

# Software Interface

## CCURPWM (WC-PWM-1012 Output)

# PCIe 12-Channel Pulse Width Modulation Output Card (PWM)

<i>Driver</i>	ccurpwm (WC-PWM-1012)	
<i>Platform</i>	RedHawk Linux® (CentOS/Rocky/RHEL & Ubuntu), Native Ubuntu® and Native Red Hat Enterprise Linux® <sup>1</sup>	
<i>Vendor</i>	Concurrent Real-Time	
<i>Hardware</i>	PCIe 12-Channel Pulse Width Modulation Output Card (CP-PWM-1012)	
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# 1. Introduction

This document provides the software interface to the **ccurpwm** driver which communicates with the Concurrent Real-Time PCI Express 12-Channel Pulse Width Modulation Output Card (CP-PWM-1012).

The software package that accompanies this board provides the ability for advanced users to communicate directly with the board via the driver *ioctl(2)* and *mmap(2)* system calls. When programming in this mode, the user needs to be intimately familiar with both the hardware and the register programming interface to the board. Failure to adhere to correct programming will result in unpredictable results.

Additionally, the software package is accompanied with an extensive set of application programming interface (API) calls that allow the user to access all capabilities of the board. The API allows the user the ability to communicate directly with the board through the *ioctl(2)* and *mmap(2)* system calls. In this case, there is a risk of conflicting with API calls and therefore should only be used by advanced users who are intimately familiar with, the hardware, board registers and the driver code.

Various example tests have been provided in the *test* directories to assist the user in writing their applications.

## 1.1 Related Documents

- Pulse Width Output Card Installation on RedHawk Release Notes by Concurrent Real-Time.

## 2. Software Support

Software support is provided for users to communicate directly with the board using the kernel system calls (*Direct Driver Access*) or the supplied *API*. Both approaches are identified below to assist the user in software development.

### 2.1 Direct Driver Access

#### 2.1.1 open(2) system call

In order to access the board, the user first needs to open the device using the standard system call *open(2)*.

```
int    fp;
fp = open("/dev/ccurpwm0", O_RDWR);
```

The file pointer '*fp*' is then used as an argument to other system calls. The device name specified is of the format "/dev/ccurpwm<num>" where *num* is a digit 0..9 which represents the board number that is to be accessed.

#### 2.1.2 ioctl(2) system call

This system call provides the ability to control and get responses from the board. The nature of the control/response will depend on the specific *ioctl* command.

```
int    status;
int    arg;
status = ioctl(fp, <IOCTL_COMMAND>, &arg);
```

where '*fp*' is the file pointer that is returned from the *open(2)* system call. *<IOCTL\_COMMAND>* is one of the *ioctl* commands below and *arg* is a pointer to an argument that could be anything and is dependent on the command being invoked. If no argument is required for a specific command, then set to *NULL*.

Driver IOCTL command:

```
IOCTL_CCURPWM_ADD_IRQ
IOCTL_CCURPWM_DISABLE_PCI_INTERRUPTS
IOCTL_CCURPWM_ENABLE_PCI_INTERRUPTS
IOCTL_CCURPWM_GET_DRIVER_ERROR
IOCTL_CCURPWM_GET_DRIVER_INFO
IOCTL_CCURPWM_GET_PHYSICAL_MEMORY
IOCTL_CCURPWM_INIT_BOARD
IOCTL_CCURPWM_MAIN_CONTROL_REGISTERS
IOCTL_CCURPWM_MMAP_SELECT
IOCTL_CCURPWM_NO_COMMAND
IOCTL_CCURPWM_PCI_BRIDGE_REGISTERS
IOCTL_CCURPWM_PCI_CONFIG_REGISTERS
IOCTL_CCURPWM_REMOVE_IRQ
IOCTL_CCURPWM_RESET_BOARD
```

*IOCTL\_CCURPWM\_ADD\_IRQ*: This *ioctl* does not have any arguments. Its purpose is to setup the driver interrupt handler to handle interrupts. This driver currently does not use interrupts for DMA and hence there is no need to use this call. This *ioctl* is only invoked if the user has issued the *IOCTL\_CCURPWM\_REMOVE\_IRQ* call earlier to remove the interrupt handler.

*IOCTL\_CCURPWM\_DISABLE\_PCI\_INTERRUPTS*: This *ioctl* does not have any arguments. Currently, it does not perform any operation.

*IOCTL\_CCURPWM\_ENABLE\_PCI\_INTERRUPTS*: This *ioctl* does not have any arguments. Currently, it does not perform any operation.

*IOCTL\_CCURPWM\_GET\_DRIVER\_ERROR*: The argument supplied to this *ioctl* is a pointer to the *ccurpwm\_user\_error\_t* structure. Information on the structure is located in the *ccurpwm\_user.h* include file. The error returned is the last reported error by the driver. If the argument pointer is *NULL*, the current error is reset to *CCURPWM\_SUCCESS*.

*IOCTL\_CCURPWM\_GET\_DRIVER\_INFO*: The argument supplied to this *ioctl* is a pointer to the *ccurpwm\_ccurpwm\_driver\_info\_t* structure. Information on the structure is located in the *ccurpwm\_user.h* include file. This *ioctl* provides useful driver information.

*IOCTL\_CCURPWM\_GET\_PHYSICAL\_MEMORY*: The argument supplied to this *ioctl* is a pointer to the *ccurpwm\_phys\_mem\_t* structure. Information on the structure is located in the *ccurpwm\_user.h* include file. If physical memory is not allocated, the call will fail, otherwise, the call will return the physical memory address and size in bytes. The only reason to request and get physical memory from the driver is to allow the user to perform DMA operations and bypass the driver and library. Care must be taken when performing user-level DMA as incorrect programming could lead to unpredictable results including but not limited to corrupting the kernel and any device connected to the system.

*IOCTL\_CCURPWM\_INIT\_BOARD*: This *ioctl* does not have any arguments. This call resets the board to a known initial default state. This call is currently identical to the *IOCTL\_CCURPWM\_RESET\_BOARD* call.

*IOCTL\_CCURPWM\_MAIN\_CONTROL\_REGISTERS*: This *ioctl* dumps all the PCI Main Control registers and is mainly used for debug purpose. The argument to this *ioctl* is a pointer to the

*ccurpwm\_main\_control\_register\_t* structure. Raw 32-bit data values are read from the board and loaded into this structure.

**IOCTL\_CCURPWM\_MMAP\_SELECT:** The argument to this *ioctl* is a pointer to the *ccurpwm\_mmap\_select\_t* structure. Information on the structure is located in the *ccurpwm\_user.h* include file. This call needs to be made prior to the *mmap(2)* system call so as to direct the *mmap(2)* call to perform the requested mapping specified by this *ioctl*. The three possible mappings that are performed by the driver are to *mmap* the local register space (*CCURPWM\_SELECT\_LOCAL\_MMAP*), the configuration register space (*CCURPWM\_SELECT\_CONFIG\_MMAP*) and a physical memory (*CCURPWM\_SELECT\_PHYS\_MEM\_MMAP*) that is created by the *mmap(2)* system call.

**IOCTL\_CCURPWM\_NO\_COMMAND:** This *ioctl* does not have any arguments. It is only provided for debugging purpose and should not be used as it serves no purpose for the user.

