDPRC_ADC_Perform_Auto_Calibration()
ccurDPRC_ADC_Perform_External_Negative_Calibration()
ccurDPRC_ADC_Perform_External_Offset_Calibration()
ccurDPRC_ADC_Perform_External_Positive_Calibration()
ccurDPRC_ADC_Perform_Negative_Calibration()
ccurDPRC_ADC_Perform_Offset_Calibration()
ccurDPRC_ADC_Perform_Positive_Calibration()
ccurDPRC_ADC_Read_Channels()
ccurDPRC_ADC_Read_Channels_Calibration()
ccurDPRC_ADC_Set_Negative_Cal()
ccurDPRC_ADC_Set_Offset_Cal()
ccurDPRC_ADC_Set_Positive_Cal()
ccurDPRC_ADC_Write_Channels_Calibration()
ccurDPRC_Add_Irq()
ccurDPRC_Clear_Driver_Error()
ccurDPRC_Clear_Electronic_Fuse_Trip_Fault()
ccurDPRC_Clear_Lib_Error()
ccurDPRC_Close()
ccurDPRC_DataToVolts()
ccurDPRC_DigitalPotentiometerAndIo_Activate()
ccurDPRC_Disable_Pci_Interrupts()
ccurDPRC_Enable_Pci_Interrupts()
ccurDPRC_Fast_Memcpy()
ccurDPRC_Fast_Memcpy_Unlocked()
ccurDPRC_Fraction_To_Hex()
ccurDPRC_Get_Board_CSR()
ccurDPRC_Get_Board_Info()
ccurDPRC_Get_CalibrationBus_Control()
ccurDPRC_Get_Digital_Potentiometer()
ccurDPRC_Get_Digital_Potentiometer_Test()
ccurDPRC_Get_Driver_Error()
ccurDPRC_Get_Driver_Info()
ccurDPRC_Get_Driver_Read_Mode()
```

```

ccurDPRC_Get_Driver_Write_Mode()
ccurDPRC_Get_Electronic_Fuse_Base()
ccurDPRC_Get_Electronic_Fuse_Internals()
ccurDPRC_Get_Electronic_Fuse_Multiplier()
ccurDPRC_Get_Electronic_Fuse_Status()
ccurDPRC_Get_Electronic_Fuse_Threshold()
ccurDPRC_Get_Electronic_Fuse_Trip()
ccurDPRC_Get_Interrupt_Control()
ccurDPRC_Get_Interrupt_Status()
ccurDPRC_Get_Interrupt_Timeout_Seconds()
ccurDPRC_Get_IO_Control()
ccurDPRC_Get_Lib_Error_Description()
ccurDPRC_Get_Lib_Error()
ccurDPRC_Get_Mapped_Config_Ptr()
ccurDPRC_Get_Mapped_Driver_Library_Ptr()
ccurDPRC_Get_Mapped_Local_Ptr()
ccurDPRC_Get_Open_File_Descriptor()
ccurDPRC_Get_Physical_Memory()
ccurDPRC_Get_Value()
ccurDPRC_Hex_To_Fraction()
ccurDPRC_Identify_Board()
ccurDPRC_Initialize_Board()
ccurDPRC_MMap_Physical_Memory()
ccurDPRC_Munmap_Physical_Memory()
ccurDPRC_NanoDelay()
ccurDPRC_Open()
ccurDPRC_Read()
ccurDPRC_Read_Serial_Prom()
ccurDPRC_Read_Serial_Prom_Item()
ccurDPRC_Remove_Irq()
ccurDPRC_Reset_Board()
ccurDPRC_Select_Driver_Read_Mode()
ccurDPRC_Select_Driver_Write_Mode()
ccurDPRC_Serial_Prom_Write_Override()
ccurDPRC_Set_Board_CSR()
ccurDPRC_Set_CalibrationBus_Control()
ccurDPRC_Set_Digital_Potentiometer()
ccurDPRC_Set_Digital_Potentiometer_Test()
ccurDPRC_Set_Interrupt_Control()
ccurDPRC_Set_Interrupt_Status()
ccurDPRC_Set_Interrupt_Timeout_Seconds()
ccurDPRC_Set_IO_Control()
ccurDPRC_Set_Value()
ccurDPRC_VoltsToData()
ccurDPRC_VoltsToDataChanCal()
ccurDPRC_Wait_For_Interrupt()
ccurDPRC_Write()
ccurDPRC_Write_Serial_Prom()
ccurDPRC_Write_Serial_Prom_Item()

```

### 2.2.1 ccurDPRC\_Abort\_DMA()

This call will abort any DMA operation that is in progress. Normally, the user should not use this call unless they are providing their own DMA handling.

```

/*****
  _ccurdprc_lib_error_number_t ccurDPRC_Abort_DMA(void *Handle)

Description: Abort any DMA in progress

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR           (successful)
         # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN         (device not open)
         # CCURDPRC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURDPRC_LIB_IOCTL_FAILED     (driver ioctl call failed)
*****/

```

### 2.2.2 ccurDPRC\_Activate\_Board()

This call activates the ADC, Potentiometer and I/O in a specific sequence to ensure proper board activation. This is the preferred and recommended call to activate the card. Using the individual ADC and Potentiometer activation calls, not being performed in correct sequence could result in unpredictable behavior of the card.

```

/*****
  _ccurdprc_lib_error_number_t ccurDPRC_Activate_Board(void *Handle)

Description: Activate ADC, Potentiometer and I/O Control module

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR           (successful)
         # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN         (device not open)
         # CCURDPRC_LIB_NO_LOCAL_REGION   (local region not present)
         # CCURDPRC_LIB_ADC_FAILURE      (ADC failure)
         # CCURDPRC_LIB_ELECTRONIC_FUSE_TRIPPED (Electronic Fuse tripped)
*****/

```

### 2.2.3 ccurDPRC\_ADC\_Activate()

This call gives the user the ability to activate, disable and get the current ADC state. The user can also use this call to return the current state of the ADC without any change by specifying a pointer to current\_state and setting activate to CCURDPRC\_ADC\_ALL\_ENABLE\_DO\_NOT\_CHANGE. If the ADC is already active and the user issues a CCURDPRC\_ADC\_ALL\_ENABLE, no additional activation will be performed. To cause the ADC to go through a full reset, the user needs to issue the CCURDPRC\_ADC\_ALL\_DISABLE followed by CCURDPRC\_ADC\_ALL\_ENABLE.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_ADC_Activate (void *Handle,
                        _ccurdprc_adc_all_enable_t activate,
                        _ccurdprc_adc_all_enable_t *current_state)

Description: Activate/DeActivate ADC module

```

```

Input:   void                                     *Handle      (Handle pointer)
         _ccurdprc_adc_all_enable_t             activate      (activate/deactivate)
         # CCURDPRC_ADC_ALL_DISABLE
         # CCURDPRC_ADC_ALL_ENABLE
         # CCURDPRC_ADC_ALL_ENABLE_DO_NOT_CHANGE
Output:  _ccurdprc_adc_all_enable_t             *current_state (active/deactive)
         # CCURDPRC_ADC_ALL_DISABLE
         # CCURDPRC_ADC_ALL_ENABLE
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR                (successful)
         # CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN                (device not open)
         # CCURDPRC_LIB_INVALID_ARG             (invalid argument)
         # CCURDPRC_LIB_NO_LOCAL_REGION         (local region not present)
*****/

```

## 2.2.4 ccurDPRC\_ADC\_Get\_Negative\_Cal()

This call returns the negative ADC calibration information to the user.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_ADC_Get_Negative_Cal(void             *Handle,
                               ccurdprc_adc_cal_t *cal)

```

Description: Get the ADC Negative Calibration data.

```

Input:   void                                     *Handle      (handle pointer)
Output:  ccurdprc_adc_cal_t                       *cal          (pointer to board cal)
         uint   Raw[CCURDPRC_MAX_CHANNELS];
         double  Float[CCURDPRC_MAX_CHANNELS];
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR                (successful)
         # CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN                (device not open)
         # CCURDPRC_LIB_INVALID_ARG             (invalid argument)
         # CCURDPRC_LIB_NO_LOCAL_REGION         (local region not present)
*****/

```

## 2.2.5 ccurDPRC\_ADC\_Get\_Offset\_Cal()

This call returns the offset ADC calibration information to the user.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_ADC_Get_Offset_Cal(void             *Handle,
                               ccurdprc_adc_cal_t *cal)

```

Description: Get the ADC Offset Calibration data.

```

Input:   void                                     *Handle      (handle pointer)
Output:  ccurdprc_adc_cal_t                       *cal          (pointer to board cal)
         uint   Raw[CCURDPRC_MAX_CHANNELS];
         double  Float[CCURDPRC_MAX_CHANNELS];
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR                (successful)
         # CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN                (device not open)
         # CCURDPRC_LIB_INVALID_ARG             (invalid argument)
         # CCURDPRC_LIB_NO_LOCAL_REGION         (local region not present)
*****/

```

## 2.2.6 ccurDPRC\_ADC\_Get\_Positive\_Cal()

This call returns the positive ADC calibration information to the user.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_ADC_Get_Positive_Cal(void          *Handle,
                                ccurdprc_adc_cal_t *cal)

Description: Get the ADC Positive Calibration data.

Input:  void          *Handle (handle pointer)
Output: ccurdprc_adc_cal_t *cal (pointer to board cal)
        uint Raw[CCURDPRC_MAX_CHANNELS];
        double Float[CCURDPRC_MAX_CHANNELS];
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/
```

## 2.2.7 ccurDPRC\_ADC\_Perform\_Auto\_Calibration()

This call performs a full ADC calibration.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_ADC_Perform_Auto_Calibration(void *Handle)

Description: Perform ADC Auto Calibration

Input:  void *Handle (handle pointer)
Output: none
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (library not open)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURDPRC_LIB_NO_RESOURCE     (no free PLL available)
        # CCURDPRC_LIB_IO_ERROR        (read error)
        # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
        # CCURDPRC_LIB_ADC_FAILURE     (ADC failure)
        # CCURDPRC_LIB_ELECTRONIC_FUSE_TRIPPED
                                           (Electronic Fuse tripped)
*****/
```

## 2.2.8 ccurDPRC\_ADC\_Perform\_External\_Negative\_Calibration()

Use this call to perform an external negative calibration. Prior to calling this function, the ADC inputs must be provided with a negative signal close to -10 Volts, otherwise this call will fail. Additionally, the user can specify a range of channels.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_ADC_Perform_External_Negative_Calibration(void *Handle,
                                                       _ccurdprc_channel_t chan_start,
                                                       _ccurdprc_channel_t chan_end,
                                                       double ReferenceVoltage)

Description: Perform ADC External Negative Calibration
```

```

Input:  void                *Handle          (handle pointer)
        _ccurdprc_channel_t chan_start      (start channel)
        _ccurdprc_channel_t chan_end        (end channel)
        double              ReferenceVoltage (Reference Voltage)
Output:  none
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR             (successful)
        # CCURDPRC_LIB_BAD_HANDLE          (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN            (library not open)
        # CCURDPRC_LIB_INVALID_ARG         (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION     (local region not present)
        # CCURDPRC_LIB_NO_RESOURCE         (no free PLL available)
        # CCURDPRC_LIB_IO_ERROR            (read error)
        # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

## 2.2.9 ccurDPRC\_ADC\_Perform\_External\_Offset\_Calibration()

Use this call to perform an external offset calibration. Prior to calling this function, the ADC inputs must be provided with a offset signal close to 0 Volts, otherwise this call will fail. Additionally, the user can specify a range of channels. Once this call is executed, the user will need to perform external negative and external positive calibrations as this call resets these gains to 1.0 prior to calibration.

```

/*****
_ccurdprc_lib_error_number_t
ccurDPRC_ADC_Perform_External_Offset_Calibration(void      *Handle,
                                                _ccurdprc_channel_t  chan_start,
                                                _ccurdprc_channel_t  chan_end)

Description: Perform ADC External Offset Calibration

Input:  void                *Handle          (handle pointer)
        _ccurdprc_channel_t chan_start      (start channel)
        _ccurdprc_channel_t chan_end        (end channel)
Output:  none
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR             (successful)
        # CCURDPRC_LIB_BAD_HANDLE          (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN            (library not open)
        # CCURDPRC_LIB_INVALID_ARG         (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION     (local region not present)
        # CCURDPRC_LIB_NO_RESOURCE         (no free PLL available)
        # CCURDPRC_LIB_IO_ERROR            (read error)
        # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

## 2.2.10 ccurDPRC\_ADC\_Perform\_External\_Positive\_Calibration()

Use this call to perform an external positive calibration. Prior to calling this function, the ADC inputs must be provided with a positive signal close to +10 Volts, otherwise this call will fail. Additionally, the user can specify a range of channels.

```

/*****
_ccurdprc_lib_error_number_t
ccurDPRC_ADC_Perform_External_Positive_Calibration(void      *Handle,
                                                _ccurdprc_channel_t  chan_start,
                                                _ccurdprc_channel_t  chan_end,
                                                double              ReferenceVoltage)

Description: Perform ADC External Positive Calibration

```



```

Input:   void          *Handle          (handle pointer)
         _ccurdprc_channel_t chan_start (start channel)
         _ccurdprc_channel_t chan_end   (end channel)
         double        ReferenceVoltage (Reference Voltage)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR        (successful)
         # CCURDPRC_LIB_BAD_HANDLE      (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN        (library not open)
         # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
         # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
         # CCURDPRC_LIB_NO_RESOURCE     (no free PLL available)
         # CCURDPRC_LIB_IO_ERROR        (read error)
         # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

### 2.2.11 ccurDPRC\_ADC\_Perform\_Negative\_Calibration()

This call performs a negative calibration using the internal reference voltage.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Perform_Negative_Calibration(void *Handle)

Description: Perform ADC Negative Calibration

Input:   void *Handle          (handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR        (successful)
         # CCURDPRC_LIB_BAD_HANDLE      (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN        (library not open)
         # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
         # CCURDPRC_LIB_NO_RESOURCE     (no free PLL available)
         # CCURDPRC_LIB_IO_ERROR        (read error)
         # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

### 2.2.12 ccurDPRC\_ADC\_Perform\_Offset\_Calibration()

This call performs an offset calibration using the internal reference voltage. Once this call is executed, the user will need to perform negative and positive calibrations as this call resets these gains to 1.0 prior to calibration.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Perform_Offset_Calibration(void *Handle)

Description: Perform ADC Offset Calibration

Input:   void *Handle          (handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR        (successful)
         # CCURDPRC_LIB_BAD_HANDLE      (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN        (library not open)
         # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
         # CCURDPRC_LIB_NO_RESOURCE     (no free PLL available)
         # CCURDPRC_LIB_IO_ERROR        (read error)
         # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/

```

### 2.2.13 ccurDPRC\_ADC\_Perform\_Positive\_Calibration()

This call performs a positive calibration using the internal reference voltage.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Perform_Positive_Calibration(void *Handle)

Description: Perform ADC Positive Calibration

Input:   void   *Handle           (handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR           (successful)
        # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (library not open)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
        # CCURDPRC_LIB_NO_RESOURCE     (no free PLL available)
        # CCURDPRC_LIB_IO_ERROR        (read error)
        # CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE (Clock is not active)
*****/
```

### 2.2.14 ccurDPRC\_ADC\_Read\_Channels()

This call provides the user an easy method of reading the ADC channels. User can supply a channel mask.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Read_Channels(void *Handle,
                             _ccurdprc_channel_mask_t ChanMask,
                             ccurdprc_adc_volts_t *adc_volts)

Description: Read ADC Channels

Input:   void   *Handle           (Handle pointer)
        _ccurdprc_channel_mask_t ChanMask   (specify channel mask)
        # CCURDPRC_CHANNEL_MASK_0
        # CCURDPRC_CHANNEL_MASK_1
        # CCURDPRC_CHANNEL_MASK_2
        # CCURDPRC_CHANNEL_MASK_3
        # CCURDPRC_CHANNEL_MASK_4
        # CCURDPRC_CHANNEL_MASK_5
        # CCURDPRC_CHANNEL_MASK_6
        # CCURDPRC_CHANNEL_MASK_7
        # CCURDPRC_CHANNEL_MASK_8
        # CCURDPRC_CHANNEL_MASK_9
        # CCURDPRC_CHANNEL_MASK_10
        # CCURDPRC_CHANNEL_MASK_11
        # CCURDPRC_CHANNEL_MASK_12
        # CCURDPRC_CHANNEL_MASK_13
        # CCURDPRC_CHANNEL_MASK_14
        # CCURDPRC_CHANNEL_MASK_15
        # CCURDPRC_ALL_CHANNELS_MASK

Output:  ccurdprc_adc_volts_t *adc_volts (pointer to ADC volts)
        uint   Raw[CCURDPRC_MAX_CHANNELS];
        double Float[CCURDPRC_MAX_CHANNELS];

Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR           (successful)
        # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/
```

## 2.2.15 ccurDPRC\_ADC\_Read\_Channels\_Calibration()

This routine reads the ADC channel calibration registers and dumps them to the user specified file. If the file name specified is NULL, then information is written to *stdout*.

```
/*
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Read_Channels_Calibration(void *Handle,
                                       char *filename)

Description: Read ADC Channels Calibration

Input:   void *Handle           (handle pointer)
Output:  char *filename         (pointer to filename)
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR           (successful)
        # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (library not open)
        # CCURDPRC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURDPRC_LIB_CANNOT_OPEN_FILE (cannot open calib. file)
*/
```

## 2.2.16 ccurDPRC\_ADC\_Set\_Negative\_Cal()

This call allows the user to set the negative calibration data for all the channels by supplying floating point *Float* gains to the call. Users can supply CCURDPRC\_DO\_NOT\_CHANGE as a gain for any channel that should not be changed. Additionally, this call will return the *RAW* value of the gain supplied that is written to the board.

```
/*
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Set_Negative_Cal(void *Handle,
                               ccurdprc_adc_cal_t *cal)

Description: Set the ADC Negative Calibration data.

Input:   void *Handle           (handle pointer)
         ccurdprc_adc_cal_t *cal (pointer to board cal)
         uint Raw[CCURDPRC_MAX_CHANNELS];
         double Float[CCURDPRC_MAX_CHANNELS];

Output:  none
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR           (successful)
        # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (library not open)
        # CCURDPRC_LIB_INVALID_ARG      (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURDPRC_LIB_NO_RESOURCE      (no free PLL available)
        # CCURDPRC_LIB_IO_ERROR         (read error)
*/
```

## 2.2.17 ccurDPRC\_ADC\_Set\_Offset\_Cal()

This call allows the user to set the offset calibration data for all the channels by supplying floating point *Float* offset to the call. Users can supply CCURDPRC\_DO\_NOT\_CHANGE as a gain for any channel that should not be changed. Additionally, this call will return the *Raw* value of the offset supplied that is written to the board.

```
/*
_ccurdprc_lib_error_number_t
ccurdPRC_ADC_Set_Offset_Cal(void *Handle,
                             ccurdprc_adc_cal_t *cal)
*/
```

Description: Set the ADC Offset Calibration data.

```
Input:   void          *Handle      (handle pointer)
         ccurdprc_adc_cal_t      *cal      (pointer to board cal)
         uint          Raw[CCURDPRC_MAX_CHANNELS];
         double        Float[CCURDPRC_MAX_CHANNELS];

Output:  none

Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR      (successful)
         # CCURDPRC_LIB_BAD_HANDLE    (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN      (library not open)
         # CCURDPRC_LIB_INVALID_ARG   (invalid argument)
         # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
         # CCURDPRC_LIB_NO_RESOURCE   (no free PLL available)
         # CCURDPRC_LIB_IO_ERROR      (read error)
*****/
```

## 2.2.18 ccurDPRC\_ADC\_Set\_Positive\_Cal()

This call allows the user to set the positive calibration data for all the channels by supplying floating point *Float* gains to the call. Users can supply CCURDPRC\_DO\_NOT\_CHANGE as a gain for any channel that should not be changed. Additionally, this call will return the *Raw* value of the gain supplied that is written to the board.

```
/*
_ccurdprc_lib_error_number_t
ccurdprc_adc_set_positive_cal(void          *Handle,
                               ccurdprc_adc_cal_t *cal)
*/
```

Description: Set the ADC Positive Calibration data.

```
Input:   void          *Handle      (handle pointer)
         ccurdprc_adc_cal_t      *cal      (pointer to board cal)
         uint          Raw[CCURDPRC_MAX_CHANNELS];
         double        Float[CCURDPRC_MAX_CHANNELS];

Output:  none

Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR      (successful)
         # CCURDPRC_LIB_BAD_HANDLE    (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN      (library not open)
         # CCURDPRC_LIB_INVALID_ARG   (invalid argument)
         # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
         # CCURDPRC_LIB_NO_RESOURCE   (no free PLL available)
         # CCURDPRC_LIB_IO_ERROR      (read error)
*****/
```

## 2.2.19 ccurDPRC\_ADC\_Write\_Channels\_Calibration()

This call allows the user to write the calibration registers from a user supplied calibration file.

```
/*
_ccurdprc_lib_error_number_t
ccurdprc_adc_write_channels_calibration(void *Handle,
                                       char *filename)
*/
```

Description: Write Channels Calibration

```
Input:   void *Handle      (handle pointer)
Output:  char *filename    (pointer to filename)
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR      (successful)
         # CCURDPRC_LIB_BAD_HANDLE    (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN      (library not open)
```

```

# CCURDPRC_LIB_NO_LOCAL_REGION      (local region not present)
# CCURDPRC_LIB_CANNOT_OPEN_FILE    (cannot open calib. file)
# CCURDPRC_LIB_INVALID_ARG         (invalid argument)
*****/

```

### 2.2.20 ccurDPRC\_Add\_Irq()

This call will add the driver interrupt handler if it has not been added. Normally, the user should not use this call unless they want to disable the interrupt handler and then re-enable it.

```

/*****
int ccurDPRC_Add_Irq(void *Handle)

Description: By default, the driver assigns an interrupt handler to handle
device interrupts. If the interrupt handler was removed using
the ccurDPRC_Remove_Irq(), then this call adds it back.

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR      (successful)
         # CCURDPRC_LIB_BAD_HANDLE   (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN     (library not open)
         # CCURDPRC_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/

```

### 2.2.21 ccurDPRC\_Clear\_Driver\_Error()

This call resets the last driver error that was maintained internally by the driver to *CCURDPRC\_SUCCESS*.

```

/*****
_ccurdprc_lib_error_number_t ccurDPRC_Clear_Driver_Error(void *Handle)

Description: Clear any previously generated driver related error.

Input:   void *Handle           (Handle pointer)
Output:  none
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR      (successful)
         # CCURDPRC_LIB_BAD_HANDLE   (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN     (device not open)
         # CCURDPRC_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/

```

### 2.2.22 ccurDPRC\_Clear\_Electronic\_Fuse\_Trip\_Fault()

If an electronic fuse trip fault occurred for a channel, that channel is no longer accessible to the user until the channel fuse trip fault is reset. Users need to query as to why the electronic fuse trip fault occurred, correct the condition that caused the fuse trip fault, and then clear the fuse trip fault for the channel with the help of this call. If the reason for the fuse trip fault is not cleared, the fault is cleared, it is likely that the electronic fuse trip will re-occur immediately. If multiple electronic fuse trip faults occur for a channel, the faults will be queued to a quantity of two deep. This call ensures that all queued faults for the requested channel are also cleared.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Clear_Electronic_Fuse_Trip_Fault (void *Handle,
                                           _ccurdprc_channel_mask_t ChanMask)

Description: Clear Electronic Fuse Trip Fault

```

```

Input:      void                    *Handle   (handle pointer)
           _ccurdprc_channel_mask_t ChanMask (specify channel mask)
           # CCURDPRC_CHANNEL_MASK_0
           # CCURDPRC_CHANNEL_MASK_1
           # CCURDPRC_CHANNEL_MASK_2
           # CCURDPRC_CHANNEL_MASK_3
           # CCURDPRC_CHANNEL_MASK_4
           # CCURDPRC_CHANNEL_MASK_5
           # CCURDPRC_CHANNEL_MASK_6
           # CCURDPRC_CHANNEL_MASK_7
           # CCURDPRC_CHANNEL_MASK_8
           # CCURDPRC_CHANNEL_MASK_9
           # CCURDPRC_CHANNEL_MASK_10
           # CCURDPRC_CHANNEL_MASK_11
           # CCURDPRC_CHANNEL_MASK_12
           # CCURDPRC_CHANNEL_MASK_13
           # CCURDPRC_CHANNEL_MASK_14
           # CCURDPRC_CHANNEL_MASK_15
           # CCURDPRC_ALL_CHANNELS_MASK

Output:     none
Return:     _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR           (successful)
           # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN         (device not open)
           # CCURDPRC_LIB_INVALID_ARG      (invalid argument)
           # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
           # CCURDPRC_LIB_IO_ERROR         (Channel Trip Fault not
                                           clearing)
*****/

```

### 2.2.23 ccurDPRC\_Clear\_Lib\_Error()

This call resets the last library error that was maintained internally by the API.

```

/*****
_ccurdprc_lib_error_number_t ccurDPRC_Clear_Lib_Error(void *Handle)

Description: Clear any previously generated library related error.

Input:      void *Handle           (Handle pointer)
Output:     none
Return:     _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR           (successful)
           # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN         (device not open)
*****

```

### 2.2.24 ccurDPRC\_Close()

This call is used to close an already opened device using the *ccurDPRC\_Open()* call.

```

/*****
_ccurdprc_lib_error_number_t ccurDPRC_Close(void *Handle)

Description: Close a previously opened device.

Input:      void *Handle           (Handle pointer)
Output:     none
Return:     _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR           (successful)
           # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN         (device not open)
*****/

```

### 2.2.25 ccurDPRC\_DataToVolts()

This routine takes a raw analog input data value and converts it to a floating point.

```

/*****
  double ccurDPRC_DataToVolts(int us_data)

  Description: Convert Data to volts

  Input:   int          us_data          (data to convert)
  Output:  none
  Return:  double       volts            (returned volts)
*****/

```

### 2.2.26 ccurDPRC\_DigitalPotentiometerAndIo\_Activate()

This call gives the user the ability to activate, disable and get the current ADC state.

```

/*****
  ccurDPRC_DigitalPotentiometerAndIo_Activate()
  _ccurdprc_lib_error_number_t
  ccurDPRC_DigitalPotentiometerAndIo_Activate (void          *Handle,
                                               _ccurdprc_digital_pot_and_io_enable_t activate,
                                               _ccurdprc_digital_pot_and_io_enable_t *current_state)

  Description: Activate/DeActivate Digital Potentiometer and I/O module

  Input:   void          *Handle          (Handle pointer)
           _ccurdprc_digital_pot_and_io_enable_t activate (activate/deactivate)
           # CCURDPRC_DIGITAL_POT_AND_IO_DISABLE
           # CCURDPRC_DIGITAL_POT_AND_IO_ENABLE
           # CCURDPRC_DIGITAL_POT_AND_IO_ENABLE_DO_NOT_CHANGE

  Output:  _ccurdprc_digital_pot_and_io_enable_t *current_state
                                               (active/deactive)
           # CCURDPRC_DIGITAL_POT_AND_IO_DISABLE
           # CCURDPRC_DIGITAL_POT_AND_IO_ENABLE

  Return:  _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR          (successful)
           # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN        (device not open)
           # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
           # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/

```

### 2.2.27 ccurDPRC\_Disable\_Pci\_Interrupts()

The purpose of this call is to disable PCI interrupts. This call shouldn't be used during normal reads as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Disable_Pci_Interrupts (void *Handle)

  Description: Disable interrupts being generated by the board.