**IOCTL\_CCURPWM\_PCI\_BRIDGE\_REGISTERS:** This *ioctl* dumps all the PCI bridge registers and is mainly used for debug purpose. The argument to this *ioctl* is a pointer to the *ccurpwm\_pci\_bridge\_register\_t* structure. Raw 32-bit data values are read from the board and loaded into this structure.

**IOCTL\_CCURPWM\_PCI\_CONFIG\_REGISTERS:** This *ioctl* dumps all the PCI configuration registers and is mainly used for debug purpose. The argument to this *ioctl* is a pointer to the *ccurpwm\_pci\_config\_reg\_addr\_mapping\_t* structure. Raw 32-bit data values are read from the board and loaded into this structure.

**IOCTL\_CCURPWM\_REMOVE\_IRQ:** This *ioctl* does not have any arguments. Its purpose is to remove the interrupt handler that was previously setup. This driver currently does not use interrupts for DMA and hence there is no need to use this call. The user should not issue this call, otherwise, reads will time out.

**IOCTL\_CCURPWM\_RESET\_BOARD:** This *ioctl* does not have any arguments. This call resets the board to a known initial default state. This call is currently identical to the *IOCTL\_CCURPWM\_INIT\_BOARD* call.

## 2.1.3 mmap(2) system call

This system call provides the ability to map either the local board registers, the configuration board registers or create and map a physical memory that can be used for user DMA. Prior to making this system call, the user needs to issue the *ioctl(2)* system call with the *IOCTL\_CCURPWM\_MMAP\_SELECT* command. When mapping either the local board registers or the configuration board registers, the *ioctl* call returns the size of the register mapping which needs to be specified in the *mmap(2)* call. In the case of mapping a physical memory, the size of physical memory to be created is supplied to the *mmap(2)* call.

```
int *munmap_local_ptr;
ccurpwm_local_ctrl_data_t *local_ptr;
ccurpwm_mmap_select_t mmap_select;
unsigned long mmap_local_size;

mmap_select.select = CCURPWM_SELECT_LOCAL_MMAP;
mmap_select.offset=0;
mmap_select.size=0;

ioctl(fp, IOCTL_CCURPWM_MMAP_SELECT, (void *)&mmap_select);
mmap_local_size = mmap_select.size;
```

```

munmap_local_ptr = (int *) mmap((caddr_t)0, map_local_size,
                                (PROT_READ|PROT_WRITE), MAP_SHARED, fp, 0);

local_ptr = (ccurpwm_local_ctrl_data_t *)munmap_local_ptr;
local_ptr = (ccurpwm_local_ctrl_data_t *)((char *)local_ptr +
                                           mmap_select.offset);

if(munmap_local_ptr != NULL)
    munmap((void *)munmap_local_ptr, mmap_local_size);

```

## 2.2 Application Program Interface (API) Access

The API is the recommended method of communicating with the board for most users. The following are a list of calls that are available.

```

Ccurpwm_Add_Irq()
Ccurpwm_Clear_Driver_Error()
Ccurpwm_Clear_Lib_Error()
Ccurpwm_Close()
Ccurpwm_Disable_Pci_Interrupts()
Ccurpwm_Enable_Pci_Interrupts()
Ccurpwm_Fast_Memcpy()
Ccurpem_Fast_Memcpy_Unlocked()
Ccurpwm_Get_Driver_Error()
Ccurpwm_Get_Info()
Ccurpwm_Get_Lib_Error_Description()
Ccurpwm_Get_Lib_Error()
Ccurpwm_Get_Mapped_Config_Ptr()
Ccurpwm_Get_Mapped_Local_Ptr()
Ccurpwm_Get_Physical_Memory()
Ccurpwm_Get_PWM()
Ccurpwm_Get_PWM_Individual()
Ccurpwm_Get_Value()
Ccurpwm_Initialize_Board()
Ccurpwm_MMap_Physical_Memory()
Ccurpwm_Munmap_Physical_Memory()
Ccurpwm_NanoDelay()
Ccurpwm_Open()
ccurpwm_PWM_Resync()
Ccurpwm_Read()
Ccurpwm_Remove_Irq()
Ccurpwm_Reset_Board()
ccurpwm_Set_PWM()
Ccurpwm_Set_PWM_Individual()
Ccurpwm_Set_Value()
Ccurpwm_Write()

```

### 2.2.1 Ccurpwm\_Add\_Irq()

This call will add the driver interrupt handler if it has not been added. Normally, the user should not use this call unless they want to disable the interrupt handler and then re-enable it.

```

/*****
int Ccurpwm_Add_Irq(void *Handle)

```

Description: By default, the driver assigns an interrupt handler to handle device interrupts. If the interrupt handler was removed using the Ccurpwm\_Remove\_Irq(), then this call adds it back.

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```

Input:      void *Handle                (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR        (successful)
           CCURPWM_LIB_BAD_HANDLE      (no/bad handler supplied)
           CCURPWM_LIB_NOT_OPEN        (device not open)
           CCURPWM_LIB_IOCTL_FAILED    (driver ioctl call failed)
*****/

```

## 2.2.2 Ccurpwm\_Clear\_Driver\_Error()

This call resets the last driver error that was maintained internally by the driver to *CCURPWM\_SUCCESS*.

```

/*****
int Ccurpwm_Clear_Driver_Error(void *Handle)

Description: Clear any previously generated driver related error.

Input:      void *Handle                (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR        (successful)
           CCURPWM_LIB_BAD_HANDLE      (no/bad handler supplied)
           CCURPWM_LIB_NOT_OPEN        (device not open)
           CCURPWM_LIB_IOCTL_FAILED    (driver ioctl call failed)
*****/

```

## 2.2.3 Ccurpwm\_Clear\_Lib\_Error()

This call resets the last library error that was maintained internally by the API.

```

/*****
int Ccurpwm_Clear_Lib_Error(void *Handle)

Description: Clear any previously generated library related error.

Input:      void *Handle                (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR        (successful)
           CCURPWM_LIB_BAD_HANDLE      (no/bad handler supplied)
           CCURPWM_LIB_NOT_OPEN        (device not open)
*****/

```

## 2.2.4 Ccurpwm\_Close()

This call is used to close an already opened device using the *Ccurpwm\_Open()* call.

```

/*****
int Ccurpwm_Close(void *Handle)

Description: Close a previously opened device.

Input:      void *Handle                (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR        (successful)
           CCURPWM_LIB_BAD_HANDLE      (no/bad handler supplied)
           CCURPWM_LIB_NOT_OPEN        (device not open)
*****/

```

## 2.2.5 Ccurpwm\_Disable\_Pci\_Interrupts()

The purpose of this call is to disable PCI interrupts. Currently, this call performs no action.

```

/*****
int Ccurpwm_Disable_Pci_Interrupts(void *Handle)

Description: Disable interrupts being generated by the board.

Input:      void *Handle          (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR   (successful)
           CCURPWM_LIB_BAD_HANDLE (no/bad handler supplied)
           CCURPWM_LIB_NOT_OPEN   (device not open)
           CCURPWM_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/
```

## 2.2.6 Ccurpwm\_Enable\_Pci\_Interrupts()

The purpose of this call is to enable PCI interrupts. Currently, this call performs no action.

```

/*****
int Ccurpwm_Enable_Pci_Interrupts(void *Handle)

Description: Enable interrupts being generated by the board.