  Input:   void *Handle          (handle pointer)
  Output:  None
  Return:  _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR          (successful)
           # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN        (device not open)
           # CCURDPRC_LIB_IOCTL_FAILED    (driver ioctl call failed)
*****/

```

\*\*\*\*\*/

### 2.2.28 ccurDPRC\_Enable\_Pci\_Interrupts()

The purpose of this call is to enable PCI interrupts. This call shouldn't be used during normal reads as calls could time out. The driver handles enabling and disabling interrupts during its normal course of operation.

/\*\*\*\*\*

```
_ccurdprc_lib_error_number_t
ccurdPRC_Enable_Pci_Interrupts (void *Handle, uint interrupt_mask)
```

Description: Enable interrupts being generated by the board.

Input: void \*Handle (Handle pointer)
uint interrupt\_mask (interrupt mask)

Output: none

Return: \_ccurdprc\_lib\_error\_number\_t
# CCURDPRC\_LIB\_NO\_ERROR (successful)
# CCURDPRC\_LIB\_BAD\_HANDLE (no/bad handler supplied)
# CCURDPRC\_LIB\_NOT\_OPEN (device not open)
# CCURDPRC\_LIB\_IOCTL\_FAILED (driver ioctl call failed)

\*\*\*\*\*/

### 2.2.29 ccurDPRC\_Fast\_Memcpy()

The purpose of this call is to provide a fast mechanism to copy between hardware and memory using programmed I/O. The library performs appropriate locking while the copying is taking place.

/\*\*\*\*\*

```
ccurdPRC_Fast_Memcpy(void *Handle,
volatile void *Destination,
volatile void *Source,
int SizeInBytes)
```

Description: Perform fast copy to/from buffer using Programmed I/O (WITH LOCKING)

Input: void \*Handle (Handle pointer)
volatile void \*Source (pointer to source buffer)
int SizeInBytes (transfer size in bytes)
Output: volatile void \*Destination (pointer to destination buffer)

Return: \_ccurdprc\_lib\_error\_number\_t
# CCURDPRC\_LIB\_NO\_ERROR (successful)
# CCURDPRC\_LIB\_BAD\_HANDLE (no/bad handler supplied)
# CCURDPRC\_LIB\_NOT\_OPEN (device not open)

\*\*\*\*\*/

### 2.2.30 ccurDPRC\_Fast\_Memcpy\_Unlocked()

The purpose of this call is to provide a fast mechanism to copy between hardware and memory using programmed I/O. The library does not perform any locking. User needs to provide external locking instead.

/\*\*\*\*\*

```
void
ccurdPRC_Fast_Memcpy_Unlocked(volatile void *Destination,
volatile void *Source,
int SizeInBytes)
```

Description: Perform fast copy to/from buffer using Programmed I/O (WITHOUT LOCKING)

Input: volatile void \*Source (pointer to source buffer)
int SizeInBytes (transfer size in bytes)



```

    Oupput: volatile void *Destination      (pointer to destination buffer)
    Return: none
    *****/

```

### 2.2.31 ccurDPRC\_Fraction\_To\_Hex()

This converts a fractional decimal to a hexadecimal value.

```

/*****
    int
    ccurDPRC_Fraction_To_Hex (double Fraction,
                             uint    *value)

    Description: Convert Fractional Decimal to Hexadecimal

    Input:      double    Fraction    (fraction to convert)
    Output:     uint      *value      (converted hexadecimal value)
    Return:     1          (call failed)
               0          (good return)
    *****/

```

### 2.2.32 ccurDPRC\_Get\_Board\_CSR()

This call returns information from the board status register.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Get_Board_CSR (void          *Handle,
                           ccurdprc_board_csr_t *bcsr)

    Description: Get Board Control and Status information

    Input:      void          *Handle    (Handle pointer)
    Output:     ccurdprc_board_csr_t    *bcsr    (pointer to board csr)
               _ccurdprc_bcsr_identify_board_t identify_board
               # CCURDPRC_BCSR_IDENTIFY_BOARD_DISABLE
               # CCURDPRC_BCSR_IDENTIFY_BOARD_ENABLE

    Return:     _ccurdprc_lib_error_number_t
               # CCURDPRC_LIB_NO_ERROR          (successful)
               # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
               # CCURDPRC_LIB_NOT_OPEN        (device not open)
               # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
               # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
    *****/

```

### 2.2.33 ccurDPRC\_Get\_Board\_Info()

This call returns the board id, the board type and the firmware revision level for the selected board. This board id is 0x9300 and board type is 0x1.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Get_Board_Info (void          *Handle,
                             ccurdprc_board_info_t *binfo)

    Description: Get Board Information

    Input:      void          *Handle    (handle pointer)
    Output:     ccurdprc_board_info_t    *binfo    (pointer to board info)
               int          board_id    (board id)
               int          board_type  (board type)
               int          firmware_rev (firmware revision)
               ccurdprc_sprom_header_t sprom_header

```

```

        u_int32_t   board_serial_number   (serial number)
        u_short    sprom_revision        (serial prom revision)
    int    number_of_channels   (number of hardware channels)
    int    all_channels_mask    (all channels mask)
    double cal_ref_voltage      (calibration reference voltage)
    double voltage_range       (maximum voltage range)
Return:   _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler
supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/

```

### 2.2.34 ccurDPRC\_Get\_CalibrationBus\_Control()

This call returns the bus calibration control.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Get_CalibrationBus_Control (void *Handle,
                                        _ccurdprc_calibration_bus_control_t *bus_control)

Description: Get Calibration Bus Control

Input:      void *Handle (handle pointer)
Output:     _ccurdprc_calibration_bus_control_t *bus_control (pointer to control select)
        # CCURDPRC_CALIBRATIONBUS_CONTROL_OPEN
        # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_2_5_VOLTS
        # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_10_VOLTS
        # CCURDPRC_CALIBRATIONBUS_CONTROL_MINUS_10_VOLTS

        # CCURDPRC_CALIBRATIONBUS_CONTROL_GROUND

        # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_8_MILLIAMP
        # CCURDPRC_CALIBRATIONBUS_CONTROL_MINUS_8_MILLIAMP
        # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_16_MILLIAMP
Return:     _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/

```

### 2.2.35 ccurDPRC\_Get\_Digital\_Potentiometer()

This call returns to the user the raw and ohms value of the digital potentiometer for the selected channels.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Get_Digital_Potentiometer (void *Handle,
                                        _ccurdprc_channel_mask_t ChanMask,
                                        ccurdprc_digital_potentiometer_t *DPValue)

Description: Get Digital Potentiometer Value

Input:      void *Handle (Handle pointer)
            _ccurdprc_channel_mask_t ChanMask (specify channel mask)
        # CCURDPRC_CHANNEL_MASK_0
        # CCURDPRC_CHANNEL_MASK_1

```

```

# CCURDPRC_CHANNEL_MASK_2
# CCURDPRC_CHANNEL_MASK_3
# CCURDPRC_CHANNEL_MASK_4
# CCURDPRC_CHANNEL_MASK_5
# CCURDPRC_CHANNEL_MASK_6
# CCURDPRC_CHANNEL_MASK_7
# CCURDPRC_CHANNEL_MASK_8
# CCURDPRC_CHANNEL_MASK_9
# CCURDPRC_CHANNEL_MASK_10
# CCURDPRC_CHANNEL_MASK_11
# CCURDPRC_CHANNEL_MASK_12
# CCURDPRC_CHANNEL_MASK_13
# CCURDPRC_CHANNEL_MASK_14
# CCURDPRC_CHANNEL_MASK_15
# CCURDPRC_ALL_CHANNELS_MASK
Output: ccurdprc_digital_potentiometer_t *DPValue (pointer to Digital
                                             Potentiometer Value)
        uint      Raw[CCURDPRC_MAX_CHANNELS];
        uint      Ohms[CCURDPRC_MAX_CHANNELS];
Return:  _ccurdprc_lib_error_number_t
# CCURDPRC_LIB_NO_ERROR                (successful)
# CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
# CCURDPRC_LIB_NOT_OPEN                (device not open)
# CCURDPRC_LIB_INVALID_ARG            (invalid argument)
# CCURDPRC_LIB_NO_LOCAL_REGION        (local region not present)
# CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE
                                         (Potentiometer and I/O Control not active)
*****/

```

## 2.2.36 ccurDPRC\_Get\_Digital\_Potentiometer\_Test()

This call returns to the user the power-down and mode selection of the digital potentiometer for the selected channels.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Get_Digital_Potentiometer_Test(void                *Handle,
                                         _ccurdprc_channel_mask_t  ChanMask,
                                         ccurdprc_digital_potentiometer_test_t *DPTTest)

```

Description: Get Digital Potentiometer Test

Input: void \*Handle (Handle pointer)  
\_ccurdprc\_channel\_mask\_t ChanMask (specify channel mask)

```

# CCURDPRC_CHANNEL_MASK_0
# CCURDPRC_CHANNEL_MASK_1
# CCURDPRC_CHANNEL_MASK_2
# CCURDPRC_CHANNEL_MASK_3
# CCURDPRC_CHANNEL_MASK_4
# CCURDPRC_CHANNEL_MASK_5
# CCURDPRC_CHANNEL_MASK_6
# CCURDPRC_CHANNEL_MASK_7
# CCURDPRC_CHANNEL_MASK_8
# CCURDPRC_CHANNEL_MASK_9
# CCURDPRC_CHANNEL_MASK_10
# CCURDPRC_CHANNEL_MASK_11
# CCURDPRC_CHANNEL_MASK_12
# CCURDPRC_CHANNEL_MASK_13
# CCURDPRC_CHANNEL_MASK_14
# CCURDPRC_CHANNEL_MASK_15
# CCURDPRC_ALL_CHANNELS_MASK
Output: ccurdprc_digital_potentiometer_test_t *DPTTest (pointer to

```

```

                                Digital Potentiometer Test)
    _ccurdprc_digital_potentiometer_test_t
                                DigitalPotTest[CCURDPRC_MAX_CHANNELS];
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT0
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT1
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT2
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT3
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_100K
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_FORCE_FAILURE
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_MODE_20K
    # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_MODE_100K
Return:  _ccurdprc_lib_error_number_t
    # CCURDPRC_LIB_NO_ERROR                (successful)
    # CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
    # CCURDPRC_LIB_NOT_OPEN                (device not open)
    # CCURDPRC_LIB_INVALID_ARG            (invalid argument)
    # CCURDPRC_LIB_NO_LOCAL_REGION        (local region error)
    # CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE
                                                (Potentiometer and I/O Control not active)
    *****/

```

### 2.2.37 ccurDPRC\_Get\_Driver\_Error()

This call returns the last error generated by the driver.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Get_Driver_Error (void          *Handle,
                                ccurdprc_user_error_t *ret_err)

Description: Get the last error generated by the driver.

Input:   void          *Handle          (Handle pointer)
Output:  ccurdprc_user_error_t *ret_err (error struct pointer)
        uint error          (error number)
        char name[CCURDPRC_ERROR_NAME_SIZE] (error name used in driver)
        char desc[CCURDPRC_ERROR_DESC_SIZE] (error description)
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR                (successful)
        # CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN                (device not open)
        # CCURDPRC_LIB_INVALID_ARG            (invalid argument)
        # CCURDPRC_LIB_IOCTL_FAILED           (driver ioctl call failed)
    *****/

```

```

#define CCURDPRC_ERROR_NAME_SIZE    64
#define CCURDPRC_ERROR_DESC_SIZE    128

typedef struct _ccurdprc_user_error_t
{
    uint error;                /* error number */
    char name[CCURDPRC_ERROR_NAME_SIZE]; /* error name used in driver */
    char desc[CCURDPRC_ERROR_DESC_SIZE]; /* error description */
} ccurdprc_user_error_t;

enum
{
    CCURDPRC_SUCCESS = 0,
    CCURDPRC_INVALID_PARAMETER,
    CCURDPRC_DMA_TIMEOUT,
    CCURDPRC_OPERATION_CANCELLED,
    CCURDPRC_RESOURCE_ALLOCATION_ERROR,
    CCURDPRC_INVALID_REQUEST,

```

```

    CCURDPRC_FAULT_ERROR,
    CCURDPRC_BUSY,
    CCURDPRC_ADDRESS_IN_USE,
    CCURDPRC_USER_INTERRUPT_TIMEOUT,
    CCURDPRC_DMA_INCOMPLETE,
    CCURDPRC_DATA_UNDERFLOW,
    CCURDPRC_DATA_OVERFLOW,
    CCURDPRC_IO_FAILURE,
    CCURDPRC_PCI_ABORT_INTERRUPT_ACTIVE,
};

```

## 2.2.38 ccurDPRC\_Get\_Driver\_Info()

This call returns internal information that is maintained by the driver.

```

/*****

```

```

    _ccurdprc_lib_error_number_t
    ccurDPRC_Get_Driver_Info (void          *Handle,
                             ccurdprc_driver_info_t *info)

```

Description: Get device information from driver.

Input: void \*Handle (handle pointer)

Output: ccurdprc\_driver\_info\_t \*info (info struct pointer)

```

    char    version[12]
    char    built[32]
    char    module_name[16]
    int     board_index
    char    board_desc[32]
    int     bus
    int     slot
    int     func
    int     vendor_id
    int     sub_vendor_id
    int     board_id
    int     board_type
    int     sub_device_id
    int     board_info
    int     msi_support
    int     irqlevel
    int     firmware
    int     number_of_channels
    int     all_channels_mask
    double  cal_ref_voltage
    int     max_dma_samples
    int     dma_size
    double  voltage_range
    ccurdprc_driver_int_t interrupt
    unsigned long long count
    u_int status
    u_int mask
    int timeout_seconds
    int     Ccurdprc_Max_Region
    ccurdprc_dev_region_t mem_region[CCURDPRC_MAX_REGION]
    uint physical_address
    uint size
    uint flags
    uint *virtual_address
    ccurdprc_sprom_header_t sprom_header
    u_int32_t board_serial_number
    u_short sprom_revision
Return:    _ccurdprc_lib_error_number_t

```

```

# CCURDPRC_LIB_NO_ERROR (successful)
# CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURDPRC_LIB_NOT_OPEN (device not open)
# CCURDPRC_LIB_INVALID_ARG (invalid argument)
# CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
# CCURDPRC_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/

```

### 2.2.39 ccurDPRC\_Get\_Driver\_Read\_Mode()

This call returns the driver read mode.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Get_Driver_Read_Mode (void *Handle,
                               _ccurdprc_driver_rw_mode_t *mode)

Description: Get current read mode that will be selected by the 'read()' call

Input:      void *Handle (handle pointer)
Output:     _ccurdprc_driver_rw_mode_t *mode (pointer to read mode)
            # CCURDPRC_PIO_CHANNEL
            # CCURDPRC_DMA_CHANNEL

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR (successful)
            # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN (device not open)
            # CCURDPRC_LIB_INVALID_ARG (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
            # CCURDPRC_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/

```

### 2.2.40 ccurDPRC\_Get\_Driver\_Write\_Mode()

This call is currently not supported for driver writes. This call returns the driver write mode.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Get_Driver_Write_Mode (void *Handle,
                                _ccurdprc_driver_rw_mode_t *mode)

Description: Get current write mode that will be selected by the 'write()' call

Input:      void *Handle (handle pointer)
Output:     _ccurdprc_driver_rw_mode_t *mode (pointer to write mode)
            # CCURDPRC_PIO_CHANNEL
            # CCURDPRC_DMA_CHANNEL

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR (successful)
            # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN (device not open)
            # CCURDPRC_LIB_INVALID_ARG (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
            # CCURDPRC_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/

```

### 2.2.41 ccurDPRC\_Get\_Electronic\_Fuse\_Base()

This call returns the Electronic Fuse Base for the selected channels. This value where the channel will fault for a short (10 ohm) resistance. This is for information only and must not be changed by the user, otherwise, it could result in damage to the board.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Get_Electronic_Fuse_Base (void                *Handle,
                                   _ccurdprc_channel_mask_t  ChanMask,
                                   ccurdprc_electronic_fuse_base_t Base)

Description: Get Electronic Fuse Base information

Input:      void                *Handle  (handle pointer)
            _ccurdprc_channel_mask_t  ChanMask  (specify channel mask)
            # CCURDPRC_CHANNEL_MASK_0
            # CCURDPRC_CHANNEL_MASK_1
            # CCURDPRC_CHANNEL_MASK_2
            # CCURDPRC_CHANNEL_MASK_3
            # CCURDPRC_CHANNEL_MASK_4
            # CCURDPRC_CHANNEL_MASK_5
            # CCURDPRC_CHANNEL_MASK_6
            # CCURDPRC_CHANNEL_MASK_7
            # CCURDPRC_CHANNEL_MASK_8
            # CCURDPRC_CHANNEL_MASK_9
            # CCURDPRC_CHANNEL_MASK_10
            # CCURDPRC_CHANNEL_MASK_11
            # CCURDPRC_CHANNEL_MASK_12
            # CCURDPRC_CHANNEL_MASK_13
            # CCURDPRC_CHANNEL_MASK_14
            # CCURDPRC_CHANNEL_MASK_15
            # CCURDPRC_ALL_CHANNELS_MASK

Output:     ccurdprc_electronic_fuse_base_t  Base[CCURDPRC_MAX_CHANNELS]
            (pointer to electronic fuse base channel array)
            _ccurdprc_electronic_fuse_base_t
            int      base_raw;
            double   base_volts;

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
*****/

```

## 2.2.42 ccurdPRC\_Get\_Electronic\_Fuse Internals()

This call returns the internal settings for the electronic fuse trip for the selected channels. This is for information only and must not be changed by the user, otherwise it could result in damage to the board.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Get_Electronic_Fuse_Internals (void                *Handle,
                                         ccurdprc_electronic_fuse_internals_t *ElectronicFuse)

Description: Get Electronic Fuse Internals information

Input:      void                *Handle  (handle pointer)
Output:     ccurdprc_electronic_fuse_internals_t  ElectronicFuse (pointer to
electronic fuse internals)
            int      electrical_short_raw;
            double   electrical_short_volts;
            int      delay;
            int      count;
            int      io_delay_raw;
            double   io_delay_microseconds;
            int      maximum_resistance_raw;

```

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```

        double maximum_resistance_ohms;
        int maximum_voltage_raw;
        double maximum_voltage_volts;
        int voltage_fault_delay_raw;
        int voltage_fault_delay_microseconds;
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR (successful)
        # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN (device not open)
        # CCURDPRC_LIB_INVALID_ARG (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/

```

### 2.2.43 ccurDPRC\_Get\_Electronic\_Fuse\_Multiplier()

This call returns the Electronic Fuse Multiplier for the selected channels. This is the value where the channel will fault for a resistance other than a short (10 ohm) resistance. This is for information only and must not be changed by the user, otherwise, it could result in damage to the board.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Get_Electronic_Fuse_Multiplier (void *Handle,
                                         _ccurdprc_channel_mask_t ChanMask,
                                         ccurdprc_electronic_fuse_multiplier_t Multiplier)

```

Description: Get Electronic Fuse Multiplier information

```

Input:  void *Handle (handle pointer)
        _ccurdprc_channel_mask_t ChanMask (specify channel mask)
        # CCURDPRC_CHANNEL_MASK_0
        # CCURDPRC_CHANNEL_MASK_1
        # CCURDPRC_CHANNEL_MASK_2
        # CCURDPRC_CHANNEL_MASK_3
        # CCURDPRC_CHANNEL_MASK_4
        # CCURDPRC_CHANNEL_MASK_5
        # CCURDPRC_CHANNEL_MASK_6
        # CCURDPRC_CHANNEL_MASK_7
        # CCURDPRC_CHANNEL_MASK_8
        # CCURDPRC_CHANNEL_MASK_9
        # CCURDPRC_CHANNEL_MASK_10
        # CCURDPRC_CHANNEL_MASK_11
        # CCURDPRC_CHANNEL_MASK_12
        # CCURDPRC_CHANNEL_MASK_13
        # CCURDPRC_CHANNEL_MASK_14
        # CCURDPRC_CHANNEL_MASK_15
        # CCURDPRC_ALL_CHANNELS_MASK
Output:  ccurdprc_electronic_fuse_multiplier_t
Multiplier[CCURDPRC_MAX_CHANNELS] (pointer to electronic fuse
multiplier channel array)
        _ccurdprc_electronic_fuse_multiplier_t
        int multiplier_raw;
        double multiplier_volts;
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR (successful)
        # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN (device not open)
        # CCURDPRC_LIB_INVALID_ARG (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/

```



## 2.2.44 ccurDPRC\_Get\_Electronic\_Fuse\_Status()

This call returns the various Electronic Fuse Trip Status for the board.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Get_Electronic_Fuse_Status (void *Handle,
                                       ccurdprc_electronic_fuse_status_t *Status)

  Description: Get Electronic Fuse Status information

  Input:      void *Handle (handle pointer)
  Output:     ccurdprc_electronic_fuse_status_t Status (pointer to
electronic fuse status)
  _ccurdprc_efstat_fuse_tripped_t any_fuse_tripped
      # CCURDPRC_EFSTAT_FUSE_NOT_TRIPPED
      # CCURDPRC_EFSTAT_FUSE_TRIPPED
  _ccurdprc_efstat_fuse_adc_failed_t adc_1_fuse_failed
      # CCURDPRC_EFSTAT_FUSE_ADC_NOT_FAILED
      # CCURDPRC_EFSTAT_FUSE_ADC_FAILED
  _ccurdprc_efstat_fuse_adc_failed_t adc_0_fuse_failed
      # CCURDPRC_EFSTAT_FUSE_ADC_NOT_FAILED
      # CCURDPRC_EFSTAT_FUSE_ADC_FAILED
  _ccurdprc_efstat_fuse_tripped_t
channel_fuse_tripped[CCURDPRC_MAX_CHANNELS]
      # CCURDPRC_EFSTAT_FUSE_NOT_TRIPPED
      # CCURDPRC_EFSTAT_FUSE_TRIPPED
  int
channel_fuse_tripped_mask
  Return:     _ccurdprc_lib_error_number_t
      # CCURDPRC_LIB_NO_ERROR (successful)
      # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
      # CCURDPRC_LIB_NOT_OPEN (device not open)
      # CCURDPRC_LIB_INVALID_ARG (invalid argument)
      # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/
```

## 2.2.45 ccurDPRC\_Get\_Electronic\_Fuse\_Threshold()

This call returns the Electronic Fuse Threshold for selected channels. This is for information only and must not be changed by the user, otherwise, it could result in damage to the board.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Get_Electronic_Fuse_Threshold (void *Handle,
                                           _ccurdprc_channel_mask_t ChanMask,
                                           ccurdprc_electronic_fuse_threshold_t Threshold)

  Description: Get Electronic Fuse Threshold information

  Input:      void *Handle (handle pointer)
              _ccurdprc_channel_mask_t ChanMask (specify channel mask)
              # CCURDPRC_CHANNEL_MASK_0
              # CCURDPRC_CHANNEL_MASK_1
              # CCURDPRC_CHANNEL_MASK_2
              # CCURDPRC_CHANNEL_MASK_3
              # CCURDPRC_CHANNEL_MASK_4
              # CCURDPRC_CHANNEL_MASK_5
              # CCURDPRC_CHANNEL_MASK_6
              # CCURDPRC_CHANNEL_MASK_7
              # CCURDPRC_CHANNEL_MASK_8
              # CCURDPRC_CHANNEL_MASK_9
              # CCURDPRC_CHANNEL_MASK_10
*****/
```

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```

        # CCURDPRC_CHANNEL_MASK_11
        # CCURDPRC_CHANNEL_MASK_12
        # CCURDPRC_CHANNEL_MASK_13
        # CCURDPRC_CHANNEL_MASK_14
        # CCURDPRC_CHANNEL_MASK_15
        # CCURDPRC_ALL_CHANNELS_MASK
Output:      ccurdprc_electronic_fuse_threshold_t
Threshold[CCURDPRC_MAX_CHANNELS]

(pointer to electronic fuse
threshold channel array)
      _ccurdprc_electronic_fuse_threshold_t
      int      threshold_raw;
      double   threshold_volts;
Return:     _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR      (successful)
        # CCURDPRC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN     (device not open)
        # CCURDPRC_LIB_INVALID_ARG  (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/

```

## 2.2.46 ccurDPRC\_Get\_Electronic\_Fuse\_Trip()

This call returns the Electronic Fuse Trip for selected channels. This is for information only and must not be changed by the user, otherwise, it could result in damage to the board.

```

/*****
      _ccurdprc_lib_error_number_t
      ccurDPRC_Get_Electronic_Fuse_Trip (void      *Handle,
                                         _ccurdprc_channel_mask_t ChanMask,
                                         ccurdprc_electronic_fuse_channel_trip_t Trip)

```

Description: Get Electronic Fuse Trip information

```

Input:      void      *Handle      (handle pointer)
            _ccurdprc_channel_mask_t ChanMask (specify channel mask)
            # CCURDPRC_CHANNEL_MASK_0
            # CCURDPRC_CHANNEL_MASK_1
            # CCURDPRC_CHANNEL_MASK_2
            # CCURDPRC_CHANNEL_MASK_3
            # CCURDPRC_CHANNEL_MASK_4
            # CCURDPRC_CHANNEL_MASK_5
            # CCURDPRC_CHANNEL_MASK_6
            # CCURDPRC_CHANNEL_MASK_7
            # CCURDPRC_CHANNEL_MASK_8
            # CCURDPRC_CHANNEL_MASK_9
            # CCURDPRC_CHANNEL_MASK_10
            # CCURDPRC_CHANNEL_MASK_11
            # CCURDPRC_CHANNEL_MASK_12
            # CCURDPRC_CHANNEL_MASK_13
            # CCURDPRC_CHANNEL_MASK_14
            # CCURDPRC_CHANNEL_MASK_15
            # CCURDPRC_ALL_CHANNELS_MASK
Output:     ccurdprc_electronic_fuse_channel_trip_t Trip[CCURDPRC_MAX_CHANNELS]
            (pointer to electronic fuse trip channel array)
            _ccurdprc_electronic_fuse_channel_trip_t
            _ccurdprc_eft_fuse_tripped_t      fuse_trip_status
            # CCURDPRC_EFT_FUSE_NOT_TRIPPED
            # CCURDPRC_EFT_FUSE_TRIPPED
            _ccurdprc_eft_invalid_calibration_fuse_trip_t
            invalid_calibration_trip
            # CCURDPRC_EFT_FUSE_NOT_TRIPPED
            # CCURDPRC_EFT_FUSE_TRIPPED

```

```

        _ccurDPRC_eft_potentiometer_failure_fuse_trip_t
        potentiometer_failure_trip
        # CCURDPRC_EFT_FUSE_NOT_TRIPPED
        # CCURDPRC_EFT_FUSE_TRIPPED
        _ccurDPRC_eft_adc_failure_fuse_trip_t          adc_failure_trip
        # CCURDPRC_EFT_FUSE_NOT_TRIPPED
        # CCURDPRC_EFT_FUSE_TRIPPED
        _ccurDPRC_eft_switch_voltage_fuse_trip_t      witch_voltage_trip
        # CCURDPRC_EFT_FUSE_NOT_TRIPPED
        # CCURDPRC_EFT_FUSE_TRIPPED
        _ccurDPRC_eft_adc_compare_fuse_trip_t         adc_compare_trip
        # CCURDPRC_EFT_FUSE_NOT_TRIPPED
        # CCURDPRC_EFT_FUSE_TRIPPED
        uint                                           last_adc_tripped_raw
        double                                          last_adc_tripped_volts
Return:      _ccurDPRC_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR                      (successful)
        # CCURDPRC_LIB_BAD_HANDLE                    (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN                      (device not open)
        # CCURDPRC_LIB_INVALID_ARG                   (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION               (local region error)
*****/

```

## 2.2.47 ccurDPRC\_Get\_Interrupt\_Control()

This call returns the interrupt control information.

```

/*****
_ccurDPRC_lib_error_number_t
ccurDPRC_Get_Interrupt_Control (void          *Handle,
                                ccurDPRC_interrupt_t *intr)

Description: Get Interrupt Control information

Input:      void          *Handle (handle pointer)
Output:     ccurDPRC_interrupt_t *intr (pointer to interrupt control)
            int global_int
            int plx_local_int
Return:     _ccurDPRC_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/

```

## 2.2.48 ccurDPRC\_Get\_Interrupt\_Status()

This call returns the current status of the PLX interrupt.

```

/*****
_ccurDPRC_lib_error_number_t
ccurDPRC_Get_Interrupt_Status (void          *Handle,
                                ccurDPRC_interrupt_t *intr)

Description: Get Interrupt Status information

Input:      void          *Handle (handle pointer)
Output:     ccurDPRC_interrupt_t *intr (pointer to interrupt status)
            int plx_local_int
            # CCURDPRC_ISR_LOCAL_PLX_NONE
            # CCURDPRC_ISR_LOCAL_PLX_OCCURRED
Return:     _ccurDPRC_lib_error_number_t

```

```

# CCURDPRC_LIB_NO_ERROR          (successful)
# CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
# CCURDPRC_LIB_NOT_OPEN          (device not open)
# CCURDPRC_LIB_INVALID_ARG       (invalid argument)
# CCURDPRC_LIB_NO_LOCAL_REGION   (local region error)
*****/

```

### 2.2.49 ccurDPRC\_Get\_Interrupt\_Timeout\_Seconds()

This call returns the read time out maintained by the driver. It is the time that the read call will wait before it times out. The call could time out because a DMA fails to complete. The device should have been opened in the block mode (*O\_NONBLOCK* not set) for reads to wait for the operation to complete.

```

/*****
_ccurdprc_lib_error_number_t
ccurDPRC_Get_Interrupt_Timeout_Seconds (void      *Handle,
                                         int      *int_timeout_secs)

Description: Get Interrupt Timeout Seconds

Input:   void      *Handle      (Handle pointer)
Output:  int       *int_timeout_secs (pointer to int tout secs)
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE        (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN          (device not open)
        # CCURDPRC_LIB_INVALID_ARG       (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION   (local region not present)
        # CCURDPRC_LIB_IOCTL_FAILED     (ioctl error)
*****/

```

### 2.2.50 ccurDPRC\_Get\_IO\_Control()

This call returns the IO Control settomg for the selected channels.

```

/*****
_ccurdprc_lib_error_number_t
ccurDPRC_Get_IO_Control(void      *Handle,
                           _ccurdprc_channel_mask_t ChanMask,
                           ccurdprc_io_control_t   *IoControl)

Description: Get I/O Control

Input:   void      *Handle      (Handle pointer)
        _ccurdprc_channel_mask_t ChanMask      (specify channel mask)
        # CCURDPRC_CHANNEL_MASK_0
        # CCURDPRC_CHANNEL_MASK_1
        # CCURDPRC_CHANNEL_MASK_2
        # CCURDPRC_CHANNEL_MASK_3
        # CCURDPRC_CHANNEL_MASK_4
        # CCURDPRC_CHANNEL_MASK_5
        # CCURDPRC_CHANNEL_MASK_6
        # CCURDPRC_CHANNEL_MASK_7
        # CCURDPRC_CHANNEL_MASK_8
        # CCURDPRC_CHANNEL_MASK_9
        # CCURDPRC_CHANNEL_MASK_10
        # CCURDPRC_CHANNEL_MASK_11
        # CCURDPRC_CHANNEL_MASK_12
        # CCURDPRC_CHANNEL_MASK_13
        # CCURDPRC_CHANNEL_MASK_14
        # CCURDPRC_CHANNEL_MASK_15
        # CCURDPRC_ALL_CHANNELS_MASK

```

```

Output:  ccurdprc_io_control_t          *IoControl (pointer to I/O
control)

        _ccurdprc_io_control_t
IoSignal[CCURDPRC_MAX_CHANNELS];
        # CCURDPRC_IO_CONTROL_OPEN
        # CCURDPRC_IO_CONTROL_EXTERNAL
        # CCURDPRC_IO_CONTROL_TEST_BUS
        # CCURDPRC_IO_CONTROL_RA_GROUND_FAULT
        # CCURDPRC_IO_CONTROL_RB_GROUND_FAULT
        # CCURDPRC_IO_CONTROL_RA_RB_GROUND_FAULT
        # CCURDPRC_IO_CONTROL_RA_V_PLUS_FAULT
        # CCURDPRC_IO_CONTROL_RB_V_PLUS_FAULT
        # CCURDPRC_IO_CONTROL_RA_RB_V_PLUS_FAULT
        # CCURDPRC_IO_CONTROL_RA_V_PLUS_RB_GROUND_FAULT_SWITCH
        # CCURDPRC_IO_CONTROL_RA_GROUND_RB_V_PLUS_FAULT_SWITCH

Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
        # CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE
                                           (Potentiometer and I/O Control not active)
*****/

```

### 2.2.51 ccurDPRC\_Get\_Lib\_Error\_Description()

This call returns the library error name and description for the supplied error number.

```

/*****

ccurDPRC_Get_Lib_Error_Description()

Description: Get Error Description of supplied error number.

Input:  int          ErrorNumber      (Library error number)
Output: ccurdprc_lib_error_description_t *lib_error_desc (error description struct pointer)
        -- int found
        -- char name[CCURDPRC_LIB_ERROR_NAME_SIZE] (last library error name)
        -- char desc[CCURDPRC_LIB_ERROR_DESC_SIZE] (last library error description)

Return: none

*****/

```

### 2.2.52 ccurDPRC\_Get\_Lib\_Error()

This call provides detailed information about the last library error that was maintained by the API.

```

/*****

_ccurdprc_lib_error_number_t
ccurDPRC_Get_Lib_Error (void          *Handle,
                       ccurdprc_lib_error_t *lib_error)

Description: Get last error generated by the library.

Input:  void          *Handle          (Handle pointer)
Output: ccurdprc_lib_error_t *lib_error (error struct pointer)
        -- uint error          (last library error number)
        -- char name[CCURDPRC_LIB_ERROR_NAME_SIZE] (last library error name)
        -- char desc[CCURDPRC_LIB_ERROR_DESC_SIZE] (last library error
        description)
        -- int line_number      (last library error line number
        in lib)

```

```

-- char function[CCURDPRC_LIB_ERROR_FUNC_SIZE]
                                (library function in error)
-- ccurdprc_lib_error_backtrace_t BT[CCURDPRC_BACK_TRACE_DEPTH]
                                (backtrace of errors)
-- int line_number
                                (line number in library)
-- char function[CCURDPRC_LIB_ERROR_FUNC_SIZE]
                                (library function)

Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN        (device not open)
*****/
typedef struct
{
    int line_number;                /* line number in library */
    char function[CCURDPRC_LIB_ERROR_FUNC_SIZE]; /* library function */
} ccurdprc_lib_error_backtrace_t;

typedef struct
{
    uint error;                     /* last library error number */
    char name[CCURDPRC_LIB_ERROR_NAME_SIZE]; /* last library error name */
    char desc[CCURDPRC_LIB_ERROR_DESC_SIZE]; /* last library error description */
    int line_number;                /* last library error line number in
                                lib */
    char function[CCURDPRC_LIB_ERROR_FUNC_SIZE]; /* library function in error */
    ccurdprc_lib_error_backtrace_t BT[CCURDPRC_BACK_TRACE_DEPTH];
                                /* backtrace of errors */
} ccurdprc_lib_error_t;

```

#### Possible library errors:

```

CCURDPRC_LIB_NO_ERROR          = 0, /* successful */
CCURDPRC_LIB_INVALID_ARG     = -1, /* invalid argument */
CCURDPRC_LIB_ALREADY_OPEN    = -2, /* already open */
CCURDPRC_LIB_OPEN_FAILED     = -3, /* open failed */
CCURDPRC_LIB_BAD_HANDLE      = -4, /* bad handle */
CCURDPRC_LIB_NOT_OPEN        = -5, /* device not opened */
CCURDPRC_LIB_MMAP_SELECT_FAILED = -6, /* mmap selection failed */
CCURDPRC_LIB_MMAP_FAILED     = -7, /* mmap failed */
CCURDPRC_LIB_MUNMAP_FAILED   = -8, /* munmap failed */
CCURDPRC_LIB_NOT_MAPPED     = -9, /* not mapped */
CCURDPRC_LIB_ALREADY_MAPPED  = -10, /* already mapped */
CCURDPRC_LIB_IOCTL_FAILED    = -11, /* driver ioctl failed */
CCURDPRC_LIB_IO_ERROR        = -12, /* i/o error */
CCURDPRC_LIB_INTERNAL_ERROR  = -13, /* internal library error */
CCURDPRC_LIB_NOT_IMPLEMENTED = -14, /* call not implemented */
CCURDPRC_LIB_LOCK_FAILED     = -15, /* failed to get lib lock */
CCURDPRC_LIB_NO_LOCAL_REGION = -16, /* local region not present */
CCURDPRC_LIB_NO_CONFIG_REGION = -17, /* config region not present */
CCURDPRC_LIB_NO_SOLUTION_FOUND = -18, /* no solution found */
CCURDPRC_LIB_CONVERTER_RESET = -19, /* converter not active */
CCURDPRC_LIB_NO_RESOURCE     = -20, /* resource not available */
CCURDPRC_LIB_CALIBRATION_RANGE_ERROR = -21, /* calibration voltage out of range */
CCURDPRC_LIB_CANNOT_OPEN_FILE = -23, /* cannot open file */
CCURDPRC_LIB_BAD_DATA_IN_CAL_FILE = -24, /* bad date in calibration file */
CCURDPRC_LIB_UNUSED_25       = -25, /* UNUSED */
CCURDPRC_LIB_SERIAL_PROM_BUSY = -26, /* serial prom busy */
CCURDPRC_LIB_SERIAL_PROM_FAILURE = -27, /* serial prom failure - malfunction
occurred */
CCURDPRC_LIB_INVALID_CRC     = -28, /* invalid CRC read */
CCURDPRC_LIB_SERIAL_PROM_WRITE_PROTECTED = -29, /* serial prom is write protected */
CCURDPRC_LIB_ADC_IS_NOT_ACTIVE = -30, /* ADC is not active */

```

```

CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE          = -31, /* Digital Potentiometer & I/O is not
                                                    active */
CCURDPRC_LIB_CLOCK_IS_NOT_ACTIVE                      =  32, /* ADC Clock is not active */
CCURDPRC_LIB_ADC_FAILURE                              = -33, /* ADC Failure */
CCURDPRC_LIB_ELECTRONIC_FUSE_TRIPPED                  = -34, /* Electronic Fuse Tripped */

```

### 2.2.53 ccurDPRC\_Get\_Mapped\_Config\_Ptr()

If the user wishes to bypass the API and communicate directly with the board configuration registers, then they can use this call to acquire a pointer to these registers. Please note that any type of access (read or write) by bypassing the API could compromise the API and results could be unpredictable. It is recommended that only advanced users should use this call and with extreme care and intimate knowledge of the hardware programming registers before attempting to access these registers. For information on the registers, refer to the *ccurdprc\_user.h* include file that is supplied with the driver.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Get_Mapped_Config_Ptr (void                *Handle,
                               ccurdprc_config_local_data_t **config_ptr)

Description: Get mapped configuration pointer.

Input:   void                *Handle      (Handle pointer)
Output:  ccurdprc_config_local_data_t **config_ptr (config struct ptr)
        -- structure in ccurdprc_user.h
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN        (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_CONFIG_REGION (config region not present)
*****/

```

### 2.2.54 ccurDPRC\_Get\_Mapped\_Driver\_Library\_Ptr()

The driver and library share a common structure. This call returns a pointer to the shared driver/library structure.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Get_Mapped_Driver_Library_Ptr (void                *Handle,
                                       ccurdprc_driver_library_common_t **driver_lib_ptr)

Description: Get mapped Driver/Library structure pointer.

Input:   void                *Handle      (Handle pointer)
Output:  ccurdprc_driver_library_common_t **driver_lib_ptr
        (driver_lib struct ptr)
        uint dma_abort_count          (DMA abort count)
        ccurdprc_sprom_header_t sprom_header
        u_int32_t board_serial_number (serial number)
        u_short   sprom_revision     (serial revision)
        uint library_needs_initialization
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN        (device not open)
        # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
*****/

```

## 2.2.55 ccurDPRC\_Get\_Mapped\_Local\_Ptr()

If the user wishes to bypass the API and communicate directly with the board control and data registers, then they can use this call to acquire a pointer to these registers. Please note that any type of access (read or write) by bypassing the API could compromise the API and results could be unpredictable. It is recommended that only advanced users should use this call and with extreme care and intimate knowledge of the hardware programming registers before attempting to access these registers. For information on the registers, refer to the *ccurdprc\_user.h* include file that is supplied with the driver.

```
/*
_ccurdprc_lib_error_number_t
ccurdPRC_Get_Mapped_Local_Ptr (void *Handle,
                               ccurdprc_local_ctrl_data_t **local_ptr)

Description: Get mapped local pointer.

Input: void *Handle (Handle pointer)
Output: ccurdprc_local_ctrl_data_t **local_ptr (local struct ptr)
        -- structure in ccurdprc_user.h
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR (successful)
        # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN (device not open)
        # CCURDPRC_LIB_INVALID_ARG (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
*/
```

## 2.2.56 ccurDPRC\_Get\_Open\_File\_Descriptor()

When the library *ccurdPRC\_Open()* call is successfully invoked, the board is opened using the system call *open(2)*. The file descriptor associated with this board is returned to the user with this call. This call allows advanced users to bypass the library and communicate directly with the driver with calls like *read(2)*, *ioctl(2)*, etc. Normally, this is not recommended as internal checking and locking is bypassed and the library calls can no longer maintain integrity of the functions. This is only provided for advanced users who want more control and are aware of the implications.

```
/*
_ccurdprc_lib_error_number_t
ccurdPRC_Get_Open_File_Descriptor (void *Handle,
                                   int *fd)

Description: Get Open File Descriptor

Input: void *Handle (Handle pointer)
Output: int *fd (open file descriptor)
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR (successful)
        # CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN (device not open)
        # CCURDPRC_LIB_INVALID_ARG (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
*/
```

## 2.2.57 ccurDPRC\_Get\_Physical\_Memory()

This call returns to the user the physical memory pointer and size that was previously allocated by the *ccurdPRC\_Mmap\_Physical\_Memory()* call. The physical memory is allocated by the user when they wish to perform their own DMA and bypass the API. Once again, this call is only useful for advanced users.

```
/*
_ccurdprc_lib_error_number_t
```



```

ccurDPRC_Get_Physical_Memory (void          *Handle,
                               ccurdprc_phys_mem_t *phys_mem)

Description: Get previously mmaped() physical memory address and size

Input:      void          *Handle          (handle pointer)
Output:     ccurdprc_phys_mem_t *phys_mem  (mem struct pointer)
           void *phys_mem
           uint phys_mem_size
Return:     _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR          (successful)
           # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN        (device not open)
           # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
           # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
*****/

```

## 2.2.58 ccurDPRC\_Get\_Value()

This call allows the user to read the board registers. The actual data returned will depend on the command register information that is requested. Refer to the hardware manual for more information on what is being returned. Most commands return a pointer to an unsigned integer.

```

/*****
ccurDPRC_Get_Value()
_ccurdprc_lib_error_number_t
ccurDPRC_Get_Value (void          *Handle,
                   CCURDPRC_CONTROL cmd,
                   void          *value)

```

Description: Return the value of the specified board register.

```

Input:      void          *Handle          (handle pointer)
           CCURDPRC_CONTROL cmd          (register definition)
           # CCURDPRC_CONTROL_BOARD_INFORMATION
           # CCURDPRC_CONTROL_BOARD_CSR
           # CCURDPRC_CONTROL_INTERRUPT_CONTROL
           # CCURDPRC_CONTROL_INTERRUPT_STATUS
           # CCURDPRC_CONTROL_CALIBRATION_BUS_CONTROL
           # CCURDPRC_CONTROL_FIRMWARE_SPI_COUNTER_STATUS
           # CCURDPRC_CONTROL_ADC_ENABLE
           # CCURDPRC_CONTROL_DIGITAL_POTENTIOMETER_AND_IO_ENABLE

           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_0
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_1
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_2
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_3
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_4
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_5
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_6
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_7
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_8
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_9
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_10
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_11
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_12
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_13
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_14
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_15

           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_0
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_1
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_2

```

```

# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_3
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_4
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_5
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_6
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_7
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_8
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_9
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_10
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_11
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_12
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_13
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_14
# CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_15

# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_0
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_1
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_2
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_3
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_4
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_5
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_6
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_7
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_8
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_9
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_10
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_11
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_12
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_13
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_14
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_15

# CCURDPRC_ADC_DATA_CHANNEL_0
# CCURDPRC_ADC_DATA_CHANNEL_1
# CCURDPRC_ADC_DATA_CHANNEL_2
# CCURDPRC_ADC_DATA_CHANNEL_3
# CCURDPRC_ADC_DATA_CHANNEL_4
# CCURDPRC_ADC_DATA_CHANNEL_5
# CCURDPRC_ADC_DATA_CHANNEL_6
# CCURDPRC_ADC_DATA_CHANNEL_7
# CCURDPRC_ADC_DATA_CHANNEL_8
# CCURDPRC_ADC_DATA_CHANNEL_9
# CCURDPRC_ADC_DATA_CHANNEL_10
# CCURDPRC_ADC_DATA_CHANNEL_11
# CCURDPRC_ADC_DATA_CHANNEL_12
# CCURDPRC_ADC_DATA_CHANNEL_13
# CCURDPRC_ADC_DATA_CHANNEL_14
# CCURDPRC_ADC_DATA_CHANNEL_15

# CCURDPRC_CONTROL_SPROM_STAT_ADDR_WRITE_DATA

# CCURDPRC_IO_CONTROL_CHANNEL_0
# CCURDPRC_IO_CONTROL_CHANNEL_1
# CCURDPRC_IO_CONTROL_CHANNEL_2
# CCURDPRC_IO_CONTROL_CHANNEL_3
# CCURDPRC_IO_CONTROL_CHANNEL_4
# CCURDPRC_IO_CONTROL_CHANNEL_5
# CCURDPRC_IO_CONTROL_CHANNEL_6
# CCURDPRC_IO_CONTROL_CHANNEL_7
# CCURDPRC_IO_CONTROL_CHANNEL_8
# CCURDPRC_IO_CONTROL_CHANNEL_9
# CCURDPRC_IO_CONTROL_CHANNEL_10
# CCURDPRC_IO_CONTROL_CHANNEL_11
# CCURDPRC_IO_CONTROL_CHANNEL_12

```

```

# CCURDPRC_IO_CONTROL_CHANNEL_13
# CCURDPRC_IO_CONTROL_CHANNEL_14
# CCURDPRC_IO_CONTROL_CHANNEL_15

# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_0
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_1
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_2
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_3
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_4
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_5
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_6
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_7
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_8
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_9
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_10
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_11
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_12
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_13
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_14
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_15

# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_0
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_1
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_2
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_3
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_4
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_5
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_6
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_7
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_8
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_9
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_10
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_11
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_12
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_13
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_14
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_15

# CCURDPRC_CONTROL_SPROM_READ_DATA

# CCURDPRC_ELECTRONIC_FUSE_STATUS

# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_ELECTRICAL_SHORT_VALUE
# CCURDPRC_ELECTRONIC_FUSE_DELAY_VALUE
# CCURDPRC_ELECTRONIC_FUSE_COUNT_VALUE
# CCURDPRC_ELECTRONIC_FUSE_IO_DELAY_VALUE

```

```

# CCURDPRC_ELECTRONIC_FUSE_MAXIMUM_RESISTANCE
# CCURDPRC_ELECTRONIC_FUSE_MAXIMUM_VOLTAGE
# CCURDPRC_ELECTRONIC_FUSE_VOLTAGE_FAULT_DELAY

# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_15

# CCURDPRC_CONTROL_SPI_RAM
Output: void *value; (pointer to value)
Return: _ccurdprc_lib_error_number_t
# CCURDPRC_LIB_NO_ERROR (successful)
# CCURDPRC_LIB_BAD_HANDLE (no/bad handler supplied)
# CCURDPRC_LIB_NOT_OPEN (device not open)
# CCURDPRC_LIB_INVALID_ARG (invalid argument)
# CCURDPRC_LIB_NO_LOCAL_REGION (local region error)

```

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### 2.2.59 ccurDPRC\_Hex\_To\_Fraction()

This call converts a hexadecimal value to a fractional decimal.

```
double
ccurDPRC_Hex_To_Fraction (uint value)

Description: Convert Hexadecimal to Fractional Decimal

Input:      uint      value      (hexadecimal to convert)
Output:     none
Return:     double    Fraction    (converted fractional value)
*****/
```