Input:      void *Handle          (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR   (successful)
           CCURPWM_LIB_BAD_HANDLE (no/bad handler supplied)
           CCURPWM_LIB_NOT_OPEN   (device not open)
           CCURPWM_LIB_IOCTL_FAILED (driver ioctl call failed)
*****/
```

## 2.2.7 Ccurpwm\_Fast\_Memcpy()

The purpose of this call is to provide a fast mechanism to copy between hardware and memory using programmed I/O. The library performs appropriate locking while the copying is taking place.

```

/*****
Ccurpwm_Fast_Memcpy()

Description: Perform fast copy to/from buffer using Programmed I/O
            (WITH LOCKING)

Input:      void *Handle          (handle pointer)
            volatile void *Source (pointer to source buffer)
            int SizeInBytes       (transfer size in bytes)
Output:     volatile void *Destination (pointer to destination buffer)
Return:     _ccurpwm_lib_error_number_t
            - CCURPWM_LIB_NO_ERROR   (successful)
            - CCURPWM_LIB_BAD_HANDLE (no/bad handler supplied)
            - CCURPWM_LIB_NOT_OPEN   (device not open)
*****/
```

## 2.2.8 Ccurpwm\_Fast\_Memcpy\_Unlocked()

The purpose of this call is to provide a fast mechanism to copy between hardware and memory using programmed I/O. The library does not perform any locking. User needs to provide external locking instead.

```

/*****
Ccurpwm_Fast_Memcpy_Unlocked()

Description: Perform fast copy to/from buffer using Programmed I/O
             (WITHOUT LOCKING)

Input:      volatile void *Source      (pointer to source buffer)
            int              SizeInBytes (transfer size in bytes)
Output:     volatile void *Destination (pointer to destination buffer)
Return:     None
*****/

```

## 2.2.9 Ccurpwm\_Get\_Driver\_Error()

This call returns the last error generated by the driver.

```

/*****
int Ccurpwm_Get_Driver_Error(void *Handle, ccurpwm_user_error_t *ret_err)

Description: Get the last error generated by the driver.

Input:      void *Handle                (handle pointer)
Output:     ccurpwm_user_error_t *ret_err (error struct pointer)
Return:     CCURPWM_LIB_NO_ERROR        (successful)
            CCURPWM_LIB_BAD_HANDLE      (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN        (device not open)
            CCURPWM_LIB_INVALID_ARG     (invalid argument)
            CCURPWM_LIB_IOCTL_FAILED    (driver ioctl call failed)
*****/

#define CCURPWM_ERROR_NAME_SIZE    64
#define CCURPWM_ERROR_DESC_SIZE    128
typedef struct _ccurpwm_user_error_t {
    uint    error;                /* error number */
    char    name[CCURPWM_ERROR_NAME_SIZE]; /* error name used in driver */
    char    desc[CCURPWM_ERROR_DESC_SIZE]; /* error description */
} ccurpwm_user_error_t;

enum {
    CCURPWM_SUCCESS = 0,
    CCURPWM_INVALID_PARAMETER,
    CCURPWM_TIMEOUT,
    CCURPWM_OPERATION_CANCELLED,
    CCURPWM_RESOURCE_ALLOCATION_ERROR,
    CCURPWM_INVALID_REQUEST,
    CCURPWM_FAULT_ERROR,
    CCURPWM_BUSY,
    CCURPWM_ADDRESS_IN_USE,
    CCURPWM_DMA_TIMEOUT,
};

```

## 2.2.10 Ccurpwm\_Get\_Info()

This call returns internal information that is maintained by the driver.

```

/*****
int Ccurpwm_Get_Info(void *Handle,  ccurpwm_driver_info_t *info)

Description: Get device information from driver.

Input:      void *Handle          (handle pointer)
Output:     ccurpwm_driver_info_t *info  (info struct pointer)
-- char info.version
-- char *info.built
-- char *info.module_name[16]
-- int  info.board_type
-- char *info.board_desc[32]
-- int  info.bus
-- int  info.slot
-- int  info.func
-- int  info.vendor_id
-- int  info.device_id
-- int  info.board_id
-- int  info.firmware
-- int  info.interrupt_count
-- U_int info.mem_region[].physical_address
-- U_int info.mem_region[].size
-- U_int info.mem_region[].flags
-- U_int info.mem_region[].virtual_address
Return:     CCURPWM_LIB_NO_ERROR          (successful)
            CCURPWM_LIB_BAD_HANDLE       (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN        (device not open)
            CCURPWM_LIB_INVALID_ARG     (invalid argument)
            CCURPWM_LIB_IOCTL_FAILED    (driver ioctl call failed)
*****/

typedef struct
{
    uint    physical_address;
    uint    size;
    uint    flags;
    uint    *virtual_address;
} ccurpwm_dev_region_t;

#define CCURPWM_MAX_REGION 32

typedef struct
{
    char            version[12];          /* driver version */
    char            built[32];            /* driver date built */
    char            module_name[16];      /* driver name */
    int             board_type;           /* board type */
    char            board_desc[32];       /* board description */
    int             bus;                  /* bus number */
    int             slot;                 /* slot number */
    int             func;                 /* function number */
    int             vendor_id;            /* vendor id */
    int             device_id;            /* device id */
    int             board_id;             /* board id */
    int             firmware;             /* firmware number if applicable*/
    int             interrupt_count;      /* interrupt count */
    int             Ccurpwm_Max_Region; /*kernel DEVICE_COUNT_RESOURCE*/

    ccurpwm_dev_region_t mem_region[CCURPWM_MAX_REGION];
} ccurpwm_driver_info_t;

```

## 2.2.11 Ccurpwm\_Get\_Lib\_Error\_Description()

This call returns the library error name and description for the supplied error number.

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```

/*****

Ccurpwm_Get_Lib_Error_Description()

Description: Get Error Description of supplied error number.

Input:   int      ErrorNumber      (Library error number)
Output:  ccurpwm_lib_error_description_t  *lib_error_desc  (error description struct pointer)
        -- int found
        -- char name[CCURPWM_LIB_ERROR_NAME_SIZE] (last library error name)
        -- char desc[CCURPWM_LIB_ERROR_DESC_SIZE] (last library error description)

Return:  none

*****/

```

## 2.2.12 Ccurpwm\_Get\_Lib\_Error()

This call provides detailed information about the last library error that was maintained by the API.

```

/*****

int Ccurpwm_Get_Lib_Error(void *Handle, ccurpwm_lib_error_t *lib_error)

Description: Get last error generated by the library.

Input:      void *Handle      (handle pointer)
Output:     ccurpwm_lib_error_t *lib_error (error struct pointer)
        -- uint error      (error number)
        -- char name[CCURPWM_LIB_ERROR_NAME_SIZE] (error name)
        -- char desc[CCURPWM_LIB_ERROR_DESC_SIZE] (error description)
        -- int line_number      (error line number in lib)
        -- char function[CCURPWM_LIB_ERROR_FUNC_SIZE]
                                (library function in error)

Return:     CCURPWM_LIB_BAD_HANDLE      (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN      (device not open)
            Last Library Error

*****/

typedef struct _ccurpwm_lib_error_t {
    uint    error;                /* lib error number */
    char    name[CCURPWM_LIB_ERROR_NAME_SIZE]; /* error name used in lib */
    char    desc[CCURPWM_LIB_ERROR_DESC_SIZE]; /* error description */
    int     line_number;          /* line number in library */
    char    function[CCURPWM_LIB_ERROR_FUNC_SIZE];
                                /* library function */
} ccurpwm_lib_error_t;

```

## 2.2.13 Ccurpwm\_Get\_Mapped\_Config\_Ptr()

If the user wishes to bypass the API and communicate directly with the board configuration registers, then they can use this call to acquire a pointer to these registers. Please note that any type of access (read or write) by bypassing the API could compromise the API and results could be unpredictable. It is recommended that only advanced users should use this call and with extreme care and intimate knowledge of the hardware programming registers before attempting to access these registers. For information on the registers, refer to the *ccurpwm\_user.h* include file that is supplied with the driver.

```

/*****

int Ccurpwm_Get_Mapped_Config_Ptr(void *Handle,
                                ccurpwm_config_local_data_t **config_ptr)

Description: Get mapped configuration pointer.