### 2.2.60 ccurDPRC\_Identify\_Board()

This call is useful in identifying a physical board via software control. It causes the front LED to either flash or stay steady. Users can also specify the number of seconds they wish to flash the LED.

```
ccurdprc_lib_error_number_t
ccurDPRC_Identify_Board (void *Handle,
                        _ccurdprc_identify_t Identify)

Description: Identify the board by setting the front LED

Input:      void *Handle      (Handle pointer)
            _ccurdprc_identify_t Identify
            # CCURDPRC_IDENTIFY_OFF      (turn off flashing)
            # CCURDPRC_IDENTIFY_ON      (turn on flashing)
            # Number of seconds to flash (flash for number of seconds)

Output:     none
Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR      (successful)
            # CCURDPRC_LIB_BAD_HANDLE   (no/bad handler supplied)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
            # CCURDPRC_LIB_NOT_OPEN     (device not open)
            # CCURDPRC_LIB_INVALID_ARG  (invalid argument)
*****/
```

### 2.2.61 ccurDPRC\_Initialize\_Board()

This call resets the board to a default initial state. This call is currently identical to the *ccurDPRC\_Reset\_Board()* call.

```
_ccurdprc_lib_error_number_t
ccurDPRC_Initialize_Board (void *Handle)

Description: Initialize the board.

Input:      void *Handle      (Handle pointer)
Output:     none
Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR      (successful)
            # CCURDPRC_LIB_BAD_HANDLE   (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN     (device not open)
            # CCURDPRC_LIB_IOCTL_FAILED (driver ioctl call failed)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region not present)
*****/
```

## 2.2.62 ccurDPRC\_MMap\_Physical\_Memory()

This call is provided for advanced users to create a physical memory of specified size that can be used for DMA. The allocated DMA memory is rounded to a page size. If a physical memory is not available, this call will fail, at which point the user will need to issue the *ccurDPRC\_Munmap\_Physical\_Memory()* API call to remove the previously allocated physical memory.

```
/*
  _ccurdprc_lib_error_number_t
  ccurDPRC_MMap_Physical_Memory (void *Handle,
                                int size,
                                void **mem_ptr)
```

Description: Allocate a physical DMA memory for size bytes.

```
Input:      void      *Handle      (handle pointer)
            int       size         (size in bytes)
Output:     void      **mem_ptr    (mapped memory pointer)
Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR      (successful)
            # CCURDPRC_LIB_BAD_HANDLE   (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN     (device not open)
            # CCURDPRC_LIB_INVALID_ARG  (invalid argument)
            # CCURDPRC_LIB_MMAP_SELECT_FAILED (mmap selection failed)
            # CCURDPRC_LIB_MMAP_FAILED  (mmap failed)
```

```
*/
```

## 2.2.63 ccurDPRC\_Munmap\_Physical\_Memory()

This call simply removes a physical memory that was previously allocated by the *ccurDPRC\_MMap\_Physical\_Memory()* API call.

```
/*
  _ccurdprc_lib_error_number_t
  ccurDPRC_Munmap_Physical_Memory (void *Handle)
```

Description: Unmap a previously mapped physical DMA memory.

```
Input:      void      *Handle      (handle pointer)
Output:     None
Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR      (successful)
            # CCURDPRC_LIB_BAD_HANDLE   (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN     (device not open)
            # CCURDPRC_LIB_INVALID_ARG  (invalid argument)
            # CCURDPRC_LIB_MMAP_SELECT_FAILED (mmap selection failed)
            # CCURDPRC_LIB_MMAP_FAILED  (mmap failed)
```

```
*/
```

## 2.2.64 ccurDPRC\_NanoDelay()

This call goes into a tight loop spinning for the requested nano seconds specified by the user.

```
/*
  void
  ccurDPRC_NanoDelay (unsigned long long NanoDelay)
```

Description: Delay (loop) for user specified nano-seconds

```
Input:      unsigned long long NanoDelay      (number of nano-secs to delay)
Output:     none
Return:     none
```

\*\*\*\*\*/

## 2.2.65 ccurDPRC\_Open()

This is the first call that needs to be issued by a user to open a device and access the board through the rest of the API calls. What is returned is a handle to a *void pointer* that is supplied as an argument to the other API calls. The *Board\_Number* is a valid board number [0..9] that is associated with a physical card. There must exist a character special file */dev/ccurdprc<Board\_Number>* for the call to be successful. One character special file is created for each board found when the driver is successfully loaded.

The *oflag* is the flag supplied to the *open(2)* system call by this API. It is normally '0' (*zero*), however the user may use the *O\_NONBLOCK* option for *read(2)* calls which will change the default reading in block mode.

This driver allows multiple applications to open the same board by specifying an additional *oflag O\_APPEND*. It is then the responsibility of the user to ensure that the various applications communicating with the same cards are properly synchronized. Various tests supplied in this package has the *O\_APPEND* flags enabled, however, it is strongly recommended that only one application be run with a single card at a time, unless the user is well aware of how the applications are going to interact with each other and accept any unpredictable results.

In case of error, *errno* is also set for some non-system related errors encountered.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Open (void      **My_Handle,
                 int       Board_Number,
                 int       oflag)

  Description: Open a device.

  Input:   void      **Handle      (Handle pointer to pointer)
           int       Board_Number  (0-9 board number)
           int       oflag         (open flags)

  Output:  none

  Return:  _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR      (successful)
           # CCURDPRC_LIB_INVALID_ARG  (invalid argument)
           # CCURDPRC_LIB_ALREADY_OPEN (device already opened)
           # CCURDPRC_LIB_OPEN_FAILED  (device open failed)
           # CCURDPRC_LIB_ALREADY_MAPPED (memory already mmaped)
           # CCURDPRC_LIB_MMAP_SELECT_FAILED (mmap selection failed)
           # CCURDPRC_LIB_MMAP_FAILED  (mmap failed)
*****/
```

## 2.2.66 ccurDPRC\_Read()

Currently, this call is not supported. It basically calls the *read(2)* system call with the exception that it performs necessary *locking* and returns the *errno* returned from the system call in the pointer to the *error* variable.

For specific information about the data being returned for the various read modes, refer to the *read(2)* system call description the *Driver Direct Access* section.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Read (void      *Handle,
                 void      *buf,
                 int       size,
                 int       *bytes_read,
*****/
```

```

        int          *error)

Description: Perform a read operation.

Input:   void      *Handle          (Handle pointer)
         int       size             (size of buffer in bytes)
Output:  void      *buf             (pointer to buffer)
         int       *bytes_read      (bytes read)
         int       *error           (returned errno)
Return:  _ccurdprc_lib_error_number_t
         # CCURDPRC_LIB_NO_ERROR    (successful)
         # CCURDPRC_LIB_BAD_HANDLE  (no/bad handler supplied)
         # CCURDPRC_LIB_NOT_OPEN    (device not open)
         # CCURDPRC_LIB_IO_ERROR    (read failed)
*****/

```

## 2.2.67 ccurDPRC\_Read\_Serial\_Prom()

This is a basic call to read short word entries from the serial prom. The user specifies a word offset within the serial prom and a word count, and the call returns the data read in a pointer to short words.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Read_Serial_Prom(void          *Handle,
                           ccurdprc_sprom_rw_t *spr)

Description: Read Serial Prom for specified number of words

Input:      void          *Handle          (handle pointer)
            ccurdprc_sprom_rw_t *spr      (pointer to struct)
            u_short word_offset
            u_short num_words
Output:     ccurdprc_sprom_rw_t *spr      (pointer to struct)
            u_short *data_ptr
Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR      (successful)
            # CCURDPRC_LIB_BAD_HANDLE    (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN     (device not open)
            # CCURDPRC_LIB_INVALID_ARG  (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
            # CCURDPRC_LIB_SERIAL_PROM_BUSY (serial prom busy)
            # CCURDPRC_LIB_SERIAL_PROM_FAILURE (serial prom failure)
*****/

```

## 2.2.68 ccurDPRC\_Read\_Serial\_Prom\_Item()

This call is used to read well defined sections in the serial prom. The user supplies the serial prom section that needs to be read and the data is returned in a section specific structure.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Read_Serial_Prom_Item(void          *Handle,
                                _ccurdprc_sprom_access_t item,
                                void          *item_ptr)

Description: Read Serial Prom for specified item

Input:      void          *Handle          (handle pointer)
            _ccurdprc_sprom_access_t item (select item)
            CCURDPRC_SPROM_HEADER
Output:     ccurdprc_sprom_header_t sprom_header (pinter to item struct)
            u_int32_t board_serial_number

```



```

                u_short      sprom_revision
Return:      _ccurdprc_lib_error_number_t
             # CCURDPRC_LIB_NO_ERROR          (successful)
             # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
             # CCURDPRC_LIB_NOT_OPEN         (device not open)
             # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
             # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
             # CCURDPRC_LIB_SERIAL_PROM_BUSY (serial prom busy)
             # CCURDPRC_LIB_SERIAL_PROM_FAILURE (serial prom failure)
*****/

```

## 2.2.69 ccurDPRC\_Remove\_Irq()

The purpose of this call is to remove the interrupt handler that was previously set up. The interrupt handler is managed internally by the driver and the library. The user should not issue this call, otherwise reads will time out.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Remove_Irq (void *Handle)

```

Description: By default, the driver sets up a shared IRQ interrupt handler when the device is opened. Now if for any reason, another device is sharing the same IRQ as this driver, the interrupt handler will also be entered every time the other shared device generates an interrupt. There are times that a user, for performance reasons may wish to run the board without interrupts enabled. In that case, they can issue this ioctl to remove the interrupt handling capability from the driver.

```

Input:  void *Handle          (Handle pointer)
Output: none
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_IOCTL_FAILED     (driver ioctl call failed)
*****/

```

## 2.2.70 ccurDPRC\_Reset\_Board()

This call resets the board to a known initial default state. This call is currently identical to the *ccurdprc\_Initialize\_Board()* call.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Reset_Board (void *Handle)

```

Description: Reset the board.

```

Input:  void *Handle          (Handle pointer)
Output: none
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR          (successful)
        # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN         (device not open)
        # CCURDPRC_LIB_IOCTL_FAILED     (driver ioctl call failed)
        # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/

```

## 2.2.71 ccurDPRC\_Select\_Driver\_Read\_Mode()

This call can be used to select the driver read mode.

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```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Select_Driver_Read_Mode (void                                *Handle,
                                _ccurdprc_driver_rw_mode_t mode)

Description: Select Driver Read Mode

Input:      void                                *Handle      (handle pointer)
            _ccurdprc_driver_rw_mode_t mode      (select read mode)
            # CCURDPRC_PIO_CHANNEL
            # CCURDPRC_DMA_CHANNEL                (CURRENTLY NOT SUPPORTED)

Output:     none

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR              (successful)
            # CCURDPRC_LIB_BAD_HANDLE            (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN              (device not open)
            # CCURDPRC_LIB_INVALID_ARG          (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION       (local region error)
*****/

```

### 2.2.72 ccurDPRC\_Select\_Driver\_Write\_Mode()

This call is currently not supported for driver writes. This call can be used to select the driver write mode.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Select_Driver_Write_Mode (void                                *Handle,
                                _ccurdprc_driver_rw_mode_t mode)

Description: Select Driver Write Mode

Input:      void                                *Handle      (handle pointer)
            _ccurdprc_driver_rw_mode_t mode      (select write mode)
            # CCURDPRC_PIO_CHANNEL
            # CCURDPRC_DMA_CHANNEL

Output:     none

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR              (successful)
            # CCURDPRC_LIB_BAD_HANDLE            (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN              (device not open)
            # CCURDPRC_LIB_INVALID_ARG          (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION       (local region error)
*****/

```

### 2.2.73 ccurDPRC\_Serial\_Prom\_Write\_Override()

The serial prom is non-volatile and its information is preserved during a power cycle. It contains useful information and settings that the customer could lose if they were to inadvertently overwrite. For this reason, all calls that write to the serial proms will fail with a write protect error, unless this write protect override API is invoked prior to writing to the serial proms. Once the Write Override is enabled, it will stay in effect until the user closes the device or re-issues this call to disable writes to the serial prom.

The calls that will fail unless the write protect is disabled are:

- ccurDPRC\_Write\_Serial\_Prom()
- ccurDPRC\_Write\_Serial\_Prom\_Item()

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Serial_Prom_Write_Override (void *Handle,
                                    int action)

```

Description: Set Serial Prom Write Override

```
Input:      void          *Handle          (handle pointer)
           _ccurdprc_bool_t  action        (override action)
           # CCURDPRC_TRUE
           # CCURDPRC_FALSE

Output:     none

Return:     _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR          (successful)
           # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN        (device not open)
           # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
           # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
*****/
```

## 2.2.74 ccurDPRC\_Set\_Board\_CSR()

This call is used to set the board control register.

```
/*
*_ccurdprc_lib_error_number_t
ccurdprc_Set_Board_CSR (void          *Handle,
                       ccurdprc_board_csr_t *bcsr)

Description: Set Board Control and Status information

Input:      void          *Handle (Handle pointer)
           ccurdprc_board_csr_t *bcsr (pointer to board csr)
           _ccurdprc_bcsr_identify_board_t identify_board
           # CCURDPRC_BCSR_IDENTIFY_BOARD_DISABLE
           # CCURDPRC_BCSR_IDENTIFY_BOARD_ENABLE
           # CCURDPRC_BCSR_IDENTIFY_BOARD_ENABLE_DO_NOT_CHANGE

Output:     none

Return:     _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR          (successful)
           # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN        (device not open)
           # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
           # CCURDPRC_LIB_NO_LOCAL_REGION  (local region not present)
*****/
```

## 2.2.75 ccurDPRC\_Set\_CalibrationBus\_Control()

This call sets the calibration bus control.

```
/*
*_ccurdprc_lib_error_number_t
ccurdprc_Set_CalibrationBus_Control (void          *Handle,
                                     _ccurdprc_calibration_bus_control_t bus_control)

Description: Set Calibration Bus Control

Input:      void          *Handle          (handle pointer)
           _ccurdprc_calibration_bus_control_t
           bus_control          (control set)
           # CCURDPRC_CALIBRATIONBUS_CONTROL_OPEN
           # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_2_5_VOLTS
           # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_10_VOLTS
           # CCURDPRC_CALIBRATIONBUS_CONTROL_MINUS_10_VOLTS

           # CCURDPRC_CALIBRATIONBUS_CONTROL_GROUND

           # CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_8_MILLIAMP
*****/
```

```

# CCURDPRC_CALIBRATIONBUS_CONTROL_MINUS_8_MILLIAMP
# CCURDPRC_CALIBRATIONBUS_CONTROL_PLUS_16_MILLIAMP
Output:      none
Return:      _ccurdprc_lib_error_number_t
# CCURDPRC_LIB_NO_ERROR                (successful)
# CCURDPRC_LIB_BAD_HANDLE               (no/bad handler supplied)
# CCURDPRC_LIB_NOT_OPEN                 (device not open)
# CCURDPRC_LIB_INVALID_ARG              (invalid argument)
# CCURDPRC_LIB_NO_LOCAL_REGION           (local region error)
*****/

```

## 2.2.76 ccurDPRC\_Set\_Digital\_Potentiometer()

This call is used for setting the digital potentiometer resistance in ohms for the selected channels. Users need to supply valid resistances for channels in ohms and the call will set them accordingly and return the raw value supplied to the hardware. Valid resistances are 10 Ohms and 45 to 1000,000 Ohms in approximately 5 Ohms increments. If an exact resistance value is not supplied to the call, it will fail, unless the user tags the resistance with CCURDPRC\_POTENTIOMETER\_AUTOCORRECT\_OHM\_TAG flag. In this case, the call will attempt to get the nearest programmable resistance value and return this value back to the user after setting it.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Set_Digital_Potentiometer_Test(void          *Handle,
                                           _ccurdprc_channel_mask_t      ChanMask,
                                           ccurdprc_digital_potentiometer_test_t *DPTest)

Description: Set Digital Potentiometer

Input:  void          *Handle          (Handle pointer)
        _ccurdprc_channel_mask_t      ChanMask      (specify channel mask)
        # CCURDPRC_CHANNEL_MASK_0
        # CCURDPRC_CHANNEL_MASK_1
        # CCURDPRC_CHANNEL_MASK_2
        # CCURDPRC_CHANNEL_MASK_3
        # CCURDPRC_CHANNEL_MASK_4
        # CCURDPRC_CHANNEL_MASK_5
        # CCURDPRC_CHANNEL_MASK_6
        # CCURDPRC_CHANNEL_MASK_7
        # CCURDPRC_CHANNEL_MASK_8
        # CCURDPRC_CHANNEL_MASK_9
        # CCURDPRC_CHANNEL_MASK_10
        # CCURDPRC_CHANNEL_MASK_11
        # CCURDPRC_CHANNEL_MASK_12
        # CCURDPRC_CHANNEL_MASK_13
        # CCURDPRC_CHANNEL_MASK_14
        # CCURDPRC_CHANNEL_MASK_15
        # CCURDPRC_ALL_CHANNELS_MASK
        ccurdprc_digital_potentiometer_t *DPValue (pointer to Digital
                                                    Potentiometer Value)
        uint      Raw[CCURDPRC_MAX_CHANNELS];
        uint      Ohms[CCURDPRC_MAX_CHANNELS];

Output:  None
Return:  _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR                (successful)
        # CCURDPRC_LIB_BAD_HANDLE               (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN                 (device not open)
        # CCURDPRC_LIB_INVALID_ARG              (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION           (local region error)
        # CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE
                                                    (Potentiometer and I/O Control not active)
*****/

```

## 2.2.77 ccurDPRC\_Set\_Digital\_Potentiometer\_Test()

This call sets the digital potentiometer test power down and modes for selected channels.

```

/*****
  ccurDPRC_Set_Digital_Potentiometer_Test()

  Description: Set Digital Potentiometer Test

  Input:   void                *Handle      (Handle pointer)
           _ccurdprc_channel_mask_t  ChanMask  (specify channel mask)
           # CCURDPRC_CHANNEL_MASK_0
           # CCURDPRC_CHANNEL_MASK_1
           # CCURDPRC_CHANNEL_MASK_2
           # CCURDPRC_CHANNEL_MASK_3
           # CCURDPRC_CHANNEL_MASK_4
           # CCURDPRC_CHANNEL_MASK_5
           # CCURDPRC_CHANNEL_MASK_6
           # CCURDPRC_CHANNEL_MASK_7
           # CCURDPRC_CHANNEL_MASK_8
           # CCURDPRC_CHANNEL_MASK_9
           # CCURDPRC_CHANNEL_MASK_10
           # CCURDPRC_CHANNEL_MASK_11
           # CCURDPRC_CHANNEL_MASK_12
           # CCURDPRC_CHANNEL_MASK_13
           # CCURDPRC_CHANNEL_MASK_14
           # CCURDPRC_CHANNEL_MASK_15
           # CCURDPRC_ALL_CHANNELS_MASK
           ccurdprc_digital_potentiometer_test_t *DPTest (pointer to Digital
                                                         Potentiometer Test)
           _ccurdprc_digital_potentiometer_test_t
  DigitalPotTest[CCURDPRC_MAX_CHANNELS];
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT0
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT1
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT2
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_20K_POT3
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_PWRDWN_100K
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_FORCE_FAILURE
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_MODE_20K
           # CCURDPRC_DIGITAL_POTENTIOMETER_TEST_MODE_100K

  Output:  None
  Return:  _ccurdprc_lib_error_number_t
           # CCURDPRC_LIB_NO_ERROR                (successful)
           # CCURDPRC_LIB_BAD_HANDLE              (no/bad handler supplied)
           # CCURDPRC_LIB_NOT_OPEN                (device not open)
           # CCURDPRC_LIB_INVALID_ARG             (invalid argument)
           # CCURDPRC_LIB_NO_LOCAL_REGION         (local region error)
           # CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE
                                                         (Potentiometer and I/O Control not active)
  *****/

```

## 2.2.78 ccurDPRC\_Set\_Interrupt\_Control()

This call sets the interrupt control.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Set_Interrupt_Control (void                *Handle,
                                 ccurdprc_interrupt_t *intr)

  Description: Set Interrupt Control information

  Input:      void                *Handle      (handle pointer)

```

```

    ccurdprc_interrupt_t  *intr          (pointer to interrupt control)
    int global_int
        # CCURDPRC_ICSR_GLOBAL_DISABLE
        # CCURDPRC_ICSR_GLOBAL_ENABLE
        # CCURDPRC_DO_NOT_CHANGE
    int plx_local_int
        # CCURDPRC_ICSR_LOCAL_PLX_DISABLE
        # CCURDPRC_ICSR_LOCAL_PLX_ENABLE
        # CCURDPRC_DO_NOT_CHANGE
Output:    none
Return:    _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/

```

## 2.2.79 ccurDPRC\_Set\_Interrupt\_Status()

This call sets/clears the PLX interrupt.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Set_Interrupt_Status (void          *Handle,
                                   ccurdprc_interrupt_t *intr)

Description: Set Interrupt Status information

Input:    void          *Handle          (handle pointer)
           ccurdprc_interrupt_t *intr    (pointer to interrupt status)
           int plx_local_int
               # CCURDPRC_INTSTAT_LOCAL_PLX_NONE
               # CCURDPRC_INTSTAT_LOCAL_PLX_RESET
               # CCURDPRC_DO_NOT_CHANGE

Output:    none
Return:    _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/

```

## 2.2.80 ccurDPRC\_Set\_Interrupt\_Timeout\_Seconds()

This call sets the read *timeout* maintained by the driver. It allows the user to change the default time out from 30 seconds to a user specified value. It is the time that the read call will wait before it times out. The call could time out if the DMA fails to complete. The device should have been opened in the blocking mode (*O\_NONBLOCK* not set) for reads to wait for the operation to complete.

```

/*****
    _ccurdprc_lib_error_number_t
    ccurDPRC_Set_Interrupt_Timeout_Seconds (void  *Handle,
                                             int    timeout_secs)

Description: Set Interrupt Timeout Seconds

Input:    void          *Handle          (Handle pointer)
           int          timeout_secs     (interrupt tout secs)

Output:    none
Return:    _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)

```

```

# CCURDPRC_LIB_BAD_HANDLE      (no/bad handler supplied)
# CCURDPRC_LIB_NOT_OPEN       (device not open)
# CCURDPRC_LIB_INVALID_ARG    (invalid argument)
*****/

```

## 2.2.81 ccurDPRC\_Set\_IO\_Control()

This call sets the I/O Controls for the selected channels.

```

/*****
_ccurdprc_lib_error_number_t
ccurdPRC_Set_IO_Control(void          *Handle,
                               _ccurdprc_channel_mask_t ChanMask,
                               ccurdprc_io_control_t   *IoControl)

```

Description: Set I/O Control

```

Input:  void          *Handle      (Handle pointer)
        _ccurdprc_channel_mask_t ChanMask  (specify channel mask)
        # CCURDPRC_CHANNEL_MASK_0
        # CCURDPRC_CHANNEL_MASK_1
        # CCURDPRC_CHANNEL_MASK_2
        # CCURDPRC_CHANNEL_MASK_3
        # CCURDPRC_CHANNEL_MASK_4
        # CCURDPRC_CHANNEL_MASK_5
        # CCURDPRC_CHANNEL_MASK_6
        # CCURDPRC_CHANNEL_MASK_7
        # CCURDPRC_CHANNEL_MASK_8
        # CCURDPRC_CHANNEL_MASK_9
        # CCURDPRC_CHANNEL_MASK_10
        # CCURDPRC_CHANNEL_MASK_11
        # CCURDPRC_CHANNEL_MASK_12
        # CCURDPRC_CHANNEL_MASK_13
        # CCURDPRC_CHANNEL_MASK_14
        # CCURDPRC_CHANNEL_MASK_15
        # CCURDPRC_ALL_CHANNELS_MASK
        ccurdprc_io_control_t      *IoControl (pointer to I/O control)
        _ccurdprc_io_control_t
IoSignal[CCURDPRC_MAX_CHANNELS];
        # CCURDPRC_IO_CONTROL_OPEN
        # CCURDPRC_IO_CONTROL_EXTERNAL
        # CCURDPRC_IO_CONTROL_TEST_BUS
        # CCURDPRC_IO_CONTROL_RA_GROUND_FAULT
        # CCURDPRC_IO_CONTROL_RB_GROUND_FAULT
        # CCURDPRC_IO_CONTROL_RA_RB_GROUND_FAULT
        # CCURDPRC_IO_CONTROL_RA_V_PLUS_FAULT
        # CCURDPRC_IO_CONTROL_RB_V_PLUS_FAULT
        # CCURDPRC_IO_CONTROL_RA_RB_V_PLUS_FAULT
        # CCURDPRC_IO_CONTROL_RA_V_PLUS_RB_GROUND_FAULT_SWITCH
        # CCURDPRC_IO_CONTROL_RA_GROUND_RB_V_PLUS_FAULT_SWITCH

Output: None
Return: _ccurdprc_lib_error_number_t
        # CCURDPRC_LIB_NO_ERROR      (successful)
        # CCURDPRC_LIB_BAD_HANDLE    (no/bad handler supplied)
        # CCURDPRC_LIB_NOT_OPEN      (device not open)
        # CCURDPRC_LIB_INVALID_ARG    (invalid argument)
        # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
        # CCURDPRC_LIB_DIGITAL_POT_AND_IO_IS_NOT_ACTIVE
          (Potentiometer and I/O Control not active)
        # CCURDPRC_LIB_ADC_FAILURE    (ADC failure)
        # CCURDPRC_LIB_ELECTRONIC_FUSE_TRIPPED
          (Electronic Fuse tripped)
*****/

```

## 2.2.82 ccurDPRC\_Set\_Value()

This call allows the advanced user to set the writable board registers. The actual data written will depend on the command register information that is requested. Refer to the hardware manual for more information on what can be written to.

Normally, users should not be changing these registers as it will bypass the API integrity and could result in an unpredictable outcome.

```
/******  
_ccurdprc_lib_error_number_t  
ccurdprc_Set_Value (void          *Handle,  
                   CCURDPRC_CONTROL cmd,  
                   void          *value)
```

Description: Set the value of the specified board register.

```
Input:      void          *Handle          (handle pointer)  
           CCURDPRC_CONTROL cmd          (register definition)  
           # CCURDPRC_CONTROL_BOARD_CSR  
           # CCURDPRC_CONTROL_INTERRUPT_CONTROL  
           # CCURDPRC_CONTROL_INTERRUPT_STATUS  
           # CCURDPRC_CONTROL_CALIBRATION_BUS_CONTROL  
           # CCURDPRC_CONTROL_FIRMWARE_SPI_COUNTER_STATUS  
           # CCURDPRC_CONTROL_ADC_ENABLE  
           # CCURDPRC_CONTROL_DIGITAL_POTENTIOMETER_AND_IO_ENABLE  
  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_0  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_1  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_2  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_3  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_4  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_5  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_6  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_7  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_8  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_9  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_10  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_11  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_12  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_13  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_14  
           # CCURDPRC_ADC_POSITIVE_CAL_CHANNEL_15  
  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_0  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_1  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_2  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_3  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_4  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_5  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_6  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_7  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_8  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_9  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_10  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_11  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_12  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_13  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_14  
           # CCURDPRC_ADC_NEGATIVE_CAL_CHANNEL_15
```



```
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_0
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_1
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_2
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_3
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_4
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_5
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_6
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_7
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_8
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_9
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_10
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_11
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_12
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_13
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_14
# CCURDPRC_ADC_OFFSET_CAL_CHANNEL_15

# CCURDPRC_CONTROL_SPROM_STAT_ADDR_WRITE_DATA

# CCURDPRC_IO_CONTROL_CHANNEL_0
# CCURDPRC_IO_CONTROL_CHANNEL_1
# CCURDPRC_IO_CONTROL_CHANNEL_2
# CCURDPRC_IO_CONTROL_CHANNEL_3
# CCURDPRC_IO_CONTROL_CHANNEL_4
# CCURDPRC_IO_CONTROL_CHANNEL_5
# CCURDPRC_IO_CONTROL_CHANNEL_6
# CCURDPRC_IO_CONTROL_CHANNEL_7
# CCURDPRC_IO_CONTROL_CHANNEL_8
# CCURDPRC_IO_CONTROL_CHANNEL_9
# CCURDPRC_IO_CONTROL_CHANNEL_10
# CCURDPRC_IO_CONTROL_CHANNEL_11
# CCURDPRC_IO_CONTROL_CHANNEL_12
# CCURDPRC_IO_CONTROL_CHANNEL_13
# CCURDPRC_IO_CONTROL_CHANNEL_14
# CCURDPRC_IO_CONTROL_CHANNEL_15

# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_0
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_1
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_2
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_3
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_4
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_5
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_6
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_7
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_8
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_9
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_10
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_11
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_12
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_13
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_14
# CCURDPRC_DIGITAL_POT_VALUE_CHANNEL_15

# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_0
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_1
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_2
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_3
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_4
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_5
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_6
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_7
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_8
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_9
```

```
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_10
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_11
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_12
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_13
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_14
# CCURDPRC_DIGITAL_POT_TEST_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_TRIP_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_ELECTRICAL_SHORT_VALUE
# CCURDPRC_ELECTRONIC_FUSE_DELAY_VALUE
# CCURDPRC_ELECTRONIC_FUSE_COUNT_VALUE
# CCURDPRC_ELECTRONIC_FUSE_IO_DELAY_VALUE
# CCURDPRC_ELECTRONIC_FUSE_MAXIMUM_RESISTANCE
# CCURDPRC_ELECTRONIC_FUSE_MAXIMUM_VOLTAGE
# CCURDPRC_ELECTRONIC_FUSE_VOLTAGE_FAULT_DELAY

# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_BASE_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_13
```

```

# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_MULTIPLIER_CHANNEL_15

# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_0
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_1
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_2
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_3
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_4
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_5
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_6
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_7
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_8
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_9
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_10
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_11
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_12
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_13
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_14
# CCURDPRC_ELECTRONIC_FUSE_THRESHOLD_CHANNEL_15

# CCURDPRC_CONTROL_SPI_RAM
void          *value          (pointer to value to be set)
Output:      None
Return:      _ccurdprc_lib_error_number_t
             # CCURDPRC_LIB_NO_ERROR          (successful)
             # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
             # CCURDPRC_LIB_NOT_OPEN         (device not open)
             # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
             # CCURDPRC_LIB_NO_LOCAL_REGION  (local region error)
*****/

```

### 2.2.83 ccurDPRC\_VoltsToData()

This call converts user supplied volts to raw data.

```

/*****
uint
ccurdPRC_VoltsToData (double volts)

Description: Convert Volts to data

Input:      double   volts          (volts to convert)
Output:     none
Return:     uint     data           (returned data)
*****/

```

### 2.2.84 ccurDPRC\_VoltsToDataChanCal()

This call converts user supplied volts to raw data for calibration registers.

```

/*****
uint
ccurdPRC_VoltsToDataChanCal (double volts)

Description: Convert Volts to Data (for Channel Calibration)

Input:      double   volts          (volts to convert)
Output:     none
Return:     uint     data           (returned data)
*****/

```

## 2.2.85 ccurDPRC\_Wait\_For\_Interrupt()

This call is made available to advanced users to bypass the API and perform their own interrupt handling. If a time out value greater than zero is specified, the call will time out after the specified seconds, otherwise it will not time out.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Wait_For_Interrupt (void          *Handle,
                              ccurdprc_driver_int_t *drv_int)

Description: Wait For Interrupt

Input:      void          *Handle          (handle pointer)
Output:     ccurdprc_driver_int_t *drv_int (pointer to drv_int struct)
            unsigned long long count
            u_int status
            u_int mask
            # CCURDPRC_INTSTAT_LOCAL_PLX_MASK
            int timeout_seconds

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
*****/
```

## 2.2.86 ccurDPRC\_Write()

This call is currently not supported.

```

/*****
  _ccurdprc_lib_error_number_t
  ccurDPRC_Write (void      *Handle,
                 void      *buf,
                 int        size,
                 int        *bytes_written,
                 int        *error)

Description: Perform a write operation.

Input:      void      *Handle          (Handle pointer)
            int        size            (number of bytes to write)
Output:     void      *buf            (pointer to buffer)
            int        *bytes_written (bytes written)
            int        *error         (returned errno)

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_IO_ERROR        (write failed)
            # CCURDPRC_LIB_NOT_IMPLEMENTED (call not implemented)
*****/
```

## 2.2.87 ccurDPRC\_Write\_Serial\_Prom()

This is a basic call to write short word entries to the serial prom. The user specifies a word offset within the serial prom and a word count, and the call writes the data pointed to by the *spw* pointer, in short words.

Prior to using this call, the user will need to issue the *ccurdprc\_Serial\_Prom\_Write\_Override()* to allowing writing to the serial prom.

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```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Write_Serial_Prom(void          *Handle,
                             ccurdprc_sprom_rw_t *spw)

Description: Write data to Serial Prom for specified number of words

Input:      void          *Handle          (handle pointer)
            ccurdprc_sprom_rw_t *spw      (pointer to struct)
            # u_short word_offset
            # u_short num_words
            # u_short *data_ptr

Output:     none

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
            # CCURDPRC_LIB_SERIAL_PROM_BUSY (serial prom busy)
            # CCURDPRC_LIB_SERIAL_PROM_FAILURE (serial prom failure)
*****/

```

## 2.2.88 ccurDPRC\_Write\_Serial\_Prom\_Item()

This call is used to write well defined sections in the serial prom. The user supplies the serial prom section that needs to be written and the data points to the section specific structure. This call should normally not be used by the user.

Prior to using this call, the user will need to issue the *ccurdprc\_Serial\_Prom\_Write\_Override()* to allowing writing to the serial prom.

```

/*****
_ccurdprc_lib_error_number_t
ccurdprc_Write_Serial_Prom_Item(void          *Handle,
                                  _ccurdprc_sprom_access_t item,
                                  void          *item_ptr)

Description: Write Serial Prom with specified item

Input:      void          *Handle          (handle pointer)
            _ccurdprc_sprom_access_t item (select item)
            # CCURDPRC_SPROM_HEADER

Output:     ccurdprc_sprom_header_t sprom_header (pinter to item struct)
            u_int32_t board_serial_number
            u_short   sprom_revision

Return:     _ccurdprc_lib_error_number_t
            # CCURDPRC_LIB_NO_ERROR          (successful)
            # CCURDPRC_LIB_BAD_HANDLE       (no/bad handler supplied)
            # CCURDPRC_LIB_NOT_OPEN        (device not open)
            # CCURDPRC_LIB_INVALID_ARG     (invalid argument)
            # CCURDPRC_LIB_NO_LOCAL_REGION (local region error)
            # CCURDPRC_LIB_SERIAL_PROM_BUSY (serial prom busy)
            # CCURDPRC_LIB_SERIAL_PROM_FAILURE (serial prom failure)
*****/

```

### 3. Test Programs

This driver and API are accompanied with an extensive set of test examples. Examples under the *Direct Driver Access* do not use the API, while those under *Application Program Interface Access* use the API.

#### 3.1 Direct Driver Access Example Tests

These set of tests are located in the *.../test* directory and do not use the API. They communicate directly with the driver. Users should be extremely familiar with both the driver and the hardware registers if they wish to communicate directly with the hardware.

##### 3.1.1 ccurdprc\_dump

This test is for debugging purpose. It dumps all the hardware registers.

Usage: ccurdprc\_dump [-b board]  
-b board: board number -- default board is 0

###### Example display:

```
./ccurdprc_dump

Device Name      : /dev/ccurdprc0
Board Serial No: 680593 (0x000a6291)

LOCAL Register 0x7ffff7ff6000 Offset=0x0
CONFIG Register 0x7ffff7ff5000 Offset=0x0

===== LOCAL BOARD REGISTERS =====
LBR: @0x0000 --> 0x93100102
LBR: @0x0004 --> 0x00000000
LBR: @0x0008 --> 0x00000000
LBR: @0x000c --> 0x00000000
LBR: @0x0010 --> 0x00000000
LBR: @0x0014 --> 0x00000001
LBR: @0x0018 --> 0x00000001
LBR: @0x001c --> 0x00000001
LBR: @0x0020 --> 0x00000001
LBR: @0x0024 --> 0x00000001
LBR: @0x0028 --> 0x00000001
LBR: @0x002c --> 0x00000001
LBR: @0x0030 --> 0x00000001
.
.
.
LBR: @0x07c0 --> 0x00000000
LBR: @0x07c4 --> 0x00000000
LBR: @0x07c8 --> 0x00000000
LBR: @0x07cc --> 0x00000000
LBR: @0x07d0 --> 0x00000000
LBR: @0x07d4 --> 0x00000000
LBR: @0x07d8 --> 0x00000000
LBR: @0x07dc --> 0x00000000
LBR: @0x07e0 --> 0x00000000
LBR: @0x07e4 --> 0x00000000
LBR: @0x07e8 --> 0x00000000
LBR: @0x07ec --> 0x00000000
LBR: @0x07f0 --> 0x00000000
```

LBR: @0x07f4 --> 0x00000000  
LBR: @0x07f8 --> 0x00000000  
LBR: @0x07fc --> 0x00000000

===== LOCAL CONFIG REGISTERS =====

LCR: @0x0000 --> 0xffffffff800  
LCR: @0x0004 --> 0x00000001  
LCR: @0x0008 --> 0x00200000  
LCR: @0x000c --> 0x00300400  
LCR: @0x0010 --> 0x00000000  
LCR: @0x0014 --> 0x00000000  
LCR: @0x0018 --> 0x42430343  
LCR: @0x001c --> 0x00000000  
LCR: @0x0020 --> 0x00000000  
LCR: @0x0024 --> 0x00000000  
LCR: @0x0028 --> 0x00000000  
LCR: @0x002c --> 0x00000000  
LCR: @0x0030 --> 0x00000000  
.  
.  
.  
LCR: @0x00c0 --> 0x00000002  
LCR: @0x00c4 --> 0x00000000  
LCR: @0x00c8 --> 0x00000000  
LCR: @0x00cc --> 0x00000000  
LCR: @0x00d0 --> 0x00000000  
LCR: @0x00d4 --> 0x00000000  
LCR: @0x00d8 --> 0x00000000  
LCR: @0x00dc --> 0x00000000  
LCR: @0x00e0 --> 0x00000000  
LCR: @0x00e4 --> 0x00000000  
LCR: @0x00e8 --> 0x00000050  
LCR: @0x00ec --> 0x00000000  
LCR: @0x00f0 --> 0x00000000  
LCR: @0x00f4 --> 0x00000000  
LCR: @0x00f8 --> 0x00000043  
LCR: @0x00fc --> 0x00000000  
LCR: @0x0100 --> 0x00000000  
LCR: @0x0104 --> 0x00000000

===== PCI CONFIG REG ADDR MAPPING =====

PCR: @0x0000 --> 0x93101542  
PCR: @0x0004 --> 0x02b00017  
PCR: @0x0008 --> 0x08800001  
PCR: @0x000c --> 0x00006008  
PCR: @0x0010 --> 0xc4c01000  
PCR: @0x0014 --> 0x00000000  
PCR: @0x0018 --> 0xc4c00000  
PCR: @0x001c --> 0x00000000  
PCR: @0x0020 --> 0x00000000  
PCR: @0x0024 --> 0x00000000  
PCR: @0x0028 --> 0x00000000  
PCR: @0x002c --> 0x905610b5  
PCR: @0x0030 --> 0x00000000  
PCR: @0x0034 --> 0x00000040  
PCR: @0x0038 --> 0x00000000  
PCR: @0x003c --> 0x0000010b

```
PCR: @0x0040 --> 0x00024801
PCR: @0x0044 --> 0x00000000
PCR: @0x0048 --> 0x00004c00
PCR: @0x004c --> 0x00000003
PCR: @0x0050 --> 0x00000000
```

=====  
===== PCI BRIDGE REGISTERS =====

```
PBR: @0x0000 --> 0x811110b5
PBR: @0x0004 --> 0x00100417
PBR: @0x0008 --> 0x06040021
PBR: @0x000c --> 0x00010010
PBR: @0x0010 --> 0xc490000c
PBR: @0x0014 --> 0x00000000
PBR: @0x0018 --> 0x00080807
PBR: @0x001c --> 0x220000f0
PBR: @0x0020 --> 0xc4c0c4c0
PBR: @0x0024 --> 0x0000fff0
PBR: @0x0028 --> 0x00000000
PBR: @0x002c --> 0x00000000
PBR: @0x0030 --> 0x00000000
```

```
.
.
```

```
PBR: @0x00d0 --> 0x00000000
PBR: @0x00d4 --> 0x00000000
PBR: @0x00d8 --> 0x00000000
PBR: @0x00dc --> 0x00000000
PBR: @0x00e0 --> 0x00000000
PBR: @0x00e4 --> 0x00000000
PBR: @0x00e8 --> 0x00000000
PBR: @0x00ec --> 0x00000000
PBR: @0x00f0 --> 0x00000000
PBR: @0x00f4 --> 0x00000000
PBR: @0x00f8 --> 0x00000000
PBR: @0x00fc --> 0x00000000
PBR: @0x0100 --> 0x00010004
PBR: @0x0104 --> 0x00000000
PBR: @0x0108 --> 0x00000000
PBR: @0x010c --> 0x00000000
PBR: @0x0110 --> 0x00000000
PBR: @0x0114 --> 0x00000000
PBR: @0x0118 --> 0x00000000
```

=====  
===== MAIN CONTROL REGISTERS =====

```
MCR: @0x0000 --> 0x00000033
MCR: @0x0004 --> 0x8000ff00
MCR: @0x0008 --> 0x00000000
MCR: @0x000c --> 0x1b008090
MCR: @0x0010 --> 0x80000002
MCR: @0x0014 --> 0x00000000
MCR: @0x0018 --> 0x00000000
MCR: @0x001c --> 0x00000000
MCR: @0x0020 --> 0x0000141f
MCR: @0x0024 --> 0x00000000
MCR: @0x0028 --> 0x00000000
MCR: @0x002c --> 0x00000000
MCR: @0x0030 --> 0xfeedface
```



```

MCR: @0x0034 --> 0x00000000
MCR: @0x0038 --> 0x00000000
MCR: @0x003c --> 0x00000000
MCR: @0x0040 --> 0x00000201
MCR: @0x0044 --> 0x00000000
MCR: @0x0048 --> 0x00810a20
MCR: @0x004c --> 0x000000d4
MCR: @0x0050 --> 0x00010700
MCR: @0x0054 --> 0x00000000
MCR: @0x0058 --> 0x080a2c2a
MCR: @0x005c --> 0x0000029a
MCR: @0x0060 --> 0x00000019
MCR: @0x0064 --> 0x00000000

```

### 3.1.2 ccurdprc\_rdtype

This is a simple program that returns the local register value for a given offset.

```

Usage: ./ccurdprc_rdtype [-b board] [-o offset] [-s size]
-b board : board number -- default board is 0
-o offset: hex offset to read from -- default offset is 0x0
-s size  : number of bytes to read -- default size is 0x4

```

#### Example display:

```
./ccurdprc_rdtype -s64
```

```

Device Name      : /dev/ccurdprc0
Board Serial No: 680593 (0x000a6291)

#### LOCAL REGS #### (length=100)
+LCL+      0  93100102  00000000  00000000  00000000  *...3.....*
+LCL+     0x10  00000000  00000001  00000001  00000001  *.....*
+LCL+     0x20  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x30  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x40  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x50  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x60  00000000

```

### 3.1.3 ccurdprc\_reg

This call displays all the boards local and configuration registers.

```

Usage: ./ccurdprc_reg [-b board]
-b board: Board number -- default board is 0

```

#### Example display:

```
./ccurdprc_reg
```

```

Device Name      : /dev/ccurdprc0
Board Serial No: 680593 (0x000a6291)

LOCAL Register 0x7ffff7ff6000 Offset=0x0

#### LOCAL REGS #### (length=2048)
+LCL+      0  93100102  00000000  00000000  00000000  *...3.....*
+LCL+     0x10  00000000  00000001  00000001  00000001  *.....*
+LCL+     0x20  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x30  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x40  00000001  00000001  00000001  00000001  *.....*
+LCL+     0x50  00000001  00000001  00000001  00000001  *.....*

```

```

+LCL+ 0x60 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0x70 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0x80 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0x90 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0xa0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0xb0 00000000 00000001 00000001 00000001 *.....*
+LCL+ 0xc0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0xd0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0xe0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0xf0 00000000 00000000 00000001 00000001 *.....*
+LCL+ 0x100 00000000 00000001 00000001 00000001 *.....*
+LCL+ 0x110 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x120 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x130 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x140 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x150 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x160 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x170 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x180 80000000 80000000 80000000 80000000 *.....*
+LCL+ 0x190 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1a0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1b0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1c0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x1d0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0x1e0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0x1f0 00000001 00000001 00000001 00000001 *.....*
+LCL+ 0x200 00000001 00000001 00000001 00000001 *.....*
.
.
+LCL+ 0x700 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x710 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x720 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x730 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x740 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x750 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x760 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x770 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x780 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x790 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x7a0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x7b0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x7c0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x7d0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x7e0 00000000 00000000 00000000 00000000 *.....*
+LCL+ 0x7f0 00000000 00000000 00000000 00000000 *.....*

```

CONFIG Register 0x7ffff7ff5000 Offset=0x0

```

#### CONFIG REGS #### (length=264)
+CFG+ 0 fffff800 00000001 00200000 00300400 *.....0..*
+CFG+ 0x10 00000000 00000000 42430343 00000000 *.....BC.C..*
+CFG+ 0x20 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x30 00000000 00000008 00000000 00000000 *.....*
+CFG+ 0x40 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x50 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0x60 00000000 00000000 0f000080 100f767c *.....v|*
+CFG+ 0x70 905610b5 000000ba 00000000 00000000 *.V.....*
+CFG+ 0x80 00000003 00000000 00000000 00000000 *.....*
+CFG+ 0x90 00000000 00000003 00000000 00000000 *.....*
+CFG+ 0xa0 00000000 00000000 00001010 00200000 *.....*
+CFG+ 0xb0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xc0 00000002 00000000 00000000 00000000 *.....*

```

```

+CFG+ 0xd0 00000000 00000000 00000000 00000000 *.....*
+CFG+ 0xe0 00000000 00000000 00000050 00000000 *.....P....*
+CFG+ 0xf0 00000000 00000000 00000043 00000000 *.....C....*
+CFG+ 0x100 00000000 00000000 *.....*

```

=====  
===== CONFIG REGISTERS =====

```

las0rr =0xfffff800 @0x00000000
las0ba =0x00000001 @0x00000004
marbr =0x00200000 @0x00000008
bigend =0x00300400 @0x0000000c
eromrr =0x00000000 @0x00000010
eromba =0x00000000 @0x00000014
lbrd0 =0x42430343 @0x00000018
dmrr =0x00000000 @0x0000001c
dmlbam =0x00000000 @0x00000020
dmlbai =0x00000000 @0x00000024
dmpbam =0x00000000 @0x00000028
dmcfga =0x00000000 @0x0000002c
oplfis =0x00000000 @0x00000030
oplfim =0x00000008 @0x00000034
mbox0 =0x00000000 @0x00000040
mbox1 =0x00000000 @0x00000044
mbox2 =0x00000000 @0x00000048
mbox3 =0x00000000 @0x0000004c
mbox4 =0x00000000 @0x00000050
mbox5 =0x00000000 @0x00000054
mbox6 =0x00000000 @0x00000058
mbox7 =0x00000000 @0x0000005c
p21dbell =0x00000000 @0x00000060
l2pdbell =0x00000000 @0x00000064
intcsr =0x0f000080 @0x00000068
cntrl =0x100f767c @0x0000006c
pcihidr =0x905610b5 @0x00000070
pcihrev =0x000000ba @0x00000074
dmamode0 =0x00000003 @0x00000080
dmapadr0 =0x00000000 @0x00000084
dmaladr0 =0x00000000 @0x00000088
dmasiz0 =0x00000000 @0x0000008c
dmapr0 =0x00000000 @0x00000090
dmamode1 =0x00000003 @0x00000094
dmapadr1 =0x00000000 @0x00000098
dmaladr1 =0x00000000 @0x0000009c
dmasiz1 =0x00000000 @0x000000a0
dmapr1 =0x00000000 @0x000000a4
dmacr0 =0x00000010 @0x000000a8
dmacr1 =0x00000010 @0x000000a9
dmaaarb =0x00200000 @0x000000ac
dmathr =0x00000000 @0x000000b0
dmac0 =0x00000000 @0x000000b4
dmac1 =0x00000000 @0x000000b8
las1rr =0x00000000 @0x000000f0
las1ba =0x00000000 @0x000000f4
lbrd1 =0x00000043 @0x000000f8
dmdac =0x00000000 @0x000000fc
pciarb =0x00000000 @0x00000100
pabtadr =0x00000000 @0x00000104

```

=====  
===== LOCAL REGISTERS =====

```

board_info =0x93100102 @0x00000000
board_csr =0x00000000 @0x00000004
interrupt_control =0x00000000 @0x00000008
interrupt_status =0x00000000 @0x0000000c
calib_bus_control =0x00000000 @0x000000b0
spi_counter_status =0x00000000 @0x000000f0