```

```

Input:      void *Handle                (handle pointer)
Output:     ccurpwm_config_local_data_t **config_ptr (config struct ptr)
            -- structure in ccurpwm_user.h
Return:     CCURPWM_LIB_NO_ERROR          (successful)
            CCURPWM_LIB_BAD_HANDLE        (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN          (device not open)
            CCURPWM_LIB_INVALID_ARG       (invalid argument)
            CCURPWM_LIB_NO_CONFIG_REGION  (config region not present)
*****

```

## 2.2.14 Ccurpwm\_Get\_Mapped\_Local\_Ptr()

If the user wishes to bypass the API and communicate directly with the board control and data registers, then they can use this call to acquire a pointer to these registers. Please note that any type of access (read or write) by bypassing the API could compromise the API and results could be unpredictable. It is recommended that only advanced users should use this call and with extreme care and intimate knowledge of the hardware programming registers before attempting to access these registers. For information on the registers, refer to the *ccurpwm\_user.h* include file that is supplied with the driver.

```

/*****
int Ccurpwm_Get_Mapped_Local_Ptr(void *Handle,
                                ccurpwm_local_ctrl_data_t **local_ptr)

Description: Get mapped local pointer.

Input:      void *Handle                (handle pointer)
Output:     ccurpwm_local_ctrl_data_t **local_ptr (local struct ptr)
            -- structure in ccurpwm_user.h
Return:     CCURPWM_LIB_NO_ERROR          (successful)
            CCURPWM_LIB_BAD_HANDLE        (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN          (device not open)
            CCURPWM_LIB_INVALID_ARG       (invalid argument)
            CCURPWM_LIB_NO_LOCAL_REGION   (local region not present)
*****

```

## 2.2.15 Ccurpwm\_Get\_Physical\_Memory()

This call returns to the user the physical memory pointer and size that was previously allocated by the *Ccurpwm\_Mmap\_Physical\_Memory()* call. The physical memory is allocated by the user when they wish to perform their own DMA and bypass the API. Once again, this call is only useful for advanced users.

```

/*****
int Ccurpwm_Get_Physical_Memory(void *Handle,
                                ccurpwm_phys_mem_t *phys_mem)

Description: Get previously mmaped() physical memory address and size

Input:      void *Handle                (handle pointer)
Output:     ccurpwm_phys_mem_t *phys_mem (mem struct pointer)
            -- void *phys_mem
            -- u_int phys_mem_size
Return:     CCURPWM_LIB_NO_ERROR          (successful)
            CCURPWM_LIB_BAD_HANDLE        (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN          (device not open)

```

```

        CCURPWM_LIB_INVALID_ARG          (invalid argument)
        CCURPWM_LIB_IOCTL_FAILED         (driver ioctl call failed)
    *****/

typedef struct {
    void          *phys_mem;             /* physical memory: physical address */
    unsigned int   phys_mem_size;        /* physical memory: memory size - bytes */
} ccurpwm_phys_mem_t;

```

## 2.2.16 Ccurpwm\_Get\_PWM()

This call returns to the user information about a specified wave. The user can specify either CCURPWM\_WAVE\_A or CCURPWM\_WAVE\_B.

```

/*****

    int Ccurpwm_Get_PWM(void *Handle, CCURPWM_WAVE wave, ccurpwm_wave_t *value)

    Description: Return the wave settings of the specified wave.

    Input:        void          *Handle          (handle pointer)
                  CCURPWM_WAVE   wave           (which wave)
    Output:        ccurpwm_wave_t *value;        (pointer to value)
    Return:        CCURPWM_LIB_NO_ERROR          (successful)
                  CCURPWM_LIB_BAD_HANDLE       (no/bad handler supplied)
                  CCURPWM_LIB_NOT_OPEN         (device not open)
                  CCURPWM_LIB_INVALID_ARG      (invalid argument)

    *****/

typedef enum {
    CCURPWM_WAVE_A=1,
    CCURPWM_WAVE_B,
} CCURPWM_WAVE;

typedef struct
{
    u_int32_t    pwm_sine_frequency;          /* sine frequency */
    u_int32_t    pwm_phase_1;                 /* phase 1 - 0 to 360 degrees */
    u_int32_t    pwm_phase_2;                 /* phase 2 - 0 to 360 degrees */
    u_int32_t    pwm_phase_3;                 /* phase 3 - 0 to 360 degrees */
    u_int32_t    pwm_deadband;                /* deadband */
    u_int32_t    pwm_PWM_frequency;           /* PWM frequency */
} _ccurpwm_raw_wave_t;

typedef struct
{
    double       pwm_sine_frequency;          /* sine frequency */
    double       pwm_phase_1;                 /* phase 1 - 0 to 360 degrees */
    double       pwm_phase_2;                 /* phase 2 - 0 to 360 degrees */
    double       pwm_phase_3;                 /* phase 3 - 0 to 360 degrees */
    u_int32_t    pwm_deadband;                /* deadband */
    double       pwm_PWM_frequency;           /* PWM frequency */
    _ccurpwm_raw_wave_t raw;                 /* raw data structure */
} ccurpwm_wave_t;

```

## 2.2.17 Ccurpwm\_Get\_PWM\_Individual()

This call allows the user to get the individual frequency and duty cycle.

```

/*****
  int Ccurpwm_Get_PWM_Individual(void *Handle, u_int32_t select,
                                ccurpwm_individual_t *value)

  Description: Return the individual settings of the specified entry.

  Input:      void      *Handle      (handle pointer)
              u_int32_t  select      (which individual)
  Output:     ccurpwm_individual_t *value; (pointer to value)
  Return:     CCURPWM_LIB_NO_ERROR      (successful)
              CCURPWM_LIB_BAD_HANDLE   (no/bad handler supplied)
              CCURPWM_LIB_NOT_OPEN     (device not open)
              CCURPWM_LIB_INVALID_ARG  (invalid argument)
*****/

```

Select ranges from 0 to (PWM\_MAX\_PWM\_FREQ\_REGS-1) individual channels.

```

typedef struct
{
    u_int32_t  pwm_PWM_frequency;    /* PWM frequency */
    u_int32_t  pwm_duty;             /* duty cycle - 0 - 100% */
} _ccurpwm_raw_individual_t;

typedef struct
{
    double  pwm_PWM_frequency;    /* PWM frequency */
    double  pwm_duty;             /* duty cycle - 0 - 100% */
    _ccurpwm_raw_individual_t raw; /* raw data structure */
} ccurpwm_individual_t;

```

## 2.2.18 Ccurpwm\_Get\_Value()

This call allows the user to read the board registers. The actual data returned will depend on the command register information that is requested. Refer to the hardware manual for more information on what is being returned. Most commands return a pointer to an unsigned integer.

```

/*****
  int Ccurpwm_Get_Value(void *Handle, CCURPWM_CONTROL cmd, void *value)

  Description: Return the value of the specified board register.

  Input:      void      *Handle      (handle pointer)
              CCURPWM_CONTROL  cmd      (register definition)
  Output:     void      *value;      (pointer to value)
  Return:     CCURPWM_LIB_NO_ERROR      (successful)
              CCURPWM_LIB_BAD_HANDLE   (no/bad handler supplied)
              CCURPWM_LIB_NOT_OPEN     (device not open)
              CCURPWM_LIB_INVALID_ARG  (invalid argument)
              CCURPWM_LIB_NO_LOCAL_REGION (local region not present)
*****/

typedef enum {
    CCURPWM_STATUS,
    CCURPWM_REVISION,

```



```

CCURPWM_RESYNC,
CCURPWM_MODE,

CCURPWM_A_SINE_FREQUENCY,
CCURPWM_A_PHASE_1,
CCURPWM_A_PHASE_2,
CCURPWM_A_PHASE_3,
CCURPWM_A_DEADBAND,
CCURPWM_A_PWM_FREQUENCY,

CCURPWM_B_SINE_FREQUENCY,
CCURPWM_B_PHASE_1,
CCURPWM_B_PHASE_2,
CCURPWM_B_PHASE_3,
CCURPWM_B_DEADBAND,
CCURPWM_B_PWM_FREQUENCY,

CCURPWM_INDIV0_PWM_FREQUENCY,
CCURPWM_INDIV0_DUTY,
CCURPWM_INDIV1_PWM_FREQUENCY,
CCURPWM_INDIV1_DUTY,
CCURPWM_INDIV2_PWM_FREQUENCY,
CCURPWM_INDIV2_DUTY,
CCURPWM_INDIV3_PWM_FREQUENCY,
CCURPWM_INDIV3_DUTY,
CCURPWM_INDIV4_PWM_FREQUENCY,
CCURPWM_INDIV4_DUTY,
CCURPWM_INDIV5_PWM_FREQUENCY,
CCURPWM_INDIV5_DUTY,
CCURPWM_INDIV6_PWM_FREQUENCY,
CCURPWM_INDIV6_DUTY,
CCURPWM_INDIV7_PWM_FREQUENCY,
CCURPWM_INDIV7_DUTY,
CCURPWM_INDIV8_PWM_FREQUENCY,
CCURPWM_INDIV8_DUTY,
CCURPWM_INDIV9_PWM_FREQUENCY,
CCURPWM_INDIV9_DUTY,
CCURPWM_INDIV10_PWM_FREQUENCY,
CCURPWM_INDIV10_DUTY,
CCURPWM_INDIV11_PWM_FREQUENCY,
CCURPWM_INDIV11_DUTY,
} CCURPWM_CONTROL;

```

## 2.2.19 Ccurpwm\_Initialize\_Board()

This call resets the board to a default initial state. This call is currently identical to the *Ccurpwm\_Reset\_Board()* call.

```

/*****
int Ccurpwm_Initialize_Board(void *Handle)

Description: Initialize the board.

Input:      void *Handle      (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR      (successful)
            CCURPWM_LIB_BAD_HANDLE    (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN      (device not open)
            CCURPWM_LIB_IOCTL_FAILED  (driver ioctl call failed)
            CCURPWM_LIB_NO_LOCAL_REGION (local region not present)
*****/

```

## 2.2.20 Ccurpwm\_MMap\_Physical\_Memory()

This call is provided for advanced users to create a physical memory of specified size that can be used for DMA. The allocated DMA memory is rounded to a page size. If a physical memory has been previously allocated, this call will fail, at which point the user will need to issue the *Ccurpwm\_Munmap\_Physical\_Memory()* API call to remove the previously allocated physical memory.

```

/*****
int Ccurpwm_MMap_Physical_Memory(void *Handle, int size, void **mem_ptr)

Description: Allocate a physical DMA memory for size bytes.
Input:      void *Handle          (handle pointer)
            int size              (size in bytes)
Output:     void **mem_ptr        (mapped memory pointer)
Return:     CCURPWM_LIB_NO_ERROR   (successful)
            CCURPWM_LIB_BAD_HANDLE (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN   (device not open)
            CCURPWM_LIB_INVALID_ARG (invalid argument)
            CCURPWM_LIB_MMAP_SELECT_FAILED (mmap selection failed)
            CCURPWM_LIB_MMAP_FAILED (mmap failed)
*****/
```

## 2.2.21 Ccurpwm\_Munmap\_Physical\_Memory()

This call simply removes a physical memory that was previously allocated by the *Ccurpwm\_MMap\_Physical\_Memory()* API call.

```

/*****
int Ccurpwm_Munmap_Physical_Memory(void *Handle)

Description: Unmap a previously mapped physical DMA memory.

Input:      void *Handle          (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR   (successful)
            CCURPWM_LIB_BAD_HANDLE (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN   (device not open)
            CCURPWM_LIB_MUNMAP_FAILED (failed to un-map memory)
            CCURPWM_LIB_NOT_MAPPED (memory not mapped)
*****/
```

## 2.2.22 Ccurpwm\_NanoDelay()

This call simply delays (loops) for user specified nanoseconds.

```

/*****
void Ccurpwm_NanoDelay(unsigned long long NanoDelay)

Description: Delay )loop for user specified nanoseconds.

Input:      unsigned long long NanoDelay      (number of nano-secs to delay)
Output:     None
Return:     None
*****/
```

## 2.2.23 Ccurpwm\_Open()

This is the first call that needs to be issued by a user to open a device and access the board through the rest of the API calls. What is returned is a handle to a *void pointer* that is supplied as an argument to the other API calls. The *Board\_Number* is a valid board number [0..9] that is associated with a physical card. There must exist a character special file */dev/ccurpwm<Board\_Number>* for the call to be successful. One character special file is created for each board found when the driver is successfully loaded.

The *oflag* is the flag supplied to the *open(2)* system call by this API. It is normally a 0, however, the user may use the *O\_NONBLOCK* option for *read(2)* calls which will change the default reading in block mode.

```
/******
int Ccurpwm_Open(void **My_Handle, int Board_Number, int oflag)

Description: Open a device.
Input:      void **Handle      (handle pointer to pointer)
            int Board_Number    (0-9 board number)
            int oflag           (open flags)

Output:     None

Return:     CCURPWM_LIB_NO_ERROR      (successful)
            CCURPWM_LIB_INVALID_ARG   (invalid argument)
            CCURPWM_LIB_ALREADY_OPEN  (device already opened)
            CCURPWM_LIB_OPEN_FAILED   (device open failed)
            CCURPWM_LIB_ALREADY_MAPPED (memory already mmapmed)
            CCURPWM_LIB_MMAP_SELECT_FAILED (mmap selection failed)
            CCURPWM_LIB_MMAP_FAILED   (mmap failed)
*****/
```

## 2.2.24 Ccurpwm\_PWM\_Resync()

This call issues a Resync command to the PWM.

```
/******
Ccurpwm_PWM_Resync()

Description: Issue resync command to the PWM

Input:      void *Handle      (handle pointer)
Return:     CCURPWM_LIB_NO_ERROR      (successful)
            CCURPWM_LIB_BAD_HANDLE    (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN      (device not open)
            CCURPWM_LIB_INVALID_ARG   (invalid argument)
*****/
```