```

ADC_Enable	=0x00000000	@0x00000100
ADC_PositiveCalibration[CCURDPRC_CHANNEL_0]	=0x80000000	@0x00000110
ADC_PositiveCalibration[CCURDPRC_CHANNEL_1]	=0x80000000	@0x00000114
ADC_PositiveCalibration[CCURDPRC_CHANNEL_2]	=0x80000000	@0x00000118
ADC_PositiveCalibration[CCURDPRC_CHANNEL_3]	=0x80000000	@0x0000011c
ADC_PositiveCalibration[CCURDPRC_CHANNEL_4]	=0x80000000	@0x00000120
ADC_PositiveCalibration[CCURDPRC_CHANNEL_5]	=0x80000000	@0x00000124
ADC_PositiveCalibration[CCURDPRC_CHANNEL_6]	=0x80000000	@0x00000128
ADC_PositiveCalibration[CCURDPRC_CHANNEL_7]	=0x80000000	@0x0000012c
ADC_PositiveCalibration[CCURDPRC_CHANNEL_8]	=0x80000000	@0x00000130
ADC_PositiveCalibration[CCURDPRC_CHANNEL_9]	=0x80000000	@0x00000134
ADC_PositiveCalibration[CCURDPRC_CHANNEL_10]	=0x80000000	@0x00000138
ADC_PositiveCalibration[CCURDPRC_CHANNEL_11]	=0x80000000	@0x0000013c
ADC_PositiveCalibration[CCURDPRC_CHANNEL_12]	=0x80000000	@0x00000140
ADC_PositiveCalibration[CCURDPRC_CHANNEL_13]	=0x80000000	@0x00000144
ADC_PositiveCalibration[CCURDPRC_CHANNEL_14]	=0x80000000	@0x00000148
ADC_PositiveCalibration[CCURDPRC_CHANNEL_15]	=0x80000000	@0x0000014c
ADC_NegativeCalibration[CCURDPRC_CHANNEL_0]	=0x80000000	@0x00000150
ADC_NegativeCalibration[CCURDPRC_CHANNEL_1]	=0x80000000	@0x00000154
ADC_NegativeCalibration[CCURDPRC_CHANNEL_2]	=0x80000000	@0x00000158
ADC_NegativeCalibration[CCURDPRC_CHANNEL_3]	=0x80000000	@0x0000015c
ADC_NegativeCalibration[CCURDPRC_CHANNEL_4]	=0x80000000	@0x00000160
ADC_NegativeCalibration[CCURDPRC_CHANNEL_5]	=0x80000000	@0x00000164
ADC_NegativeCalibration[CCURDPRC_CHANNEL_6]	=0x80000000	@0x00000168
ADC_NegativeCalibration[CCURDPRC_CHANNEL_7]	=0x80000000	@0x0000016c
ADC_NegativeCalibration[CCURDPRC_CHANNEL_8]	=0x80000000	@0x00000170
ADC_NegativeCalibration[CCURDPRC_CHANNEL_9]	=0x80000000	@0x00000174
ADC_NegativeCalibration[CCURDPRC_CHANNEL_10]	=0x80000000	@0x00000178
ADC_NegativeCalibration[CCURDPRC_CHANNEL_11]	=0x80000000	@0x0000017c
ADC_NegativeCalibration[CCURDPRC_CHANNEL_12]	=0x80000000	@0x00000180
ADC_NegativeCalibration[CCURDPRC_CHANNEL_13]	=0x80000000	@0x00000184
ADC_NegativeCalibration[CCURDPRC_CHANNEL_14]	=0x80000000	@0x00000188
ADC_NegativeCalibration[CCURDPRC_CHANNEL_15]	=0x80000000	@0x0000018c
ADC_OffsetCalibration[CCURDPRC_CHANNEL_0]	=0x00000000	@0x00000190
ADC_OffsetCalibration[CCURDPRC_CHANNEL_1]	=0x00000000	@0x00000194
ADC_OffsetCalibration[CCURDPRC_CHANNEL_2]	=0x00000000	@0x00000198
ADC_OffsetCalibration[CCURDPRC_CHANNEL_3]	=0x00000000	@0x0000019c
ADC_OffsetCalibration[CCURDPRC_CHANNEL_4]	=0x00000000	@0x000001a0
ADC_OffsetCalibration[CCURDPRC_CHANNEL_5]	=0x00000000	@0x000001a4
ADC_OffsetCalibration[CCURDPRC_CHANNEL_6]	=0x00000000	@0x000001a8
ADC_OffsetCalibration[CCURDPRC_CHANNEL_7]	=0x00000000	@0x000001ac
ADC_OffsetCalibration[CCURDPRC_CHANNEL_8]	=0x00000000	@0x000001b0
ADC_OffsetCalibration[CCURDPRC_CHANNEL_9]	=0x00000000	@0x000001b4
ADC_OffsetCalibration[CCURDPRC_CHANNEL_10]	=0x00000000	@0x000001b8
ADC_OffsetCalibration[CCURDPRC_CHANNEL_11]	=0x00000000	@0x000001bc
ADC_OffsetCalibration[CCURDPRC_CHANNEL_12]	=0x00000000	@0x000001c0
ADC_OffsetCalibration[CCURDPRC_CHANNEL_13]	=0x00000000	@0x000001c4
ADC_OffsetCalibration[CCURDPRC_CHANNEL_14]	=0x00000000	@0x000001c8
ADC_OffsetCalibration[CCURDPRC_CHANNEL_15]	=0x00000000	@0x000001cc
ADC_Data[CCURDPRC_CHANNEL_0]	=0x00000000	@0x00000280
ADC_Data[CCURDPRC_CHANNEL_1]	=0x00000000	@0x00000284
ADC_Data[CCURDPRC_CHANNEL_2]	=0x00000000	@0x00000288
ADC_Data[CCURDPRC_CHANNEL_3]	=0x00000000	@0x0000028c
ADC_Data[CCURDPRC_CHANNEL_4]	=0x00000000	@0x00000290
ADC_Data[CCURDPRC_CHANNEL_5]	=0x00000000	@0x00000294
ADC_Data[CCURDPRC_CHANNEL_6]	=0x00000000	@0x00000298
ADC_Data[CCURDPRC_CHANNEL_7]	=0x00000000	@0x0000029c
ADC_Data[CCURDPRC_CHANNEL_8]	=0x00000000	@0x000002a0
ADC_Data[CCURDPRC_CHANNEL_9]	=0x00000000	@0x000002a4
ADC_Data[CCURDPRC_CHANNEL_10]	=0x00000000	@0x000002a8
ADC_Data[CCURDPRC_CHANNEL_11]	=0x00000000	@0x000002ac
ADC_Data[CCURDPRC_CHANNEL_12]	=0x00000000	@0x000002b0
ADC_Data[CCURDPRC_CHANNEL_13]	=0x00000000	@0x000002b4

ADC_Data[CCURDPRC_CHANNEL_14]	=0x00000000	@0x000002b8
ADC_Data[CCURDPRC_CHANNEL_15]	=0x00000000	@0x000002bc
Digital_Potentiometer_and_IO_Enable	=0x00000000	@0x00000300
IO_Signal_Select[CCURDPRC_CHANNEL_0]	=0x00000000	@0x00000310
IO_Signal_Select[CCURDPRC_CHANNEL_1]	=0x00000000	@0x00000314
IO_Signal_Select[CCURDPRC_CHANNEL_2]	=0x00000000	@0x00000318
IO_Signal_Select[CCURDPRC_CHANNEL_3]	=0x00000000	@0x0000031c
IO_Signal_Select[CCURDPRC_CHANNEL_4]	=0x00000000	@0x00000320
IO_Signal_Select[CCURDPRC_CHANNEL_5]	=0x00000000	@0x00000324
IO_Signal_Select[CCURDPRC_CHANNEL_6]	=0x00000000	@0x00000328
IO_Signal_Select[CCURDPRC_CHANNEL_7]	=0x00000000	@0x0000032c
IO_Signal_Select[CCURDPRC_CHANNEL_8]	=0x00000000	@0x00000330
IO_Signal_Select[CCURDPRC_CHANNEL_9]	=0x00000000	@0x00000334
IO_Signal_Select[CCURDPRC_CHANNEL_10]	=0x00000000	@0x00000338
IO_Signal_Select[CCURDPRC_CHANNEL_11]	=0x00000000	@0x0000033c
IO_Signal_Select[CCURDPRC_CHANNEL_12]	=0x00000000	@0x00000340
IO_Signal_Select[CCURDPRC_CHANNEL_13]	=0x00000000	@0x00000344
IO_Signal_Select[CCURDPRC_CHANNEL_14]	=0x00000000	@0x00000348
IO_Signal_Select[CCURDPRC_CHANNEL_15]	=0x00000000	@0x0000034c
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_0]	=0x00032000	@0x00000400
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_1]	=0x00032000	@0x00000404
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_2]	=0x00032000	@0x00000408
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_3]	=0x00032000	@0x0000040c
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_4]	=0x00032000	@0x00000410
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_5]	=0x00032000	@0x00000414
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_6]	=0x00032000	@0x00000418
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_7]	=0x00032000	@0x0000041c
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_8]	=0x00032000	@0x00000420
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_9]	=0x00032000	@0x00000424
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_10]	=0x00032000	@0x00000428
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_11]	=0x00032000	@0x0000042c
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_12]	=0x00032000	@0x00000430
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_13]	=0x00032000	@0x00000434
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_14]	=0x00032000	@0x00000438
Digital_Potentiometer_Value[CCURDPRC_CHANNEL_15]	=0x00032000	@0x0000043c
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_0]	=0x00000100	@0x00000480
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_1]	=0x00000100	@0x00000484
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_2]	=0x00000100	@0x00000488
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_3]	=0x00000100	@0x0000048c
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_4]	=0x00000100	@0x00000490
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_5]	=0x00000100	@0x00000494
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_6]	=0x00000100	@0x00000498
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_7]	=0x00000100	@0x0000049c
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_8]	=0x00000100	@0x000004a0
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_9]	=0x00000100	@0x000004a4
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_10]	=0x00000100	@0x000004a8
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_11]	=0x00000100	@0x000004ac
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_12]	=0x00000100	@0x000004b0
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_13]	=0x00000100	@0x000004b4
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_14]	=0x00000100	@0x000004b8
Digital_Potentiometer_Test[CCURDPRC_CHANNEL_15]	=0x00000100	@0x000004bc
sprom_stat_addr_write_data	=0x00000000	@0x00000500
sprom_read_data	=0x00000000	@0x00000504
Electronic_Fuse_Status	=0x00030000	@0x00000520
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_0]	=0x00000000	@0x00000530
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_1]	=0x00000000	@0x00000534
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_2]	=0x00000000	@0x00000538
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_3]	=0x00000000	@0x0000053c
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_4]	=0x00000000	@0x00000540
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_5]	=0x00000000	@0x00000544
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_6]	=0x00000000	@0x00000548
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_7]	=0x00000000	@0x0000054c
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_8]	=0x00000000	@0x00000550

Electronic_Fuse_Trip[CCURDPRC_CHANNEL_9]	=0x00000000	@0x00000554
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_10]	=0x00000000	@0x00000558
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_11]	=0x00000000	@0x0000055c
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_12]	=0x00000000	@0x00000560
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_13]	=0x00000000	@0x00000564
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_14]	=0x00000000	@0x00000568
Electronic_Fuse_Trip[CCURDPRC_CHANNEL_15]	=0x00000000	@0x0000056c
Electronic_Fuse_Electrical_Short_Value	=0x000000b4	@0x000005b0
Electronic_Fuse_Delay_Value	=0x00000002	@0x000005b4
Electronic_Fuse_Count_Value	=0x00000001	@0x000005b8
Electronic_Fuse_IO_Delay_Value	=0x00000800	@0x000005bc
Electronic_Fuse_Maximum_Resistance	=0x000000fd	@0x000005c0
Electronic_Fuse_Maximum_Voltage	=0x000005ae0	@0x000005c4
Electronic_Fuse_Voltage_Fault_Delay	=0x00000002	@0x000005c8
Electronic_Fuse_Base[CCURDPRC_CHANNEL_0]	=0x00000241	@0x00000600
Electronic_Fuse_Base[CCURDPRC_CHANNEL_1]	=0x00000241	@0x00000604
Electronic_Fuse_Base[CCURDPRC_CHANNEL_2]	=0x00000241	@0x00000608
Electronic_Fuse_Base[CCURDPRC_CHANNEL_3]	=0x00000241	@0x0000060c
Electronic_Fuse_Base[CCURDPRC_CHANNEL_4]	=0x00000241	@0x00000610
Electronic_Fuse_Base[CCURDPRC_CHANNEL_5]	=0x00000241	@0x00000614
Electronic_Fuse_Base[CCURDPRC_CHANNEL_6]	=0x00000241	@0x00000618
Electronic_Fuse_Base[CCURDPRC_CHANNEL_7]	=0x00000241	@0x0000061c
Electronic_Fuse_Base[CCURDPRC_CHANNEL_8]	=0x00000241	@0x00000620
Electronic_Fuse_Base[CCURDPRC_CHANNEL_9]	=0x00000241	@0x00000624
Electronic_Fuse_Base[CCURDPRC_CHANNEL_10]	=0x00000241	@0x00000628
Electronic_Fuse_Base[CCURDPRC_CHANNEL_11]	=0x00000241	@0x0000062c
Electronic_Fuse_Base[CCURDPRC_CHANNEL_12]	=0x00000241	@0x00000630
Electronic_Fuse_Base[CCURDPRC_CHANNEL_13]	=0x00000241	@0x00000634
Electronic_Fuse_Base[CCURDPRC_CHANNEL_14]	=0x00000241	@0x00000638
Electronic_Fuse_Base[CCURDPRC_CHANNEL_15]	=0x00000241	@0x0000063c
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_0]	=0x0000005a	@0x00000640
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_1]	=0x0000005a	@0x00000644
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_2]	=0x0000005a	@0x00000648
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_3]	=0x0000005a	@0x0000064c
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_4]	=0x0000005a	@0x00000650
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_5]	=0x0000005a	@0x00000654
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_6]	=0x0000005a	@0x00000658
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_7]	=0x0000005a	@0x0000065c
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_8]	=0x0000005a	@0x00000660
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_9]	=0x0000005a	@0x00000664
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_10]	=0x0000005a	@0x00000668
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_11]	=0x0000005a	@0x0000066c
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_12]	=0x0000005a	@0x00000670
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_13]	=0x0000005a	@0x00000674
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_14]	=0x0000005a	@0x00000678
Electronic_Fuse_Multiplier[CCURDPRC_CHANNEL_15]	=0x0000005a	@0x0000067c
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_0]	=0x000005ae0	@0x00000680
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_1]	=0x000005ae0	@0x00000684
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_2]	=0x000005ae0	@0x00000688
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_3]	=0x000005ae0	@0x0000068c
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_4]	=0x000005ae0	@0x00000690
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_5]	=0x000005ae0	@0x00000694
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_6]	=0x000005ae0	@0x00000698
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_7]	=0x000005ae0	@0x0000069c
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_8]	=0x000005ae0	@0x000006a0
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_9]	=0x000005ae0	@0x000006a4
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_10]	=0x000005ae0	@0x000006a8
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_11]	=0x000005ae0	@0x000006ac
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_12]	=0x000005ae0	@0x000006b0
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_13]	=0x000005ae0	@0x000006b4
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_14]	=0x000005ae0	@0x000006b8
Electronic_Fuse_Threshold[CCURDPRC_CHANNEL_15]	=0x000005ae0	@0x000006bc

```

spi_ram[0..63]
@0x0700 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x0720 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x0740 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x0760 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x0780 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x07a0 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x07c0 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000
@0x07e0 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000

```

### 3.1.4 ccurdprc\_regedit

This is an interactive test to display and write to local, configuration and physical memory.

Usage: ./ccurdprc\_regedit [-b board]  
 -b board: Board number -- default board is 0

#### Example display:

```

./ccurdprc_regedit

Device Name      : /dev/ccurdprc0
Board Serial No  : 680593 (0x000a6291)
Initialize_Board: Firmware Rev. 0x01 successful

Virtual Address: 0x7ffff7ff6000
  1 = Create Physical Memory          2 = Destroy Physical memory
  3 = Display Driver Information      4 = Display Firmware RAM
  5 = Display Physical Memory Info   6 = Display Registers (CONFIG)
  7 = Display Registers (LOCAL)     8 = Dump Physical Memory
  9 = Reset Board                    10 = Write Register (LOCAL)
 11 = Write Register (CONFIG)       12 = Write Physical Memory

Main Selection ('h'=display menu, 'q'=quit)->

```

### 3.1.5 ccurdprc\_tst

This is an interactive test to exercise some of the driver features.

Usage: ./ccurdprc\_tst [-b board]  
 -b board: Board number -- default board is 0

#### Example display:

```

./ccurdprc_tst

Device Name      : /dev/ccurdprc0
Board Serial No  : 680593 (0x000a6291)
Initialize_Board: Firmware Rev. 0x01 successful

  01 = add irq                       02 = disable pci interrupts
  03 = enable pci interrupts         04 = get device error
  05 = get driver info              06 = get physical mem
  07 = init board                   08 = mmap select
  09 = mmap(CONFIG registers)       10 = mmap(LOCAL registers)
  11 = mmap(physical memory)        12 = munmap(physical memory)
  13 = no command                   14 = read operation
  15 = remove irq                   16 = reset board
  17 = write operation

Main Selection ('h'=display menu, 'q'=quit)->

```

### 3.1.6 ccurdprc\_wreg

This is a simple test to write to the local registers at the user specified offset.

```
Usage: ./ccurdprc_wreg [-b board] [-o offset] [-s size] [-v value] [-x]
  -b board : board selection -- default board is 0
  -o offset: hex offset to write to -- default offset is 0x0
  -s size  : number of bytes to write -- default size is 0x4
  -v value : hex value to write at offset -- default value is 0x0
  -x       : Do not read back just written values -- default read back values
```

#### Example display:

```
./ccurdprc_wreg -v12345678 -o0x700 -s100
```

```
Device Name      : /dev/ccurdprc0
Board Serial No: 680593 (0x000a6291)
```

```
Writing 0x12345678 to offset 0x0700 for 256 bytes
```

```
#### LOCAL REGS #### (length=256)
+LCL+ 0x700 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x710 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x720 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x730 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x740 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x750 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x760 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x770 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x780 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x790 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x7a0 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x7b0 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x7c0 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x7d0 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x7e0 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
+LCL+ 0x7f0 12345678 12345678 12345678 12345678 *.4Vx.4Vx.4Vx.4Vx*
```

### 3.1.7 Flash/ccurdprc\_flash

This program is used to burn new firmware. This must only be done at the direction of Concurrent Real-Time support team; otherwise, they could render the board useless.

```
./ccurdprc_flash -[rw] -b[board] -q -s[start] -e[end] file_name
-b [board]      : board number. Default=-1
-e [end address] : Default=0x408c83
-q             : Quite (non-interactive) mode
-r            : Read Flash and write to output file created by
./ccurdprc_flash
-s [start address]: Default=0x0
-w             : Read input file and Flash the board
Use either -r or -w to read or write the ccurdprc spi flash
The file_name is required
```

```
e.g. ./ccurdprc_flash -w -s 0x0 -e 0x408C89 -b0 FIRMWARE/CCURDPRC.bin
     ./ccurdprc_flash -r -s 0x0 -e 0x408c89 -b0 /tmp/CCURDPRC.out
```

### 3.1.8 Flash/ccurdprc\_fwreload

This program reloads the firmware. This is normally performed after a new firmware is burnt.

```
./ccurdprc_fwreload -b[board]
-b [board]      : board number. Default=-1
```

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e.g. `./ccurdprc_fwreload -b0`

### 3.1.9 Eeprom/ccurdprc\_eeprom

This program is used to burn new eeprom. This must only be done at the direction of Concurrent Real-Time support team; otherwise, they could render the board useless.

```
./ccurdprc_eeprom -b[board]
-b [board]          : board number. Default=-1
```

e.g. `./ccurdprc_eeprom -b0`

#### Example display:

```
./ccurdprc_eeprom -b0
```

```
Device Name      : /dev/ccurdprc0
Board Serial No: 680593 (0x000a6291)
```

```
Dumping EEPROM: (0x00 - 0x3f)
@0x00:  9310 1542 0880 0001 0000 0100 0000 0000
@0x08:  0000 0000 ffff f800 0000 0001 0020 0000
@0x10:  0030 0400 0000 0000 0000 0000 4243 0343
@0x18:  0000 0000 0000 0000 0000 0000 0000 0000
@0x20:  0000 0000 9056 10b5 0000 0000 0000 0000
@0x28:  0000 0043 0000 4c00 0000 0000 0002 0000
@0x30:  0000 0000 0000 0000 0000 0000 0000 0000
@0x38:  0000 0000 0000 0000 0000 0000 0000 0100
```

```
device id        = 0x9310
vendor id        = 0x1542
subsystem device id = 0x9056
subsystem vendor id = 0x10b5
eeprom revision  = 0x0100
eeprom size      = 128 bytes
eeprom crc16     = 0x0000
```

```
  d = Dump EEPROM                p = Pattern Fill EEPROM
  r = Restore EEPROM to default   w = Write EEPROM
```

```
Main Selection ('h'=display menu, 'q'=quit)->
```

## 3.2 Application Program Interface (API) Access Example Tests

These set of tests are located in the `.../test/lib` directory and use the API.

### 3.2.1 lib/ccurdprc\_adc\_calibrate

This utility can be used to perform AutoCalibration. Additionally, they can use this utility can also be used to display or write calibration information.

```
Usage: ./ccurdprc_adc_calibrate [-A] [-A!] [-b board] [-i inCalFile]
                                     [-o outCalFile] [-R] [-W]
-A                                     (perform Auto Calibration)
-A !                                   (perform Auto Calibration only if any channel not
                                     calibrated)
-b <board>                             (board #, default = 0)
-i <In Cal File>                       (input calibration file [input->board_reg])
-o <Out Cal File>                      (output calibration file [board_reg->output])
-R                                     (reset calibration registers)
-W                                     (wait for busy to clear before autocal - approx 60
```

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seconds)

Example display:

./ccurdprc\_adc\_calibrate -A

Device Name : /dev/ccurdprc0  
Board Serial No: 680593 (0x000a6291)  
Auto Calibration started...done. (3.742 seconds)

==> Dump to 'stdout'

#Date : Fri Jan 05 07:49:27 2018

#Chan	Negative	Offset	Positive
#####	#####	#####	#####
ch00:	0.99923127004876732826	0.00061035156250000000	0.99922021990641951561
ch01:	0.99947279226034879684	0.00000000000000000000	0.99952901387587189674
ch02:	0.99920631432905793190	0.00000000000000000000	0.99925487162545323372
ch03:	0.99905325518921017647	0.00000000000000000000	0.99904842255637049675
ch04:	0.99838953465223312378	-0.00061035156250000000	0.99847391713410615921
ch05:	0.99927610578015446663	0.00000000000000000000	0.99934815429151058197
ch06:	0.99905750295147299767	-0.00122070312500000000	0.99922219337895512581
ch07:	0.99851436214521527290	0.00000000000000000000	0.99861047510057687759
ch08:	1.00050740223377943039	0.00061035156250000000	1.00050500780344009399
ch09:	1.00066073611378669739	0.00000000000000000000	1.00072780018672347069
ch10:	0.99857268156483769417	0.00000000000000000000	0.99864626117050647736
ch11:	0.99877768149599432945	-0.00061035156250000000	0.99878046847879886627
ch12:	0.99823356745764613152	0.00000000000000000000	0.99832826759666204453
ch13:	0.99831963051110506058	0.00061035156250000000	0.99833270628005266190
ch14:	1.00009105587378144264	-0.00122070312500000000	1.00013939756900072098
ch15:	0.99985559144988656044	0.00000000000000000000	0.99989806674420833588

./ccurdprc\_adc\_calibrate -o OUTFILE

Device Name : /dev/ccurdprc0  
Board Serial No: 680593 (0x000a6291)

==> Dump of 'OUTFILE' file

#Date : Fri Jan 05 07:50:16 2018

#Chan	Negative	Offset	Positive
#####	#####	#####	#####
ch00:	0.99923127004876732826	0.00061035156250000000	0.99922021990641951561
ch01:	0.99947279226034879684	0.00000000000000000000	0.99952901387587189674
ch02:	0.99920631432905793190	0.00000000000000000000	0.99925487162545323372
ch03:	0.99905325518921017647	0.00000000000000000000	0.99904842255637049675
ch04:	0.99838953465223312378	-0.00061035156250000000	0.99847391713410615921
ch05:	0.99927610578015446663	0.00000000000000000000	0.99934815429151058197
ch06:	0.99905750295147299767	-0.00122070312500000000	0.99922219337895512581
ch07:	0.99851436214521527290	0.00000000000000000000	0.99861047510057687759
ch08:	1.00050740223377943039	0.00061035156250000000	1.00050500780344009399
ch09:	1.00066073611378669739	0.00000000000000000000	1.00072780018672347069
ch10:	0.99857268156483769417	0.00000000000000000000	0.99864626117050647736
ch11:	0.99877768149599432945	-0.00061035156250000000	0.99878046847879886627
ch12:	0.99823356745764613152	0.00000000000000000000	0.99832826759666204453
ch13:	0.99831963051110506058	0.00061035156250000000	0.99833270628005266190
ch14:	1.00009105587378144264	-0.00122070312500000000	1.00013939756900072098
ch15:	0.99985559144988656044	0.00000000000000000000	0.99989806674420833588

==> Board calibration data written to 'OUTFILE' file

```
./ccurdprc_adc_calibrate -i INFILE
```

```
Device Name      : /dev/ccurdprc0
Board Serial No: 680593 (0x000a6291)
===> Calibration data from 'INFILE' file written to board
```

```
===> Dump of 'INFILE' file
#Date            : Fri Jan 05 07:50:16 2018
```

#Chan	Negative	Offset	Positive
ch00:	0.99923127004876732826	0.00061035156250000000	0.99922021990641951561
ch01:	0.99947279226034879684	0.00000000000000000000	0.99952901387587189674
ch02:	0.99920631432905793190	0.00000000000000000000	0.99925487162545323372
ch03:	0.99905325518921017647	0.00000000000000000000	0.99904842255637049675
ch04:	0.99838953465223312378	-0.00061035156250000000	0.99847391713410615921
ch05:	0.99927610578015446663	0.00000000000000000000	0.99934815429151058197
ch06:	0.99905750295147299767	-0.00122070312500000000	0.99922219337895512581
ch07:	0.99851436214521527290	0.00000000000000000000	0.99861047510057687759
ch08:	1.00050740223377943039	0.00061035156250000000	1.00050500780344009399
ch09:	1.00066073611378669739	0.00000000000000000000	1.00072780018672347069
ch10:	0.99857268156483769417	0.00000000000000000000	0.99864626117050647736
ch11:	0.99877768149599432945	-0.00061035156250000000	0.99878046847879886627
ch12:	0.99823356745764613152	0.00000000000000000000	0.99832826759666204453
ch13:	0.99831963051110506058	0.00061035156250000000	0.99833270628005266190
ch14:	1.00009105587378144264	-0.00122070312500000000	1.00013939756900072098
ch15:	0.99985559144988656044	0.00000000000000000000	0.99989806674420833588

```
===> Dump to 'stdout'
#Date            : Fri Jan 05 07:51:26 2018
```