## 2.2.25 Ccurpwm\_Read()

This call is not supported for this card.

```
/******
int Ccurpwm_Read(void *Handle, void *buf, int size, int *bytes_read,
                int *error)

Description: Perform a read operation.

Input:      void *Handle      (handle pointer)
            int size          (size of buffer in bytes)
Output:     void *buf         (pointer to buffer)
```

	int *bytes_read	(bytes read)
	int *error	(returned errno)
Return:	CCURPWM_LIB_NO_ERROR	(successful)
	CCURPWM_LIB_BAD_HANDLE	(no/bad handler supplied)
	CCURPWM_LIB_NOT_OPEN	(device not open)
	CCURPWM_LIB_IO_ERROR	(read failed)
	CCURPWM_LIB_FIFO_OVERFLOW	(FIFO overflow)

\*\*\*\*\*/

## 2.2.26 Ccurpwm\_Remove\_Irq()

The purpose of this call is to remove the interrupt handler that was previously set up. The interrupt handler is managed internally by the driver and the library. The user should not issue this call, otherwise, reads will time out.

```

/*****
int Ccurpwm_Remove_Irq(void *Handle)

Description: By default, the driver sets up a shared IRQ interrupt handler
when the device is opened. Now if for any reason, another
device is sharing the same IRQ as this driver, the interrupt
handler will also be entered every time the other shared
device generates an interrupt. There are times that a user,
for performance reasons may wish to run the board without
interrupts enabled. In that case, they can issue this ioctl
to remove the interrupt handling capability from the driver.

Input:      void *Handle      (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR      (successful)
            CCURPWM_LIB_BAD_HANDLE    (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN      (device not open)
            CCURPWM_LIB_IOCTL_FAILED  (driver ioctl call failed)
*****/

```

## 2.2.27 Ccurpwm\_Reset\_Board()

This call resets the board to a known initial default state. Additionally, the Converters, Clocks, and FIFO are reset along with internal pointers and clearing of interrupts. This call is currently identical to the *Ccurpwm\_Initialize\_Board()* call.

```

/*****
int Ccurpwm_Reset_Board(void *Handle)

Description: Reset the board.

Input:      void *Handle      (handle pointer)
Output:     None
Return:     CCURPWM_LIB_NO_ERROR      (successful)
            CCURPWM_LIB_BAD_HANDLE    (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN      (device not open)
            CCURPWM_LIB_IOCTL_FAILED  (driver ioctl call failed)
            CCURPWM_LIB_NO_LOCAL_REGION (local region not present)
*****/

```

## 2.2.28 Ccurpwm\_Set\_PWM()

This call sets information for the specified wave.

```

/*****
int Ccurpwm_Set_PWM(void *Handle, CCURPWM_WAVE wave, ccurpwm_wave_t *value)

Description: Set the wave parameters for the specified wave.

Input:      void      *Handle      (handle pointer)
            CCURPWM_WAVE wave      (which wave)
            ccurpwm_wave_t *value;  (pointer to value)
Return:     CCURPWM_LIB_NO_ERROR    (successful)
            CCURPWM_LIB_BAD_HANDLE  (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN    (device not open)
            CCURPWM_LIB_INVALID_ARG (invalid argument)
*****/

typedef enum {
    CCURPWM_WAVE_A=1,
    CCURPWM_WAVE_B,
} CCURPWM_WAVE;

typedef struct
{
    u_int32_t  pwm_sine_frequency;    /* sine frequency */
    u_int32_t  pwm_phase_1;           /* phase 1 - 0 to 360 degrees */
    u_int32_t  pwm_phase_2;           /* phase 2 - 0 to 360 degrees */
    u_int32_t  pwm_phase_3;           /* phase 3 - 0 to 360 degrees */
    u_int32_t  pwm_deadband;          /* deadband */
    u_int32_t  pwm_PWM_frequency;     /* PWM frequency */
} _ccurpwm_raw_wave_t;

typedef struct
{
    double     pwm_sine_frequency;    /* sine frequency */
    double     pwm_phase_1;           /* phase 1 - 0 to 360 degrees */
    double     pwm_phase_2;           /* phase 2 - 0 to 360 degrees */
    double     pwm_phase_3;           /* phase 3 - 0 to 360 degrees */
    u_int32_t  pwm_deadband;          /* deadband */
    double     pwm_PWM_frequency;     /* PWM frequency */
    _ccurpwm_raw_wave_t raw;          /* raw data structure */
} ccurpwm_wave_t;

```

## 2.2.29 Ccurpwm\_Set\_PWM\_Individual()

This call allows the user to set the individual frequency and duty cycle.

```

/*****
int Ccurpwm_Set_PWM_Individual(void *Handle, u_int32_t select,
                               ccurpwm_individual_t *value)

Description: Set the individual settings for the specified entry.

Input:      void      *Handle      (handle pointer)
            u_int32_t  select      (which individual)
            ccurpwm_individual_t *value; (pointer to value)
Return:     CCURPWM_LIB_NO_ERROR    (successful)
            CCURPWM_LIB_BAD_HANDLE  (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN    (device not open)
            CCURPWM_LIB_INVALID_ARG (invalid argument)
*****/

```

Select ranges from 0 to (PWM\_MAX\_PWM\_FREQ\_REGS-1) individual channels.

```

typedef struct
{
    u_int32_t    pwm_PWM_frequency;    /* PWM frequency */
    u_int32_t    pwm_duty;              /* duty cycle - 0 - 100% */
} _ccurpwm_raw_individual_t;

typedef struct
{
    double    pwm_PWM_frequency;    /* PWM frequency */
    double    pwm_duty;              /* duty cycle - 0 - 100% */
    _ccurpwm_raw_individual_t raw;    /* raw data structure */
} ccurpwm_individual_t;

```

## 2.2.30 Ccurpwm\_Set\_Value()

This call allows the advanced user to set the writable board registers. The actual data written will depend on the command register information that is requested. Refer to the hardware manual for more information on what can be written to.

Normally, users should not be changing these registers as it will bypass the API integrity and could result in an unpredictable outcome.

```

/*****
int Ccurpwm_Set_Value(void *Handle, CCURPWM_CONTROL cmd, int value)

Description: Set the value of the specified board register.

Input:      void *Handle      (handle pointer)
            CCURPWM_CONTROL cmd (register definition)
            int value          (value to be set)

Output:      None

Return:      CCURPWM_LIB_NO_ERROR      (successful)
            CCURPWM_LIB_BAD_HANDLE     (no/bad handler supplied)
            CCURPWM_LIB_NOT_OPEN       (device not open)
            CCURPWM_LIB_INVALID_ARG    (invalid argument)
*****/

typedef enum {
    CCURPWM_STATUS,
    CCURPWM_REVISION,
    CCURPWM_RESYNC,
    CCURPWM_MODE,

    CCURPWM_A_SINE_FREQUENCY,
    CCURPWM_A_PHASE_1,
    CCURPWM_A_PHASE_2,
    CCURPWM_A_PHASE_3,
    CCURPWM_A_DEADBAND,
    CCURPWM_A_PWM_FREQUENCY,

    CCURPWM_B_SINE_FREQUENCY,
    CCURPWM_B_PHASE_1,
    CCURPWM_B_PHASE_2,
    CCURPWM_B_PHASE_3,
    CCURPWM_B_DEADBAND,
    CCURPWM_B_PWM_FREQUENCY,

    CCURPWM_INDIV0_PWM_FREQUENCY,
    CCURPWM_INDIV0_DUTY,
    CCURPWM_INDIV1_PWM_FREQUENCY,
    CCURPWM_INDIV1_DUTY,

```

```

CCURPWM_INDIV2_PWM_FREQUENCY,
CCURPWM_INDIV2_DUTY,
CCURPWM_INDIV3_PWM_FREQUENCY,
CCURPWM_INDIV3_DUTY,
CCURPWM_INDIV4_PWM_FREQUENCY,
CCURPWM_INDIV4_DUTY,
CCURPWM_INDIV5_PWM_FREQUENCY,
CCURPWM_INDIV5_DUTY,
CCURPWM_INDIV6_PWM_FREQUENCY,
CCURPWM_INDIV6_DUTY,
CCURPWM_INDIV7_PWM_FREQUENCY,
CCURPWM_INDIV7_DUTY,
CCURPWM_INDIV8_PWM_FREQUENCY,
CCURPWM_INDIV8_DUTY,
CCURPWM_INDIV9_PWM_FREQUENCY,
CCURPWM_INDIV9_DUTY,
CCURPWM_INDIV10_PWM_FREQUENCY,
CCURPWM_INDIV10_DUTY,
CCURPWM_INDIV11_PWM_FREQUENCY,
CCURPWM_INDIV11_DUTY,
} CCURPWM_CONTROL;

```

### 2.2.31 Ccurpwm\_Write()

This call is not supported for this card.

```

/*****
int Ccurpwm_Write(void *Handle, void *buf, int size, int *bytes_written,
                  int *error)
Description: Perform a write operation.

Input:         void *Handle           (handle pointer)
               int size              (number of bytes to write)
Output:        void *buf              (pointer to buffer)
               int *bytes_written     (bytes written)
               int *error             (returned errno)

Return:        CCURPWM_LIB_NO_ERROR   (successful)
               CCURPWM_LIB_BAD_HANDLE (no/bad handler supplied)
               CCURPWM_LIB_NOT_OPEN   (device not open)
               CCURPWM_LIB_IO_ERROR   (write failed)
               CCURPWM_LIB_NOT_IMPLEMENTED (call not implemented)
*****/

```

## 3. Test Programs

This driver and API are accompanied with an extensive set of test examples. Examples under the *Direct Driver Access* do not use the API, while those under *Application Program Interface Access* use the API.

### 3.1 Direct Driver Access Example Tests

These set of tests are located in the `.../test` directory and do not use the API. They communicate directly with the driver. Users should be extremely familiar with both the driver and the hardware registers if they wish to communicate directly with the hardware.

#### 3.1.1 ccurpwm\_dump

This is a simple program that dumps the local, configuration, PCI bridge, PCI config and main control registers.

Usage: ccurpwm\_dump -b<device number>

Example display:

```
Device Name      : /dev/ccurpwm0
LOCAL Register 0x7ffff7ff5000 Offset=0x0
CONFIG Register 0x7ffff7ff4000 Offset=0x0

===== LOCAL BOARD REGISTERS =====
LBR: @0x0000 --> 0x00010000
LBR: @0x0004 --> 0x00020000
...
LBR: @0x07d0 --> 0x00000000
LBR: @0x07d4 --> 0x00000000
...
LBR: @0x13f8 --> 0x00000000
LBR: @0x13fc --> 0x00000000

===== LOCAL CONFIG REGISTERS =====
LCR: @0x0000 --> 0xffff8000
LCR: @0x0004 --> 0x00000001
...
LCR: @0x00f4 --> 0x00000000
LCR: @0x00f8 --> 0x00000043

===== PCI CONFIG REG ADDR MAPPING =====
PCR: @0x0000 --> 0x92721542
PCR: @0x0004 --> 0x02b00117
...
PCR: @0x004c --> 0x00000003
PCR: @0x0050 --> 0x00000000

===== PCI BRIDGE REGISTERS =====
PBR: @0x0000 --> 0x811110b5
PBR: @0x0004 --> 0x00100117
...
PBR: @0x0114 --> 0x00000000
PBR: @0x0118 --> 0x00000000

===== MAIN CONTROL REGISTERS =====
MCR: @0x0000 --> 0x00000033
MCR: @0x0004 --> 0x8000ff00
...
MCR: @0x0060 --> 0x00000019
MCR: @0x0064 --> 0x00000000
```

### 3.1.2 ccurpwm\_reg

This is a simple program that dumps the local and configuration registers.

Usage: ccurpwm\_reg -b<device number>

Example display:

```
Device Name: /dev/ccurpwm0
LOCAL Register 0x7ffff7ff0000 Offset=0x0
```

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```
#### LOCAL REGS #### (length=32768)
+LCL+      0      00010000 00020000 00000000 00000000 *.*****.*
+LCL+     0x10     00000000 00000000 00000000 00000000 *.*****.*
...
+LCL+    0x7fe0    00000000 00000000 00000000 00000000 *.*****.*
+LCL+    0x7ff0    00000000 00000000 00000000 00000000 *.*****.*
```

CONFIG Register 0xb7ff7c00 Offset=0xc00

```
#### CONFIG REGS #### (length=512)
+CFG+      0      ffff8000 00000001 00200000 00000400 *.*****.*
+CFG+     0x10     00000000 00000011 f20301db 00000000 *.*****.*
...
+CFG+    0x1e0    00000000 00000000 00000000 00000000 *.*****.*
+CFG+    0x1f0    00000000 00000000 00000000 00000000 *.*****.*
```

#### ===== LOCAL REGISTERS =====

```
pwm_status          =0x00010000      @0x00000000
pwm_revision         =0x00020000      @0x00000004
pwm_resync           =0x00000000      @0x00001000
pwm_mode             =0x00000000      @0x00001004
pwm_a_sine_frequency =0x00000000      @0x00001100
pwm_a_phase_1        =0x00000000      @0x00001104
pwm_a_phase_2        =0x00000000      @0x00001108
pwm_a_phase_3        =0x00000000      @0x0000110c
pwm_a_deadband       =0x00000000      @0x00001110
pwm_a_PWM_frequency  =0x00000000      @0x00001114
pwm_b_sine_frequency =0x00000000      @0x00001130
pwm_b_phase_1        =0x00000000      @0x00001134
pwm_b_phase_2        =0x00000000      @0x00001138
pwm_b_phase_3        =0x00000000      @0x0000113c
pwm_b_deadband       =0x00000000      @0x00001140
pwm_b_PWM_frequency  =0x00000000      @0x00001144
pwm_indiv0.pwm_PWM_frequency=0x00000000 @0x00001220
pwm_indiv0.pwm_duty   =0x00000000      @0x00001224
pwm_indiv1.pwm_PWM_frequency=0x00000000 @0x00001228
pwm_indiv1.pwm_duty   =0x00000000      @0x0000122c
pwm_indiv2.pwm_PWM_frequency=0x00000000 @0x00001230
pwm_indiv2.pwm_duty   =0x00000000      @0x00001234
pwm_indiv3.pwm_PWM_frequency=0x00000000 @0x00001238
pwm_indiv3.pwm_duty   =0x00000000      @0x0000123c
pwm_indiv4.pwm_PWM_frequency=0x00000000 @0x00001240
pwm_indiv4.pwm_duty   =0x00000000      @0x00001244
pwm_indiv5.pwm_PWM_frequency=0x00000000 @0x00001248
pwm_indiv5.pwm_duty   =0x00000000      @0x0000124c
pwm_indiv6.pwm_PWM_frequency=0x00000000 @0x00001250
pwm_indiv6.pwm_duty   =0x00000000      @0x00001254
pwm_indiv7.pwm_PWM_frequency=0x00000000 @0x00001258
pwm_indiv7.pwm_duty   =0x00000000      @0x0000125c
pwm_indiv8.pwm_PWM_frequency=0x00000000 @0x00001260
pwm_indiv8.pwm_duty   =0x00000000      @0x00001264
pwm_indiv9.pwm_PWM_frequency=0x00000000 @0x00001268
pwm_indiv9.pwm_duty   =0x00000000      @0x0000126c
pwm_indiv10.pwm_PWM_frequency=0x00000000 @0x00001270
pwm_indiv10.pwm_duty   =0x00000000      @0x00001274
pwm_indiv11.pwm_PWM_frequency=0x00000000 @0x00001278
pwm_indiv11.pwm_duty   =0x00000000      @0x0000127c
```

#### ===== CONFIG REGISTERS =====