#Chan	Negative	Offset	Positive
ch00:	0.99923127004876732826	0.00061035156250000000	0.99922021990641951561
ch01:	0.99947279226034879684	0.00000000000000000000	0.99952901387587189674
ch02:	0.99920631432905793190	0.00000000000000000000	0.99925487162545323372
ch03:	0.99905325518921017647	0.00000000000000000000	0.99904842255637049675
ch04:	0.99838953465223312378	-0.00061035156250000000	0.99847391713410615921
ch05:	0.99927610578015446663	0.00000000000000000000	0.99934815429151058197
ch06:	0.99905750295147299767	-0.00122070312500000000	0.99922219337895512581
ch07:	0.99851436214521527290	0.00000000000000000000	0.99861047510057687759
ch08:	1.00050740223377943039	0.00061035156250000000	1.00050500780344009399
ch09:	1.00066073611378669739	0.00000000000000000000	1.00072780018672347069
ch10:	0.99857268156483769417	0.00000000000000000000	0.99864626117050647736
ch11:	0.99877768149599432945	-0.00061035156250000000	0.99878046847879886627
ch12:	0.99823356745764613152	0.00000000000000000000	0.99832826759666204453
ch13:	0.99831963051110506058	0.00061035156250000000	0.99833270628005266190
ch14:	1.00009105587378144264	-0.00122070312500000000	1.00013939756900072098
ch15:	0.99985559144988656044	0.00000000000000000000	0.99989806674420833588

### 3.2.2 lib/ccurdprc\_disp

This is a powerful utility to not only display the various registers but control and test the board.

```
Usage: ./ccurdprc_disp [-a RollingAve] [-A] [-b BoardNo] [-c Chan] [-d Delay]
                        [-E ExpInpVolts] [-F DebugFile] [-l LoopCnt] [-r resistance]
                        [-s InputSignal] [-t Resistance] [-X]
-a RollingAve          (Rolling average -- default =1000)
-A                      (Perform Auto Calibration using reference voltage first)
-b BoardNo             (select specific board, default = 0)
-c ChanNo              (select specific channel, default = ALL CHANNELS)
-d Delay               (Delay between screen refresh in milli-seconds -- default is 10)
-E <ExpInpVolts><@Tol> (Expected Input Volts@Tolerance -- default Tol=0.006000)
+@<Tol>               (Positive Calibration Ref Volt@Tolerance)
```

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```

    -@<Tol>          (Negative Calibration Ref Volt@Tolerance)
    r@<Tol>          (Variable expected voltage based on selected resistance in '-t'
                    option)
-f FaultGeneration (select fault 'o','RaG','RbG','RaRbG','RaV','RbV','RaRbV',
                    'RaVRbG','RaGRbV')
    -f o            (Ch0..15[ 0]=Open [fault or disabled])
    -f rag          (Ch0..15[17]=RA Ground Fault)
    -f RBg          (Ch0..15[18]=RB Ground Fault)
    -f rarbg        (Ch0..15[19]=RA & RB Ground Fault)
    -f raV          (Ch0..15[20]=RA Voltage Plus Fault)
    -f RBV          (Ch0..15[21]=RB Voltage Plus Fault)
    -f rarbV        (Ch0..15[22]=RA & RB Voltage Plus Fault)
    -f RavRbg       (Ch0..15[33]=RA Voltage Plus & RB Ground Fault Switch Test)
    -f RaGRbV       (Ch0..15[34]=RA Ground & RB Voltage Plus Fault Switch Test)
-F DebugFile       (Menu display and write to debug file)
  @DebugFile       (No menu display. Only write to debug file)
  @                (No menu display or write to debug file, only summary to stderr)
-l LoopCnt         (Loop count -- default is 0)
-r <Resistance>    (Program Potentiometer resistance (Range: 10-1000000))
-s InputSignal     (select input signal, 'e', 'g', '+', '-', 't')
  -s e             (Ch0..15=External input)
  -s g             (Ch0..15=Ground Reference)
  -s t             (Ch0..15=Positive 2.5 Volts Reference)
  -s +             (Ch0..15=Positive 10 Volts Reference)
  -s -             (Ch0..15=Negative 10 Volts Reference)
-t <Resistance>@<Err> (Perform Potentiometer Test using supplied resistance
                    (Range: 10-1000000) -- default Err=3.0%
-X                (Adjusted Measured Ohms for programmed Ohms between
                    45 and 1000000)

```

Notes: Fault generation option 'f' and input signal option 's' not allowed together  
 Potentiometer test option 't' and program resistance option 'r' not allowed together  
 Potentiometer test option 't' and input signal option 's' not allowed together  
 Potentiometer test option 't' and fault generation option 'f' not allowed together  
 Option 't' % tolerance is with respect to the user supplied resistance

```

e.g. ./ccurdprc_disp -t1240          (set all channels resistance to 1240 and display)
     ./ccurdprc_disp -t1240 -c4      (set channel 4 resistance to 1240 and display)
     ./ccurdprc_disp -t40 -Er        (set all channels resistance to 40 and validate
                                     expected voltage)
     ./ccurdprc_disp -t12345 -FDebug (set all channels resistance to 12345 and output to
                                     Debug file)
     ./ccurdprc_disp -t1240 -X       (set all channels resistance to 1240 and display
                                     adjusted measured ohms)
     ./ccurdprc_disp -s+ -E10        (set all channels to 10V and validate expected
                                     voltage)
     ./ccurdprc_disp -se -r12345     (set all channels to external and program all
                                     channels to 12345 ohms)
     ./ccurdprc_disp -se -r12345 -c5 (set channel 5 to external and program channel 5 to
                                     12345 ohms)

```

### Example display:

```
./ccurdprc_disp -A
```

```
Auto Calibration started...done. (4.773 seconds)
```

```

Specific Channel Selected[-c]: === All Channels Selected ===
Delay                          [-d]: 10 milli-seconds
Expected Input Volts           [-E]: === Not Specified ===
Loop Count                     [-l]: ***Forever***
Calibration Bus Control        : 0 (Open)

```

```

: c00 c01 c02 c03 c04 c05 c06 c07 c08 c09 c10 c11 c12 c13 c14 c15
: === === === === === === === === === === === ===
Digital Pot. Test (HexMask)    : 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100
I/O Control (chan00..15)      : 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Scan Count                     : 2161
Read Duration (microsecs)     : TotalDelta: 33.127 (min= 32.827/max= 41.054/ave= 33.434)

```

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```

##### ADC Channels (Raw Hex Data) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
=====
[0]  0000    FFFF    FFFF    0000    FFFF    FFFE    FFFE    FFFF    FFFF    FFFE
[1]  FFFF    FFFF    FFFF    FFFF    FFFF    FFFF    FFFF    FFFF    FFFF    FFFF

```

```

##### ADC Channels (Volts) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
=====
[0] +0.0000 -0.0006 -0.0006 +0.0000 -0.0006 -0.0012 -0.0012 -0.0006 -0.0006 -0.0012
[1] -0.0006 -0.0006 -0.0006 -0.0006 -0.0006 -0.0006

```

```

##### Digital Potentiometer (Programmed Raw Hex Data) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
=====
[0]  32000   32000   32000   32000   32000   32000   32000   32000   32000   32000
[1]  32000   32000   32000   32000   32000   32000

```

```

##### Digital Potentiometer (Programmed Ohms) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
=====
[0] 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000
[1] 1000000 1000000 1000000 1000000 1000000 1000000

```

Expected Input Volts: === Not Specified ===

```

===== [ volts ] =====
Chan  Min      Max      Ave      TolerExceededCnt
=====
00   -0.0012   0.0006  -0.0003      -
01   -0.0024   0.0000  -0.0006      -
02   -0.0031   0.0000  -0.0006      -
03   -0.0024   0.0000  -0.0005      -
04   -0.0018   0.0000  -0.0004      -
05   -0.0024   0.0000  -0.0006      -
06   -0.0024   0.0006  -0.0007      -
07   -0.0031   0.0000  -0.0006      -
08   -0.0037   0.0012  -0.0008      -
09   -0.0031   0.0012  -0.0009      -
10   -0.0031   0.0006  -0.0004      -
11   -0.0031   0.0012  -0.0004      -
12   -0.0024   0.0006  -0.0006      -
13   -0.0018   0.0000  -0.0005      -
14   -0.0031   0.0012  -0.0007      -
15   -0.0031   0.0012  -0.0006      -
=====

```

./ccurdprc\_disp -t12345 -X

Selected Ohms=12345, Actual Ohms=12344, Expected ADC Volts=9.081813  
Computing Channel Voltage Error at 1 MegaOhm....done

```

==== Voltage Error Adjustment at 1 MegaOhm Resistance (for high ohms adjustment)
Chan= 0 Error=+0.000386 volts
Chan= 1 Error=+0.000514 volts
Chan= 2 Error=+0.000489 volts
Chan= 3 Error=+0.000666 volts
Chan= 4 Error=+0.001069 volts
Chan= 5 Error=+0.001197 volts
Chan= 6 Error=+0.000978 volts
Chan= 7 Error=+0.001002 volts
Chan= 8 Error=+0.000630 volts
Chan= 9 Error=+0.000343 volts
Chan=10 Error=+0.000489 volts
Chan=11 Error=+0.000801 volts
Chan=12 Error=+0.000941 volts
Chan=13 Error=+0.000727 volts

```

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```

Chan=14 Error=+0.000862 volts
Chan=15 Error=+0.000849 volts
Computing Channel Ohms where expected=programmed....done

```

```

==== Point where Programmed Equal to Measured Ohm (for low ohms adjustment)

```

```

Chan= 0 Ohm=960
Chan= 1 Ohm=1023
Chan= 2 Ohm=1333
Chan= 3 Ohm=994
Chan= 4 Ohm=558
Chan= 5 Ohm=1115
Chan= 6 Ohm=713
Chan= 7 Ohm=481
Chan= 8 Ohm=1207
Chan= 9 Ohm=2573
Chan=10 Ohm=960
Chan=11 Ohm=1866
Chan=12 Ohm=1517
Chan=13 Ohm=1115
Chan=14 Ohm=650
Chan=15 Ohm=1333

```

```

Specific Channel Selected[-c]: === All Channels Selected ===

```

```

Delay [-d]: 10 milli-seconds
Expected Input Volts [-E]: === Not Specified ===
Loop Count [-l]: ***Forever***
Potentiometer Test [-t]: supplied 12345 Ohms (actual=12344) (Tolerance 3.000000% error wrt actual ohms)
Adjusted Measured Ohms [-X]: === Enabled ===
Calibration Bus Control : 8 (+8 Milli-Ampere Current)

```

```

: c00 c01 c02 c03 c04 c05 c06 c07 c08 c09 c10 c11 c12 c13 c14 c15
: === === === === === === === === === === === ===
Digital Pot. Test (HexMask) : 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100
I/O Control (chan00..15) : (** all 15 channels being set to test bus '7' in turn **)

```

```

Scan Count : 456
Ohms Tolerance Exceeded Count: 0 (=== Passed ===)
Read Duration (microsecs) : TotalDelta: 55161.612
(min=55105.278/max=55184.692/ave=55041.208)

```

```

##### ADC Channels (Raw Hex Data) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 3A27 3A2A 3A28 3A2A 3A29 3A26 3A28 3A2A 3A27 3A25
[1] 3A2A 3A20 3A27 3A26 3A28 3A22

```

```

##### ADC Channels (Volts) ##### (Expected ADC Volts for Attached Resistance is 9.0818)
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +9.0867 +9.0883 +9.0875 +9.0886 +9.0880 +9.0860 +9.0874 +9.0887 +9.0869 +9.0852
[1] +9.0885 +9.0826 +9.0864 +9.0861 +9.0873 +9.0834

```

```

##### Digital Potentiometer (Programmed Raw Hex Data) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 009E0 009E0 009E0 009E0 009E0 009E0 009E0 009E0 009E0 009E0
[1] 009E0 009E0 009E0 009E0 009E0 009E0

```

```

##### Digital Potentiometer (Programmed Ohms) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 12344 12344 12344 12344 12344 12344 12344 12344 12344 12344
[1] 12344 12344 12344 12344 12344 12344

```

```

##### Digital Potentiometer (Adjusted Internal Measured Ohms) #####
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====

```

```
[0] 12410 12433 12421 12435 12420 12388 12411 12431 12410 12388
[1] 12436 12343 12398 12397 12413 12354
```

Expected Input Volts: === Not Specified ===

```
===== [ volts ] =====
Chan  Min      Max      Ave      TolerExceededCnt
=====  =====  =====  =====  =====
00    9.0865    9.0868    9.0867    -
01    9.0882    9.0885    9.0883    -
02    9.0873    9.0877    9.0875    -
03    9.0884    9.0887    9.0886    -
04    9.0879    9.0881    9.0880    -
05    9.0858    9.0861    9.0859    -
06    9.0872    9.0875    9.0873    -
07    9.0885    9.0888    9.0887    -
08    9.0867    9.0870    9.0869    -
09    9.0850    9.0853    9.0852    -
10    9.0883    9.0887    9.0885    -
11    9.0825    9.0828    9.0827    -
12    9.0862    9.0866    9.0864    -
13    9.0858    9.0862    9.0860    -
14    9.0871    9.0875    9.0873    -
15    9.0833    9.0836    9.0834    -
=====
```

Potentiometer Resistance: supplied 12345 ohms (actual=12344) (Tolerance 3.000000 % error wrt actual ohms)

Resistance Tolerance Exceed Count: 0

```
===== [ resistance ] =====
<----- (Ohms) -----> <-- (% error wrt supplied ohms ) -->
Chan  Min      Max      Ave      Min      Max      Ave      TolerExceededCnt
=====  =====  =====  =====  =====  =====  =====  =====
00    12408    12412    12409    0.52    0.55    0.53    -
01    12430    12435    12432    0.70    0.74    0.71    -
02    12419    12424    12420    0.61    0.65    0.62    -
03    12432    12436    12434    0.71    0.75    0.73    -
04    12418    12422    12420    0.60    0.63    0.62    -
05    12385    12389    12387    0.33    0.36    0.35    -
06    12409    12413    12410    0.53    0.56    0.53    -
07    12428    12432    12430    0.68    0.71    0.70    -
08    12407    12412    12409    0.51    0.55    0.53    -
09    12386    12390    12388    0.34    0.37    0.36    -
10    12433    12439    12436    0.72    0.77    0.75    -
11    12341    12347    12344    0.02    0.02    0.00    -
12    12395    12400    12397    0.41    0.45    0.43    -
13    12393    12399    12395    0.40    0.45    0.41    -
14    12410    12415    12412    0.53    0.58    0.55    -
15    12352    12357    12354    0.06    0.11    0.08    -
=====
```

./ccurdisp -s+ -a0

```
Rolling Average Count      [-a]: 1000
Specific Channel Selected[-c]: === All Channels Selected ===
Delay                      [-d]: 10 milli-seconds
Expected Input Volts      [-E]: === Not Specified ===
Loop Count                 [-l]: ***Forever***
Calibration Bus Control    : 2 (+10 Volts Reference)

                                : c00 c01 c02 c03 c04 c05 c06 c07 c08 c09 c10 c11 c12 c13 c14 c15
                                : === === === === === === === === === === === === === ===
Digital Pot. Test (HexMask) : 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100
I/O Control (chan00..15)   : (** all 15 channels being set to test bus '7' in turn **)

Scan Count                  : 1250
Read Duration (microsecs)   : TotalDelta: 55191.640
(min=55083.646/max=55212.522/ave=55140.996)
```

```
##### ADC Channels (Raw Hex Data) (Rolling Average Count [1000/1000]) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
```

```

=====
[0] 3FFF 3FFF 3FFF 3FFE 3FFF 3FFF 3FFF 3FFF 3FFE 3FFF
[1] 3FFF 3FFF 3FFF 3FFF 4000 3FFF

```

#### ADC Channels (Volts) ####

```

=====
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] +9.9997 +9.9998 +9.9998 +9.9994 +9.9997 +9.9999 +9.9998 +9.9997 +9.9994 +9.9997
[1] +9.9998 +9.9999 +9.9998 +9.9997+10.0000+10.0000

```

#### Digital Potentiometer (Programmed Raw Hex Data) ####

```

=====
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 32000 32000 32000 32000 32000 32000 32000 32000 32000 32000
[1] 32000 32000 32000 32000 32000 32000

```

#### Digital Potentiometer (Programmed Ohms) ####

```

=====
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000
[1] 1000000 1000000 1000000 1000000 1000000 1000000

```

Expected Input Volts: === Not Specified ===

===== [ volts ] =====

Chan	Min	Max	Ave	TolerExceededCnt
00	9.9998	9.9999	9.9999	-
01	9.9998	9.9999	9.9998	-
02	9.9995	9.9996	9.9996	-
03	9.9997	9.9998	9.9998	-
04	9.9999	10.0000	10.0000	-
05	9.9997	9.9998	9.9998	-
06	9.9998	9.9999	9.9998	-
07	9.9998	9.9999	9.9999	-
08	9.9998	9.9999	9.9999	-
09	9.9994	9.9995	9.9995	-
10	9.9995	9.9995	9.9995	-
11	9.9999	10.0000	10.0000	-
12	9.9996	9.9997	9.9997	-
13	9.9996	9.9997	9.9996	-
14	9.9998	9.9999	9.9998	-
15	9.9998	9.9999	9.9998	-

./cudrprc\_disp -f RavRbG

```

Specific Channel Selected[-c]: === All Channels Selected ===
Delay [-d]: 10 milli-seconds
Expected Input Volts [-E]: === Not Specified ===
Loop Count [-l]: ***Forever***
Calibration Bus Control : 0 (Open)

```

```

: c00 c01 c02 c03 c04 c05 c06 c07 c08 c09 c10 c11 c12 c13 c14 c15
: ===
Digital Pot. Test (HexMask) : 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100 100
I/O Control (chan00..15) : 33 33 33 33 33 33 33 33 33 33 33 33 33 33 33 33

```

```

Scan Count : 3515
Read Duration (microsecs) : TotalDelta: 33.184 (min= 32.809/max= 41.355/ave= 33.440)

```

#### ADC Channels (Raw Hex Data) ####

```

=====
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====
[0] 5EF4 5EF7 5F06 5ED9 5EEA 5ED9 5EDC 5EC8 5EE6 5F02
[1] 5EC6 5EF4 5F0B 5EFA 5EF3 5F0A

```

#### ADC Channels (Volts) ####

```

=====
[0] [1] [2] [3] [4] [5] [6] [7] [8] [9]
=====

```



```

=====
[0]+14.8364+14.8383+14.8474+14.8199+14.8303+14.8199+14.8218+14.8096+14.8279+14.8450
[1]+14.8083+14.8364+14.8505+14.8401+14.8358+14.8499
=====

```

```

-----
##### Digital Potentiometer (Programmed Raw Hex Data) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
=====
[0]  32000  32000  32000  32000  32000  32000  32000  32000  32000  32000
[1]  32000  32000  32000  32000  32000  32000

```

```

##### Digital Potentiometer (Programmed Ohms) #####
      [0]      [1]      [2]      [3]      [4]      [5]      [6]      [7]      [8]      [9]
=====
[0] 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000 1000000
[1] 1000000 1000000 1000000 1000000 1000000 1000000

```

Expected Input Volts: === Not Specified ===

```

===== [ volts ] =====
Chan  Min      Max      Ave      TolerExceededCnt
=====
00   14.8236  14.8370  14.8360  -
01   14.8248  14.8395  14.8378  -
02   14.8352  14.8486  14.8467  -
03   14.8071  14.8218  14.8203  -
04   14.8175  14.8322  14.8303  -
05   14.8065  14.8218  14.8202  -
06   14.8083  14.8230  14.8218  -
07   14.7955  14.8108  14.8093  -
08   14.8157  14.8303  14.8282  -
09   14.8328  14.8462  14.8446  -
10   14.7955  14.8108  14.8087  -
11   14.8242  14.8389  14.8364  -
12   14.8376  14.8511  14.8491  -
13   14.8273  14.8413  14.8397  -
14   14.8242  14.8413  14.8369  -
15   14.8376  14.8529  14.8494  -
=====

```

### 3.2.3 lib/ccurdprc\_fault\_protection

This utility is useful in displaying any Electronic Fuse Trip faults that may have occurred.

```

Usage: ./ccurdprc_fault_protection [-A] [-b BoardNo] [-c ChannelMask] [-d Delay]
      [-F DebugFile] [-l LoopCnt] [-R]
-A          (perform Auto Calibration)
-b BoardNo  (select specific board, default = 0)
-c ChannelMask (Channel mask, default = 0xffff)
-d Delay    (Delay between screen refresh in milli-seconds -
            default is 10)
-F DebugFile (Menu display and write to debug file)
  @DebugFile (No menu display. Only write to debug file)
  @          (No menu display or write to debug file, only summary
            to stderr)
-l LoopCnt  (Loop count -- default is 0)
-R          (Clear Fault Condition)

```

#### Example display:

```
./ccurdprc_fault_protection
```

```

Channel Mask  [-c]: 0xffff
Delay         [-d]: 10 milli-seconds
Loop Count    [-l]: ***Forever***

```

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```
Scan Count          : 332
Read Duration (microsecs): TotalDelta: 204.982 (min= 203.346/max= 215.011/ave= 206.281)
```

```
Any Fuse Tripped: 0 (=== No ===)
ADC 0 Failed: 0 (=== No ===)
ADC 1 Failed: 0 (=== No ===)
Channel Fuse Tripped Mask: 0x0000
Electrical Short: 0x00b4 (0.109863 volts)
Delay: 0x0002 (2)
Count: 0x0001 (1)
I/O Delay: 0x0800 (31.000000 microseconds)
Maximum Resistance: 0x00fd (1266.000000 ohms)
Maximum Voltage: 0x5ae0 (14.199219 volts)
Voltage Fault Delay: 0x0002 (8 microseconds)
```

Ch	Trip?	Fuse_Base hex volts	Fuse_Multiplier hex volts	Potentiometer hex ohms	Threshold hex volts	IOS hex
0	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
1	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
2	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
3	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
4	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
5	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
6	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
7	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
8	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
9	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
10	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
11	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
12	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
13	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
14	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21
15	---	0241 (0.352173)	005a (0.054932)	32000 (1000000)	5ae0 (14.199219)	21

Ch	AnyTrip?	CalNotValid?	PotFail?	ADCFail?	VoltTrip?	ADCComp?	ADCValue? (hex/volts)
0	---	---	---	---	---	---	0000 (0.000000)
1	---	---	---	---	---	---	0000 (0.000000)
2	---	---	---	---	---	---	0000 (0.000000)
3	---	---	---	---	---	---	0000 (0.000000)
4	---	---	---	---	---	---	0000 (0.000000)
5	---	---	---	---	---	---	0000 (0.000000)
6	---	---	---	---	---	---	0000 (0.000000)
7	---	---	---	---	---	---	0000 (0.000000)
8	---	---	---	---	---	---	0000 (0.000000)
9	---	---	---	---	---	---	0000 (0.000000)
10	---	---	---	---	---	---	0000 (0.000000)
11	---	---	---	---	---	---	0000 (0.000000)
12	---	---	---	---	---	---	0000 (0.000000)
13	---	---	---	---	---	---	0000 (0.000000)
14	---	---	---	---	---	---	0000 (0.000000)
15	---	---	---	---	---	---	0000 (0.000000)

### 3.2.4 lib/ccurdprc\_fault\_trip\_test

This utility is only for validating the boards handling of Enetronic Fuse Trip handling.

```
Usage: ./ccurdprc_fault_trip_test [-A] [-b BoardNo] [-c ChannelMask]
                                     [-F DebugFile] [-l LoopCnt] [-R] [-t TestRun]

-A (perform Auto Calibration)
-b BoardNo (select specific board, default = 0)
-c ChannelMask (Channel mask, default = 0xffff)
-F DebugFile (Menu display and write to debug file)
  @DebugFile (No menu display. Only write to debug file)
  @ (No menu display or write to debug file, only summary
    to stderr)
-l LoopCnt (Loop count -- default is 1)
-R (Clear Fault Condition)
```

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```

-t TestRun                (Test Run Option -- default is all options)
                          ( -t1 Calibration Not Valid Trip)
                          ( -t2 ADC Failure Trip)
                          ( -t3 ADC Compare Short Failure Trip)
                          ( -t4 ADC Compare Low Resistance Failure Trip)
                          ( -t5 Potentiometer Failure Trip)
                          ( -t6 Switch Voltage Failure Trip)

```

**Example display:**

```

##### Loop      1 #####
1) Testing tripping condition for "Calibration Not Valid"
   Activating ADC and Potentiometer.....passed
   Preserving Calibration for selected channels.....passed

   Case (A)
   =====
   Clearing Calibration for selected channels.....passed
   Clearing Faults for selected channels      [0xffff]...passed
   Validating Faults for selected channels    [0xffff]...passed

   Case (B)
   =====
   Writing Potentiometer to selected Channels [0x0001]...passed
   Validating Faults for selected channels    [0xffff]...passed
   Writing Potentiometer to selected Channels [0x0002]...passed
   Validating Faults for selected channels    [0xffff]...passed
   Writing Potentiometer to selected Channels [0x0004]...passed
   .
   .
   .
   Case (C)
   =====
   Restoring Calibration for selected channels.....passed
   Clearing Faults for selected channels      [0x0001]...passed
   Writing Potentiometer to selected Channels [0x0001]...passed
   Validating Faults for selected channels    [0xffff]...passed
   Clearing Faults for selected channels      [0x0002]...passed
   Writing Potentiometer to selected Channels [0x0002]...passed
   Validating Faults for selected channels    [0xffff]...passed
   .
   .
   .
   Restoring Calibration for selected channels.....passed
   ==== PASSED ====
2) Test tripping condition for "ADC Failure".....
   Activating ADC and Potentiometer.....passed

   Case (A)
   =====
   Disabling both ADCs.....passed
   Validating Faults for selected channels    [0xffff]...passed

   Case (B)
   =====
   Writing Potentiometer to selected Channels [0x0001]...passed
   Validating Faults for selected channels    [0xffff]...passed
   Writing Potentiometer to selected Channels [0x0002]...passed
   Validating Faults for selected channels    [0xffff]...passed
   .
   .
   .
   Case (C)

```

```
=====  
Enabling all ADCs.....passed  
Validating Faults for selected channels [0xffff]...passed
```

Case (D)

```
=====  
Clearing Faults for selected channels [0x0001]...passed  
Validating Faults for selected channels [0xffff]...passed  
Clearing Faults for selected channels [0x0002]...passed  
Validating Faults for selected channels [0xffff]...passed
```

.  
. .

```
Clearing Faults for selected channels [0x8000]...passed  
Validating Faults for selected channels [0xffff]...passed
```

==== PASSED ====

- 3) Test tripping condition for "ADC Compare Short Failure".  
Activating ADC and Potentiometer.....passed

Case (A) - Calibration Control is Open

```
=====  
Writing 10 Ohms (short) to all Channels [0xffff]...passed  
Setting Electronic Fuse Short Value to 44.....passed  
Setting Electronic Fuse Short Value to 43.....passed  
Setting Electronic Fuse Short Value to 42.....passed
```

.  
. .

```
Setting Electronic Fuse Short Value to 2.....passed  
Setting Electronic Fuse Short Value to 1.....passed  
Tripped Channels Mask [0x0b00]...passed  
Setting Electronic Fuse Short Value to 0.....passed  
Tripped Channels Mask [0xffff]...passed  
1: Tripped Channels Mask [0xffff]...passed  
Validating Faults for selected channels [0xffff]...passed  
Activating ADC and Potentiometer.....passed
```

Case (B) - Calibration Control is Minus 8 Milli-Amps

```
=====  
Writing 10 Ohms (short) to all Channels [0xffff]...passed  
Setting Electronic Fuse Short Value to 44.....passed  
Tripped Channels Mask [0xff7f]...passed  
Setting Electronic Fuse Short Value to 43.....passed  
Tripped Channels Mask [0xff7f]...passed
```

.  
. .

```
Setting Electronic Fuse Short Value to 17.....passed  
Tripped Channels Mask [0xffff]...passed  
1: Tripped Channels Mask [0xffff]...passed  
Validating Faults for selected channels [0xffff]...passed  
Activating ADC and Potentiometer.....passed
```

Case (C) - Calibration Control is Plus 8 Milli-Amps

```
=====  
Writing 10 Ohms (short) to all Channels [0xffff]...passed  
Setting Electronic Fuse Short Value to 44.....passed  
Tripped Channels Mask [0xffff]...passed  
1: Tripped Channels Mask [0xffff]...passed  
Validating Faults for selected channels [0xffff]...passed  
Activating ADC and Potentiometer.....passed
```

Case (D) - Calibration Control is Plus 2.5 Volts

```

=====
Writing 10 Ohms (short) to all Channels      [0xffff]...passed
Setting Electronic Fuse Short Value to 44.....passed
Setting Electronic Fuse Short Value to 43.....passed
Setting Electronic Fuse Short Value to 42.....passed
.
.
.
Setting Electronic Fuse Short Value to 2.....passed
Setting Electronic Fuse Short Value to 1.....passed
Tripped Channels Mask                        [0x4300]...passed
Setting Electronic Fuse Short Value to 0.....passed
Tripped Channels Mask                        [0xffff]...passed
  1: Tripped Channels Mask                    [0xffff]...passed
Validating Faults for selected channels      [0xffff]...passed
Activating ADC and Potentiometer.....passed

Case (E) - Calibration Control is Minus 10 Volts
=====
Writing 10 Ohms (short) to all Channels      [0xffff]...passed
Setting Electronic Fuse Short Value to 44.....passed
Tripped Channels Mask                        [0xffff]...passed
  1: Tripped Channels Mask                    [0xffff]...passed
Validating Faults for selected channels      [0xffff]...passed
Activating ADC and Potentiometer.....passed

Case (F) - Calibration Control is Plus 10 Volts
=====
Writing 10 Ohms (short) to all Channels      [0xffff]...passed
Setting Electronic Fuse Short Value to 44.....passed
Tripped Channels Mask                        [0xffff]...passed
  1: Tripped Channels Mask                    [0xffff]...passed
Validating Faults for selected channels      [0xffff]...passed
==== PASSED ====
4) Test tripping condition for "ADC Compare Low Resistance Failure".
   Activating ADC and Potentiometer.....passed

Case (A) - Low Resistance    45 Ohms
=====
Writing 45 Ohms (short) to all Channels      [0xffff]...passed
Validating Faults for selected channels      [0xffff]...passed

Case (B) - Low Resistance    45 Ohms
=====
Setting Fuse Base to 0x0192 for channel 0.....passed
Validating Faults for selected channels      [0xffff]...passed
Setting Fuse Base to 0x0191 for channel 1.....passed
Validating Faults for selected channels      [0xffff]...passed
.
.
.
Setting Fuse Base to 0x0195 for channel 15.....passed
Validating Faults for selected channels      [0xffff]...passed

Case (C) - Low Resistance    45 Ohms
=====
Clearing Faults for selected channels        [0x0001]...passed
Validating Faults for selected channels      [0xffff]...passed
.
.
.
Clearing Faults for selected channels        [0x8000]...passed
Validating Faults for selected channels      [0xffff]...passed

```

```

Case (D) - Low Resistance    45 Ohms
=====
Writing    45 Ohms (short) to Channel    [0x0001]...passed
Validating Faults for selected channels  [0xffff]...passed
.
.
.
Writing    45 Ohms (short) to Channel    [0x8000]...passed
Validating Faults for selected channels  [0xffff]...passed

Case (E) - Low Resistance    45 Ohms
=====
Clearing Faults for selected channels    [0x0001]...passed
Setting Fuse Base/Multiplier defaults for channel 0..passed
Writing    45 Ohms (short) to Channel    [0x0001]...passed
Validating Faults for selected channels  [0xffff]...passed
.
.
.
Case (A) - Low Resistance 1265 Ohms
=====
Writing 1265 Ohms (short) to all Channels [0xffff]...passed
Validating Faults for selected channels  [0xffff]...passed

Case (B) - Low Resistance 1265 Ohms
=====
Setting Fuse Multiplier to 0x001e for channel 0.....passed
Validating Faults for selected channels  [0xffff]...passed
Setting Fuse Multiplier to 0x001e for channel 1.....passed
Validating Faults for selected channels  [0xffff]...passed
.
.
.
Setting Fuse Multiplier to 0x001e for channel 15.....passed
Validating Faults for selected channels  [0xffff]...passed

Case (C) - Low Resistance 1265 Ohms
=====
Clearing Faults for selected channels    [0x0001]...passed
Validating Faults for selected channels  [0xffff]...passed
.
.
.
Clearing Faults for selected channels    [0x8000]...passed
Validating Faults for selected channels  [0xffff]...passed

Case (D) - Low Resistance 1265 Ohms
=====
Writing 1265 Ohms (short) to Channel    [0x0001]...passed
Validating Faults for selected channels  [0xffff]...passed
.
.
.
Writing 1265 Ohms (short) to Channel    [0x8000]...passed
Validating Faults for selected channels  [0xffff]...passed

Case (E) - Low Resistance 1265 Ohms
=====
Clearing Faults for selected channels    [0x0001]...passed
Setting Fuse Base/Multiplier defaults for channel 0..passed
Writing 1265 Ohms (short) to Channel    [0x0001]...passed
Validating Faults for selected channels  [0xffff]...passed

```

```

.
.
Setting Fuse Base/Multiplier defaults for channel 15..passed
Writing 1265 Ohms (short) to Channel      [0x8000]...passed
Validating Faults for selected channels  [0xffff]...passed
==== PASSED ====
5) Test tripping condition for "Potentiometer Failure" ....
   Activating ADC and Potentiometer.....passed

Case (A)
=====
Force Potentiometer Failure on all channels.....passed
Validating Faults for selected channels  [0xffff]...passed

Case (B)
=====
Writing Potentiometer to selected Channels [0x0001]...passed
Validating Faults for selected channels  [0xffff]...passed
Writing Potentiometer to selected Channels [0x0002]...passed
Validating Faults for selected channels  [0xffff]...passed
.
.
Writing Potentiometer to selected Channels [0x8000]...passed
Validating Faults for selected channels  [0xffff]...passed

Case (C)
=====
Activating ADC and Potentiometer.....passed
Validating Faults for selected channels  [0xffff]...passed
==== PASSED ====
6) Test tripping condition for "Switch Voltage Failure"....(ToBeCoded)

```

### 3.2.5 lib/ccurdprc\_identify

This test is useful in identifying a card by displaying its LED.

```

Usage: ./ccurdprc_identify -[absx]
-a                (Identify all cards through a light sequence)
-b <board>        (board #, default = 0)
-s <seconds>      (Identify Board: ENABLED for number of seconds,
                  default = 10)
-s 0              (Identify Board: DISABLED)
-s <negative value> (Identify Board: ENABLED forever)
-x                (silent)

```

If the '-a' option is selected, all other options are ignored. This option will sequence through all the cards found in turn as follows:

- 1) The first device number will flash its LED for 10 seconds
- 2) The remaining devices numbers will be selected sequentially and flash their LEDs for 3 seconds

#### Example display:

```

./ccurdprc_identify

Device Name      : /dev/ccurdprc0
Board ID         : 9310
Board Type       : 01
Board NumChans   : 16
Board Cal Volts  : 10.000000
Board Serial No: 680584 (0x000a6288)

```

Identify ENABLED on board 0 (LED should start flashing for 10 seconds)  
Sleeping for 10 seconds...  
Identify DISABLED on board 0 (LED should stop flashing)

### 3.2.6 lib/ccurdprc\_info

This test is useful in getting information for all the *ccurdprc* devices in the system.

Usage: ./ccurdprc\_info -[bpv]  
-b <board> (board #, default = 0)  
-p <a|d> (Program Activate(a)/Disable(d) All, default = no program)  
-v (Verbose, default = no verbose)

#### Example display:

```
./ccurdprc_info
Version: 23.1.1
Build: Apr 14 2020, 12:33:40
Module: ccurdprc
Board Index: 0 (PLX-CCURDPRC)
Board Serial No: 680593 (0x000a6291)
Serial Prom Rev: 0x0000
Bus: 8
Slot: 4
Func: 0
Vendor ID: 0x1542
Sub-Vendor ID: 0x10b5
Board ID: 0x9310
Board Type: 0x0001
Sub-Device ID: 0x9056
Board Info: 0x93100102
MSI Support: Enabled
IRQ Level: 55
Firmware: 0x0001
Interrupt Count: 0
Interrupt Status: 0x0000
Number of Channels: 16
All Channel Mask: 0xffff
Calibration Reference Voltage: 10.000000 volts
Voltage Range: 0.000000 volts
Region 0: Addr=0xc4c01000 Size=512 (0x200)
Region 2: Addr=0xc4c00000 Size=2048 (0x800)
Calibration Bus Control: 00 (0x0) Bus Open
I/O Control: === Disabled ===
Potentiometer: === Disabled ===
Potentiometer Test: === Disabled ===
Analog to Digital Converter: === Disabled ===
Any Fuse Tripped: === No ===
ADC 0 Failed: ### Yes ###
ADC 1 Failed: ### Yes ###
Electrical Short: 0x00b4 (0.109863 volts)
Delay: 0x0002 (2)
Count: 0x0001 (1)
I/O Delay: 0x0800 (31.000000 volts)
Maximum Resistance: 0x00fd (1266.000000 ohms)
Maximum voltage: 0x5ae0 (14.199219 volts)
Voltage Fault Delay: 0x0002 (8 microseconds)
```

```
./ccurdprc_info -v
Version: 23.1.1
Build: Apr 14 2020, 12:33:40
Module: ccurdprc
Board Index: 0 (PLX-CCURDPRC)
Board Serial No: 680593 (0x000a6291)
Serial Prom Rev: 0x0000
Bus: 8
Slot: 4
```



```

Func: 0
Vendor ID: 0x1542
Sub-Vendor ID: 0x10b5
Board ID: 0x9310
Board Type: 0x0001
Sub-Device ID: 0x9056
Board Info: 0x93100102
MSI Support: Enabled
IRQ Level: 55
Firmware: 0x0001
Interrupt Count: 0
Interrupt Status: 0x0000
Number of Channels: 16
All Channel Mask: 0xffff
Calibration Reference Voltage: 10.000000 volts
Voltage Range: 0.000000 volts
Region 0: Addr=0xc4c01000 Size=512 (0x200)
Region 2: Addr=0xc4c00000 Size=2048 (0x800)
Calibration Bus Control: 00 (0x0) Bus Open
:
Calibration Information: Negative Offset Positive
=====
Channel 0: 0.99923393130302429199 0.00061035156250000000
0.99922629352658987045
Channel 1: 0.99947733711451292038 0.00000000000000000000
0.99953469820320606232
Channel 2: 0.99920863285660743713 0.00000000000000000000
0.99925949377939105034
Channel 3: 0.99905715836212038994 0.00000000000000000000
0.99905238440260291100
Channel 4: 0.99838956817984580994 -0.00061035156250000000
0.99847721355035901070
Channel 5: 0.99927859148010611534 0.00000000000000000000
0.99935070564970374107
Channel 6: 0.99905843008309602737 -0.00122070312500000000
0.99922330724075436592
Channel 7: 0.99851754121482372284 0.00000000000000000000
0.99861228326335549355
Channel 8: 1.00050913682207465172 0.00061035156250000000
1.00050572864711284637
Channel 9: 1.00065903877839446068 0.00000000000000000000
1.00072941137477755547
Channel 10: 0.99857431231066584587 0.00000000000000000000
0.99864789657294750214
Channel 11: 0.99878009874373674393 -0.00061035156250000000
0.99878242751583456993
Channel 12: 0.99823445873335003853 0.00000000000000000000
0.99833095585927367210
Channel 13: 0.99832039466127753258 0.00061035156250000000
0.99833637848496437073
Channel 14: 1.00009206961840391159 -0.00122070312500000000
1.00013942923396825790
Channel 15: 0.99985691532492637634 0.00000000000000000000
0.99989738129079341888
:
I/O Control: Value Description
=====
Channel 0: 00 (0x00) Open
Channel 1: 00 (0x00) Open
Channel 2: 00 (0x00) Open
Channel 3: 00 (0x00) Open
Channel 4: 00 (0x00) Open
Channel 5: 00 (0x00) Open
Channel 6: 00 (0x00) Open
Channel 7: 00 (0x00) Open
Channel 8: 00 (0x00) Open
Channel 9: 00 (0x00) Open
Channel 10: 00 (0x00) Open
Channel 11: 00 (0x00) Open
Channel 12: 00 (0x00) Open

```

```

Channel 13: 00 (0x00) Open
Channel 14: 00 (0x00) Open
Channel 15: 00 (0x00) Open
:
Potentiometer: Value (Raw) Ohms
=====
Channel 0: 204800 1000000
Channel 1: 204800 1000000
Channel 2: 204800 1000000
Channel 3: 204800 1000000
Channel 4: 204800 1000000
Channel 5: 204800 1000000
Channel 6: 204800 1000000
Channel 7: 204800 1000000
Channel 8: 204800 1000000
Channel 9: 204800 1000000
Channel 10: 204800 1000000
Channel 11: 204800 1000000
Channel 12: 204800 1000000
Channel 13: 204800 1000000
Channel 14: 204800 1000000
Channel 15: 204800 1000000
:
Potentiometer Test: Value (Mask) Description
=====
Channel 0: 0x00000100 20K Potentiometer Mode
Channel 1: 0x00000100 20K Potentiometer Mode
Channel 2: 0x00000100 20K Potentiometer Mode
Channel 3: 0x00000100 20K Potentiometer Mode
Channel 4: 0x00000100 20K Potentiometer Mode
Channel 5: 0x00000100 20K Potentiometer Mode
Channel 6: 0x00000100 20K Potentiometer Mode
Channel 7: 0x00000100 20K Potentiometer Mode
Channel 8: 0x00000100 20K Potentiometer Mode
Channel 9: 0x00000100 20K Potentiometer Mode
Channel 10: 0x00000100 20K Potentiometer Mode
Channel 11: 0x00000100 20K Potentiometer Mode
Channel 12: 0x00000100 20K Potentiometer Mode
Channel 13: 0x00000100 20K Potentiometer Mode
Channel 14: 0x00000100 20K Potentiometer Mode
Channel 15: 0x00000100 20K Potentiometer Mode
Analog to Digital Converter: Value (Hex) Volts
=====
Channel 0: 0x0000 +0.000000
Channel 1: 0xffff -0.000610
Channel 2: 0xffff -0.000610
Channel 3: 0x0000 +0.000000
Channel 4: 0xffff -0.000610
Channel 5: 0xffff -0.000610
Channel 6: 0xffff -0.000610
Channel 7: 0xffff -0.000610
Channel 8: 0xffff -0.000610
Channel 9: 0xffff -0.000610
Channel 10: 0xffff -0.000610
Channel 11: 0xffff -0.000610
Channel 12: 0xffff -0.000610
Channel 13: 0xffff -0.000610
Channel 14: 0xffff -0.000610
Channel 15: 0x0000 +0.000000
Any Fuse Tripped: === No ===
ADC 0 Failed: === No ===
ADC 1 Failed: === No ===
Electrical Short: 0x00b4 (0.109863 volts)
Delay: 0x0002 (2)
Count: 0x0001 (1)
I/O Delay: 0x0800 (31.000000 volts)
Maximum Resistance: 0x00fd (1266.000000 ohms)
Maximum voltage: 0x5ae0 (14.199219 volts)
Voltage Fault Delay: 0x0002 (8 microseconds)
:

```

```

Threshold      IOS      :      Fuse_Base      Fuse_Multiplier      Potentiometer
Channel Fault Information: Trip? hex volts      hex volts      hex ohms
hex volts      hex
=====
Channel 0: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 1: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 2: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 3: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 4: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 5: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 6: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 7: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 8: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 9: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 10: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 11: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 12: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 13: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 14: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
Channel 15: --- 0241 (0.352173) 005a (0.054932) 32000 (1000000)
5ae0 (14.199219) 00
:
Channel Fault Information: AnyTrip? CalNotValid? PotFail? ADCFail? VoltTrip? ADCComp?
ADCValue? (hex/volts)
=====
Channel 0: --- --- --- --- --- ---
0000 (0.000000)
Channel 1: --- --- --- --- --- ---
0000 (0.000000)
Channel 2: --- --- --- --- --- ---
0000 (0.000000)
Channel 3: --- --- --- --- --- ---
0000 (0.000000)
Channel 4: --- --- --- --- --- ---
0000 (0.000000)
Channel 5: --- --- --- --- --- ---
0000 (0.000000)
Channel 6: --- --- --- --- --- ---
0000 (0.000000)
Channel 7: --- --- --- --- --- ---
0000 (0.000000)
Channel 8: --- --- --- --- --- ---
0000 (0.000000)
Channel 9: --- --- --- --- --- ---
0000 (0.000000)
Channel 10: --- --- --- --- --- ---
0000 (0.000000)
Channel 11: --- --- --- --- --- ---
0000 (0.000000)
Channel 12: --- --- --- --- --- ---
0000 (0.000000)
Channel 13: --- --- --- --- --- ---
0000 (0.000000)

```

```

Channel 14: --- --- --- --- --- ---
0000 (0.000000)
Channel 15: --- --- --- --- --- ---
0000 (0.000000)

```

### 3.2.7 lib/ccurprc\_tst\_lib

This is an interactive test that accesses the various supported API calls.

```

Usage: ./ccurprc_tst_lib [-b board]
-b board: board number -- default board is 0

```

#### Example display:

```
./ccurprc_tst_lib
```

```

Device Name: /dev/ccurprc0
01 = Abort DMA
03 = Clear Library Error
05 = Display CONFIG Registers
07 = Get Board Information
09 = Get Driver Information
11 = Get Driver Write Mode
13 = Get Mapped Config Pointer
15 = Get Mapped Local Pointer
17 = Get Value
19 = MMap Physical Memory
21 = Read Operation
23 = Reset Board
25 = Select Driver Write Mode
27 = Set Value
29 = ### CALIBRATION MENU ###
31 = ### ELECTRONIC FUSE CONTROL MENU ###
33 = ### SERIAL PROM MENU ###
02 = Clear Driver Error
04 = Display BOARD Registers
06 = Get Board CSR
08 = Get Driver Error
10 = Get Driver Read Mode
12 = Get Library Error
14 = Get Mapped Driver/Library Pointer
16 = Get Physical Memory
18 = Initialize Board
20 = Munmap Physical Memory
22 = Read Channels
24 = Select Driver Read Mode
26 = Set Board CSR
28 = ### ADC CONTROL MENU ###
30 = ### DIGITAL POT AND I/O CONTROL MENU
32 = ### INTERRUPT MENU ###

```

```
Main Selection ('h'=display menu, 'q'=quit)->
```

```

Main Selection ('h'=display menu, 'q'=quit)-> 28
Command: ADC_control_menu()
01 = ADC Activate
03 = ADC Read Channels
02 = ADC Disable

```

```
ADC Selection ('h'=display menu, 'q'=quit)->
```

```

Main Selection ('h'=display menu, 'q'=quit)-> 29
Command: calibration_menu()
01 = Get Calibrated Values
03 = Perform Auto Calibration
05 = Perform External Offset Calib.
07 = Perform Negative Calibration
09 = Perform Positive Calibration
11 = Reset Calibration
13 = Set Calibration Bus Control
02 = Get Calibration Bus Control
04 = Perform External Negative Calib.
06 = Perform External Positive Calib.
08 = Perform Offset Calibration
10 = Read calibration channels
12 = Write Channels Calibration

```

```
Calibration Selection ('h'=display menu, 'q'=quit)->
```

```

Main Selection ('h'=display menu, 'q'=quit)-> 30
Command: DigitalPotAndIo_control_menu()
01 = Digital Potentiometer & I/O Activate
03 = Digital Potentiometer Get Resistance
05 = Digital Potentiometer Set Resistance
07 = I/O Control Get
02 = Digital Potentiometer & I/O Disable
04 = Digital Potentiometer Get Test
06 = Digital Potentiometer Set Test
08 = I/O Control Set

```

```
Digital Pot and I/O Selection ('h'=display menu, 'q'=quit)->
```

```

Main Selection ('h'=display menu, 'q'=quit)-> 31
Command: ElectronicFuse_control_menu()
01 = Clear Electronic Fuse Trip
03 = Get Electronic Fuse Base
02 = Dump Electronic Fuse Registers
04 = Get Electronic Fuse Internals

```

```
05 = Get Electronic Fuse Multiplier      06 = Get Electronic Fuse Status
07 = Get Electronic Fuse Threshold       08 = Get Electronic Fuse Trip
```

```
Electronic Fuse Selection ('h'=display menu, 'q'=quit)->
```

---

```
Main Selection ('h'=display menu, 'q'=quit)-> 32
Command: interrupt_menu()
01 = Add Irq                               02 = Disable Pci Interrupts
03 = Enable Pci Interrupts                 04 = Get Interrupt Control
05 = Get Interrupt Status                  06 = Get Interrupt Timeout
07 = Remove Irq                           08 = Set Interrupt Control
09 = Set Interrupt Status                  10 = Set Interrupt Timeout
```

```
Interrupt Selection ('h'=display menu, 'q'=quit)->
```

---

```
Main Selection ('h'=display menu, 'q'=quit)-> 33
Command: serial_prom_menu()
01 = Clear Serial Prom                    02 = Read Serial PROM
03 = Serial PROM Write Override           04 = Write Serial PROM
```

```
Serial PROM Selection ('h'=display menu, 'q'=quit)->
```

---

### 3.2.8 lib/Sprom/ccurdprc\_sprom

This is a simple program to demonstrate sprom access.

```
Usage: ./ccurdprc_sprom [-b board] [-C] [-D] [-S serialNo]
```

```
-b <board>          (Board #, default = 0)
-C                  (Clear ENTIRE serial PROM first)
-D                  (Dump entire serial prom)
-S <serialNo>      (Program board serial number)
```

```
e.g. ./ccurdprc_sprom -C          -> Clear Entire Serial Prom First
e.g. ./ccurdprc_sprom -D          -> Dump Entire Serial Prom
e.g. ./ccurdprc_sprom -S 12345678 -> Write Serial Number
```

#### Example display:

```
./Sprom/ccurdprc_sprom
```

```
Device Name:          /dev/ccurdprc0
Board Serial Number:  680593 (0x000a6291)
Serial PROM Revision: 0 (0x0000)
```

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