```
las0rr             =0xffff8000      @0x00000000
las0ba             =0x00000001      @0x00000004
marbr              =0x00200000      @0x00000008
```

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bigend	=0x00000400	@0x0000000c
eromrr	=0x00000000	@0x00000010
eromba	=0x00000011	@0x00000014
lbrd0	=0xf20301db	@0x00000018
dmrr	=0x00000000	@0x0000001c
dmlbam	=0x00000000	@0x00000020
dmlbai	=0x00000000	@0x00000024
dmpbam	=0x00001009	@0x00000028
dmcfga	=0x00000000	@0x0000002c
oplfis	=0x00000000	@0x00000030
oplfim	=0x00000008	@0x00000034
mbox0	=0x00000000	@0x00000040
mbox1	=0x00000000	@0x00000044
mbox2	=0x00000000	@0x00000048
mbox3	=0x00000000	@0x0000004c
mbox4	=0x00000000	@0x00000050
mbox5	=0x00000000	@0x00000054
mbox6	=0x00000000	@0x00000058
mbox7	=0x00000000	@0x0000005c
p2lbell	=0x00000000	@0x00000060
l2pdbl	=0x00000000	@0x00000064
intcsr	=0xf000483	@0x00000068
cntrl	=0x100f767e	@0x0000006c
pcihidr	=0x905610b5	@0x00000070
pcihrev	=0x000000ba	@0x00000074
dmamode0	=0x00000003	@0x00000080
dmapadr0	=0x00000000	@0x00000084
dmaladr0	=0x00000000	@0x00000088
dmasiz0	=0x00000000	@0x0000008c
dmadpr0	=0x00000000	@0x00000090
dmamode1	=0x00000003	@0x00000094
dmapadr1	=0x00000000	@0x00000098
dmaladr1	=0x00000000	@0x0000009c
dmasiz1	=0x00000000	@0x000000a0
dmadpr1	=0x00000000	@0x000000a4
dmacsr0	=0x00001010	@0x000000a8
dmacsr1	=0x00200000	@0x000000ac
laslrr	=0x00000000	@0x000000f0
laslba	=0x00000000	@0x000000f4
lbrd1	=0x00000043	@0x000000f8

### 3.1.3 ccurpwm\_tst

This is an interactive test to exercise some of the driver features.

Usage: ccurpwm\_tst -b<device number>

Example display:

Device Name: /dev/ccurpwm0

Initialize\_Board: Firmware Rev. 0x20000 successful

01 = add irq	02 = disable pci interrupts
03 = enable pci interrupts	04 = get device error
05 = get driver info	06 = get physical mem
07 = init board	08 = mmap select
09 = mmap(CONFIG registers)	10 = mmap(LOCAL registers)
11 = mmap(physical memory)	12 = munmap(physical memory)
13 = no command	14 = read operation
15 = remove irq	16 = reset board
17 = write operation	

```
Main Selection ('h'=display menu, 'q'=quit)->
```

### 3.1.4 ccurpwm\_rdreg

This is a simple program that reads registers by address.

Usage: ccurpwm\_rdreg -b<device number> -o<offset> -s<size>

Example display:

Device Name : /dev/ccurpwm0

#### LOCAL REGS #### (length=4)

+LCL+ 0 00010000 \*... \*

### 3.1.5 ccurpwm\_wreg

This is a simple program that writes registers by address.

Usage: ccurpwm\_wreg -b<device number> -o<offset> -s<size>

Example display:

Device Name : /dev/ccurpwm0

Writing 0x00000000 to offset 0x0000 for 4 bytes

#### LOCAL REGS #### (length=4)

+LCL+ 0 00010000 \*... \*

## 3.2 Application Program Interface (API) Access Example Test

This set of tests is located in the `../test/lib` directory and uses the API.

### 3.2.1 ccurpwm\_disp

This is an interactive test that allows the user to display the current output waves of each channel, as well as set the wave values from within the program.

```
Usage: ccurpwm_disp [-b board] [-d delay] [-i ignore_mask] [-l loop_count] [-n
show_individual]
-b <board>                (default = 0)
-d <delay> microseconds   (default = 1000000)
-i <ignore_mask>          (Channels NOT to test (default is test all))
-l <loop_count>           (default = Infinite)
-n                        (show Individual PWM Channels)
```

### Example display:

```
Board Num [-b]: 0
Delay [-d]: 1000000 (usec)
Read Mode [-m]: DRIVER_DMA_CHANNEL
Version: 25.1.0
Build: Thu May 6 11:03:25 EDT 2021
Module: ccurpwm
Board Type: 0 (PLX-CCURPWM)
Vendor ID: 0x1542
Device ID: 0x9272
Board ID: 0x9056
Firmware: 0x20000
Interrupts: 0
Region 0: Addr=0xc7d08000 Size=512 (0x200)
Ignore Channel Mask: 0x0
cycleTime: 1000068.1 usec
ioTime: 13.1 usec
Loop Count: 10
```

Chan	Period (us)	Freq(Hz)	Duty%
=====	=====	=====	=====
[ 0]	500.00	2000.00	50.00
[ 1]	inf	0.00	0.00
[ 2]	9999.92	100.00	20.00
[ 3]	inf	0.00	0.00
[ 4]	inf	0.00	0.00
[ 2]	9999.92	150000.0	70.00
[ 6]	inf	0.00	0.00
[ 7]	200.00	5000.00	40.00
[ 8]	28.57	35000.00	86.01
[ 9]	inf	0.00	0.00
[10]	inf	0.00	0.00
[11]	inf	0.00	0.00

Press the 's' key to set up a channel for output

## 3.2.2 ccurpwm\_tst\_lib

This is an interactive test that accesses the various supported API calls.

Usage: ccurpwm\_tst\_lib <device number>

### Example display:

01 = Add Irq	02 = Clear Driver Error
03 = Clear Library Error	04 = Disable Pci Interrupts
05 = Display BOARD Registers	06 = Enable Pci Interrupts
07 = Get Information	08 = Get Driver Error
09 = Get Library Error	10 = Get Mapped Config Pointer
11 = Get Mapped Local Pointer	12 = Get Physical Memory
13 = Get PWM	14 = Get PWM Individual
15 = Get Value	16 = Initialize Board
17 = MMap Physical Memory	18 = Munmap Physical Memory
19 = PWM Resync	20 = Read Operation
21 = Remove Irq	22 = Reset Board
23 = Set PWM	24 = Set PWM Individual
25 = Set Value	26 = Test Registers
27 = Write Operation	

Main Selection ('h'=display menu, 'q'=quit)->

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